## Dynamic Programming

Dynamic Programming is a general technique for constructing algorithms. When the method works it almost always gives an efficient solution to a problem. In order to apply the method you should go trough the following
l. Find a way if splitting your problem into subproblems. The solutions to the subproblems will usually be recorded in an array.
2. Find a recursion formula that relates the values of subproblems to the values of simpler subproblems.
3. Find a natural ordering of the subproblems and then compute the values of all subproblems in that order, using the recursion formula.

Example: Steel cutting
(This example is taken from Cormen, Leiserson, Rivest, Stein:
Introduction to Algorithms

Assume that a company Steelcutter inc. buys steel rods and cuts them into shorter rods, which it then sells. We assume that the steel rods all have integer lengths (before and after cutting). Let the given price for a steel rod of length $m$ is $p(m)$. We can assume that this is not a linear function in $m$. (Which might seem strange, but possible.) It we have a rod of length $n$, it can be cut into $1,2, \ldots ., n$ pieces of varying length. If the rod is split into pieces of lengths n1, $n 2, \ldots, n k$, the company will get a revenue $p(n 1)+p(n 2)+\ldots p(n k)$. How should the rod be cut?

Let $V(n)$ be the maximal revenue the company can get from a rod of length $n$. How can we find $V(n)$ ? One possibility is to make no cut at all. Then we get $p(n)$. Let us assume that we make a first cut of length s.
Then we see that we must have an optimal revenue $p(s)+v(n-s)$, where we assume that $v(n-s)$ is computed. We can formalize this into a recursion formula:
$\left\{\begin{array}{l}V(0)=0 \\ V(n)=\max p(s)+V(n-s) \text { for } n>0 \text { (where } s \text { is an integer } 1 \leqslant s \leqslant n \text { ) }\end{array}\right.$ s

We see that we can use the formula for recursively compute $V(1)$, $V(2), \ldots, V(n)$.

## Selection of weighted intervals

As in lecture 2 we have a set of activities given by time intervals [ $s[i], f[i]$ ). We assume that the intervals are sort by increasing finishing time. In this problem we have weights $w[i]$ on the intervals. The problem is this:

Input: $n$ Intervals [s[i], fij] with weights $w[i]$.
Goal: Find a selection of non-overlapping intervals with maximal weight sum.


1. How can we find natural subproblem? Why not index problems after the numbers of intervals?

Def: Let $M[k]$ be the maximal weigth sum you can get if you only are allowed to use the first $k$ intervals.
2. How do we find a recursion formula? It is obvious that $M[I]=\omega[I]$. If we want to use $n$ intervals, how do we do? Do we include interval $n$ in the solution or not?

If we don't then obviously we get $M[n]=M[n-1]$.
If we do, then there is a largest $k$ such that interval $k$ does not overlap interval $n$. Then we must have $M[n]=M[k]+w[n]$.

But now we can compare these two possible values of $M[n]$ and see which value is largest. From this we can tell what the best choice is.
$M[1]=\omega[I]$
$M[n]=\max (M[n-I], M[k]+w[n]) \quad$ where $k$ is the largest number such that $f[k] \leq s[n]$
3. We now compute the values $M[1], M[2], \ldots, M[n]$ in the natural order. We use an array choose[k] that indicates if interval $k$ should be a part of the optimal choice for $M[k]$ and an array $p[k]$ that indicates what the previous choice in the selection corresponding to MkJ is.

## Subset Sum

We assume that we have $n$ positive integers $a[l], a[2], \ldots, a[n]$. We are given an integer $M$. We want to know if there is a subset of the integers with sum $M$.

What are the natural subproblems here? We can try to get the sum $M$ by using fewer than $n$ integers. Or we can try to get a smaller sum than M. In fact, we will combine these two ideas.

Set $v[i, m]=l$ if there is a subset of $a[[], a[2], \ldots, a[i]$ with sum $m$ and $v[i, m]=0$ otherwise.

