VEKTORANALYS HT 2021 CELTE / CENMI ED1110 GRADIENTEN

Kursvecka 1

Kapitel 4-5 (Vektoranalys, 1:e uppl, Frassinetti/Scheffel)



version: 29-aug-2021



- Scalar fields and vector fields
- Level surfaces and level curves
- The position vector
- The gradient
- The directional derivative
- Three theorems related to the gradient
- Scalar potential \rightarrow home assignment (+övning week 2)

Connections with next topics and next weeks

Scalar and vector fields:

- They will be used throughout the course
- They are essential for line integrals, flux, Gauss' theorem, Stokes' theorem...

Gradient:

- A wide range of applications in physics and engineering
- It has links with most of the course. For example
 - week 3 (Gauss' theorem),
 - week 4 (curvilenar coordinates)
 - week 5 (nabla)
 - week 6 (Laplace and Poisson's equations)

A mosquito is flying in the room.

How does the mosquito find us in the dark?

A theory is: the mosquito flies toward the warmest region of the room

- ightarrow The mosquito must know:
 - (A) How the temperature T(x,y,z) changes along the flying direction
 - (B) In which direction it must fly to be in a warmer place as quick as possible

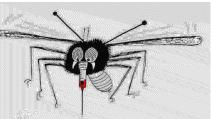
Problem

The temperature is described by the scalar field: $T(x,y,z)=x^2+2yz-z$ [°C] The mosquito is in the point P: (1,1,2)

- Question A: in which direction the mosquito must fly to be in a warmer place as quick as possible?
- Question B: How much does the temperature change in time if the mosquito flies with velocity 3m/s in direction $-2\hat{e}_x + 2\hat{e}_y + \hat{e}_z$?

To solve the problem, we need to:

- (1) introduce a **SCALAR FIELD**, T(x,y,z)
- (2) measure the rate of change of the scalar field T(x,y,z) in R^3
- (3) find the **direction** along which **the rate of change** of T(x,y,z) **is maximum**

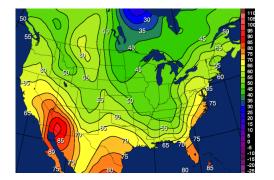


SCALAR FIELD AND VECTOR FIELD

A scalar quantity is said to be a **field** if it is a function of position A **scalar field** associates a **real number** $\phi(x,y,z)$ **to each point** (x,y,z) of the space.

Examples: - temperature distribution in the space

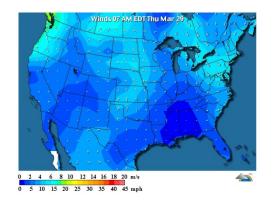
- pressure distribution in a fluid
- electrostatic potential around an electric charge



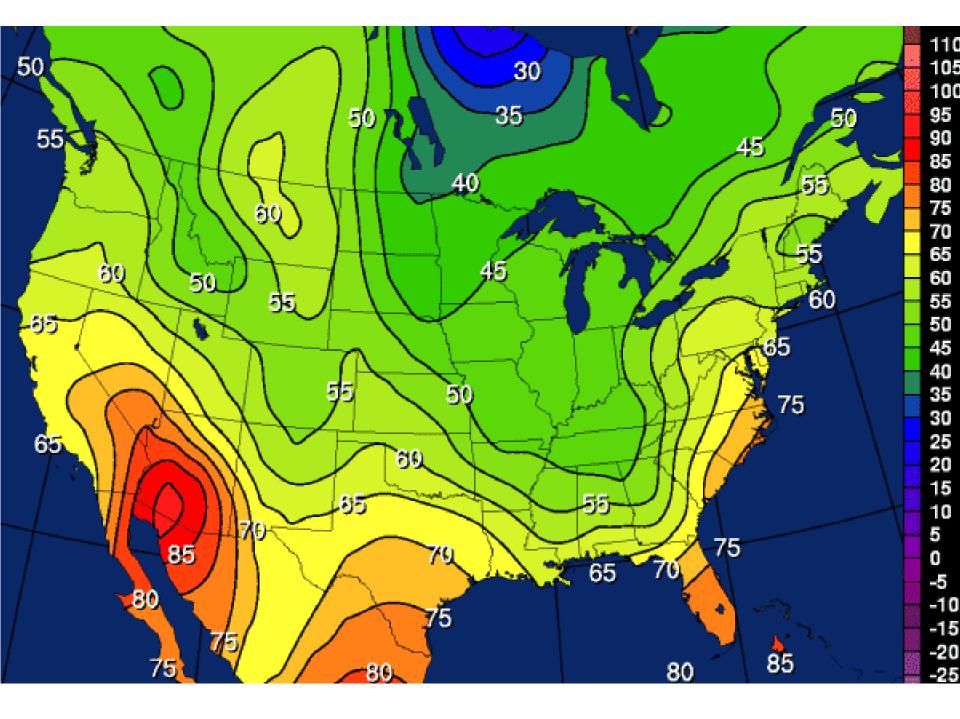
A vector quantity is said to be a **field** if it is a function of position A **vector field** associates a **vector** $\overline{A}(x,y,z)$ to each point (x,y,z) of the space.