If $v[i, m]=1$ it must be either because we can get $m j u s t$ by using the numbers $a[I], a[2], \ldots, a[i-1]$ or because we can get the sum $m-a[i]$ by using the same numbers. We get the recursion
$v[1,0]=1$
For all $i$ such that $2 \leq i \leq n$ and all $m M$ such that $a[i] \leq m$
$v[i, m]=\max (v[i-1, m], v[i-1, m-a[i]])$

We now try to construct an algorithm. We have to order the subproblems. We compute all $v[i, m]$ by running an outer loop over $I \leq i \leq n$ and an inner loop over $1 \leq m \leq M$.

Set all viji, $]=0$
Fori $\leftarrow 1$ to $n$
$v[i, 0] \leftarrow 1$
Fori $\leftarrow 2$ ton
For $m \leftarrow 1$ to $M$
If $v[i-1, m]=1$ $v[i, m] \leftarrow 1$
Else $1 f m>a[i]$ and $v[i-1, m-a[i]]=1$

$$
v[i, m] \leftarrow
$$

Return v[n,M]

When the algorithm stops, the value of $\cup[n, M]$ tells us the solution to the problem. ( 1 = " It's possible", $0=$ " lt's not possible".) The complexity is $\mathrm{O}(\mathrm{n} M$ ).

In Dynamic Programming-problems we have some value that we want to optimize. We express this value with some array like $v[n]$ and try to find a recursion formula and then use it to find all values $v[i]$. In some cases this is all we want. In other cases we might want to find the actual "choices" leading to these values. If we have an algorithm which solves the recursion equation we can often modify it so that it gives us the actual choices.

For instance, in the previous problem we wanted to to find the values v[i,m]. If we know that $v[i, m]=1$ and also want to find the terms in the sum, we can modify our algorithm:

Set all v[i,j]=0
For $i \leftarrow 1$ ton
$v[i, 0] \leftarrow 1$
choose[i,O] $\leftarrow$ FALSE

For $i \leftarrow 2$ ton
For $m \leftarrow I$ to $M$
If $\cup[i-1, m]=1$
$\frac{v[i, m] \leftarrow 1}{\text { choose }[i, O] \leftarrow \text { FALSE }}$ $p[i, m] \leftarrow[i-1, m]$
Else If $m>a[i]$ and $v[i-1, m-a[i]]=1$

$$
\begin{aligned}
& v[i, m] \leftarrow 1 \\
& \text { choose }[i, m] \leftarrow \text { TRUE } \\
& p[i, m] \leftarrow[i-1, m-a[i]]
\end{aligned}
$$

Return v[n,M]

Instead of using the bottom-up approach when solving the subset sum problem we could try a recursive variant. We could try this:

$$
\begin{gathered}
\text { urek }[i, m]= \\
\text { If } \mathrm{i}<=0 \\
\text { Return } \mathrm{O} \\
\text { If } \mathrm{m}<0 \\
\text { Return } 0 \\
\text { If } \mathrm{m}=0 \\
\text { Return I } \\
\text { If urek }[\mathrm{i}-\mathrm{l}, \mathrm{~m}]=1 \\
\text { Return I } \\
\text { If urek }[i-1, m-a[\mathrm{i}]]=1 \\
\text { Return I }
\end{gathered}
$$

But this solution is no good. The problem is that the algorithm uses repeated calls to subproblems that already have been solved.

But this modification of the recursive algorithm works better:

```
Set all comp[i,j] to FALSE
Set all v[i,j] to 0
vrek[i,m] =
    If comp \([i, m]\)
        Return v[i,m]
    If \(\mathrm{i}<=0\)
        Return 0
    If \(m<0\)
        Return 0
    If \(m=0\)
        Return 1
    If vrek[i-l, m] = I
    comp \([i, m] \leftarrow\) TRUE
    \(v[i, m] \leftarrow 1\)
    Return 1
    If \(\operatorname{vrek}[i-1, m-a[i]]=1\)
    comp \([i, m] \leftarrow\) TRUE
    \(v[i, m] \leftarrow 1\)
    Return 1
This technique of remembering already computed values is called Memoization. Sometimes it can be useful, but in most cases the bottom-up method should be preferred.
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In lecture 3 we discussed the problem of finding shortest paths in graphs with negative weights. Floyd-Warshall's algorithm is a dynamic programming algorithm for solving the problem. Actually it find the shortest distances between all pairs of nodes. We assume that we have no negative cycles.

Subproblems:
We set d[i,j,k] = length of shortest path using just nodes $\mathrm{i}, \mathrm{j}$ and nodes $1,2, \ldots$, . .

## Recursion:

$$
\begin{aligned}
& d[i, j, O]=\omega[i, j] \text { for all } i, j(\omega[i, j]=\infty \text { if there is no edge }(i, j)) \\
& d[i, j, k]=\min (d[i, j, k-I], d[i, k, k-I]+d[k, j, k-I]) I \leq k \leq n
\end{aligned}
$$

Algorithm:

Fori $\leftarrow 1$ ton
For $\mathrm{j} \leftarrow 1$ ton
$d[i, j, O] \leftarrow \omega[i, j]$
$p[i, j, 0] \leftarrow i$
Fork $\leftarrow$ lton
If $d[i, j, k-I] \leq d[i, k, k-I]+d[k, j, k-I]$
$d[i, j, k] \leftarrow d[i, j, k-1]$
$p[i, j, k] \leftarrow p[i, j, k-1]$
Else
$d[i, j, k] \leftarrow d[i, k, k-1]+d[k, j, k-1]$
$p[i, j, k] \leftarrow p[k, j, k-1]$
Fori $\leftarrow 1$ to $n$
For $\mathrm{j} \leftarrow 1$ ton $d[i, j] \leftarrow d[i, j, n]$ $p[i, j] \leftarrow p[i, j, n]$

The algorithm has complexity $O\left(n^{3}\right)$.

## Increasing sequence of numbers

Problem: Given a sequence of numbers
$x_{1}, x_{2}, \ldots, x_{n}$ we want to compute the longest sequence of increasing consecutive numbers.

Let $v(i)=$ be the length of the longest sequence ending in $x_{i}$.

Algoritm:
(1) $v(1) \leftarrow 1$
(2) for $i=2$ to $n$
(3) if $x(i-1) \leq x(i)$
(4) $\quad v(i) \leftarrow v(i-1)+1$
(5) else
(6) $\quad v(i) \leftarrow 1$
(7) return $v$

Then we compute $\max _{i} v(i)$.

We have a sequence of $n$ numbers. We want to find a longest increasing subsequence. In this case the numbers don't have to be consecutive.
(Strictly speaking, by increasing we will in this case, mean strictly increasing, i.e. <) Let the numbers be $x[1], x[2], \ldots, x[n]$.

Set $v[i]=$ Length of the longest increasing sequence ending in $x[i]$

Then $v[I]=1$. For larger $i$ we set $v[i]=\max (v[k]+1)$ where the max runs over all $k$ such that $x[k] \leq x[i]$.

We can implement this with the algorithm:
$v[1] \leftarrow 1$
For $i \leftarrow 2$ ton
$\max \leftarrow 1$
Fork $\leftarrow 1$ to $i-1$
If $x[k]<x[i]$ and $v[k]+1>\max$ $\max \leftarrow v[k]+1$
$v[i] \leftarrow$ max
$\max \leftarrow 0$
Forj $\leftarrow 1$ ton
If $v[j]>\max$
$\max \leftarrow v[j]$
Return max

## One more problem

Problem: Find the path from top to bottom that maximizes the sum of the numbers.


Let $a_{i j}$ be the number in row $i$, column $j$.

Let $V[i, j]$ be the value of the best path from $(i, j)$ down to bottom row $n$. Then
$V[i, j]= \begin{cases}a_{i j} & i=n, \\ a_{i j}+\max \{V[i+1, j], V[i+1, j+1]\} & \text { otherwise } .\end{cases}$