Examples: - velocity distribution in a fluid

- magnetic field around a magnet
- electrostatic field around an electric charge



To solve our target problem, today we will focus on scalar fields



LEVEL CURVES and LEVEL SURFACES

- Level curves and level surfaces are useful to visualize a scalar field (in R² and R³ respectively).
- What is a level curve?

A curve on which the scalar field $\phi(x,y)$ is constant:

• What is a level surface?

A surface on which the scalar field $\phi(x,y,z)$ is constant: $\phi(x,y,z)=c$

 To create an "image" of the scalar field \u03c6(x,y,z) we can consider a family of level surfaces:

 $\phi(x,y,z)=c+nh$ where h is a constant and n=0, ±1, ±2, ±3,...

Example: $\phi(x,y,z)=1$ $\phi(x,y,z)=3$ $\phi(x,y,z)=5$ $\phi(x,y,z)=7$

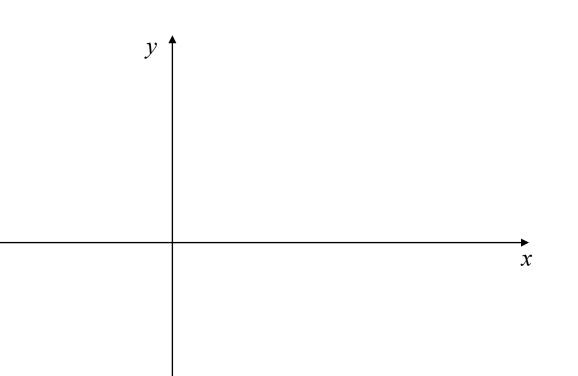
To improve the details of the "image", you can decrease the steps between one surface and the next.

(1)

(2)

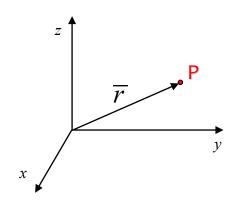
EXAMPLE

Plot the level curves of the scalar field: $\phi = \frac{x^2}{4} + y^2$



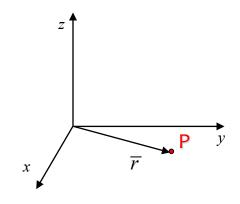
POSITION VECTOR

- The vector from the origin to the point P=(x,y,z) is called position vector \overline{r}
- Note that \overline{r} depends on the choice of the coordinate system



POSITION VECTOR

- The vector from the origin to the point P=(x,y,z) is called position vector \overline{r}
- Note that \overline{r} depends on the choice of the coordinate system



POSITION VECTOR

- The vector from the origin to the point P=(x,y,z) is called position vector \overline{r}
- Note that \overline{r} depends on the choice of the coordinate system
- \overline{r} can be expressed with different notations:

$$\overline{r} = \overline{r}(x, y, z)$$
 $\overline{r} = (x, y, z)$ $\overline{r} = x\hat{e}_x + y\hat{e}_y + z\hat{e}_z$ (in a Cartesian coordinate system)

• The absolute value of a position vector is the scalar:

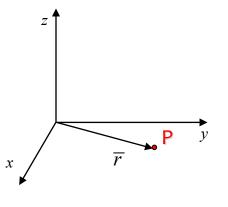
$$r = \left|\overline{r}\right| = \sqrt{x^2 + y^2 + z^2} \tag{3}$$

• The differential of a position vector can be written as a vector whose components are the differential of each position vector component:

$$\overline{r} = x\hat{e}_{x} + y\hat{e}_{y} + z\hat{e}_{z}$$

$$\downarrow$$

$$d\overline{r} = dx\hat{e}_{x} + dy\hat{e}_{y} + dz\hat{e}_{z}$$
(4)



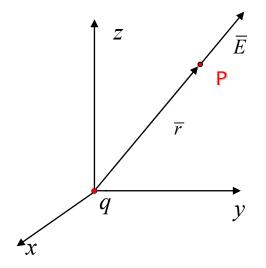
THE ELECTRIC FIELD GENERATED BY A POINT CHARGE (a useful application of the position vector)

- Consider a point charge q located in the origin and a point P defined by the position vector \overline{r}
- The absolute value of the of the electric field in P is:

$$E = \frac{1}{4\pi\varepsilon_0} \frac{q}{r^2} = \frac{1}{4\pi\varepsilon_0} \frac{q}{\left|\overline{r}\right|^2}$$

In this case, the direction of the electric field is from the origin to P, so it is given by: *r*

$$\overline{E} = \frac{1}{4\pi\varepsilon_0} \frac{q}{\left|\overline{r}\right|^2} \frac{\overline{r}}{\left|\overline{r}\right|} = \frac{q}{4\pi\varepsilon_0} \frac{\overline{r}}{\left|\overline{r}\right|^3}$$



THE ELECTRIC FIELD GENERATED BY A POINT CHARGE (a useful application of the position vector)

- Consider a point charge q located in the origin and a point P defined by the position vector \overline{r}
- The absolute value of the of the electric field in P is:

$$E = \frac{1}{4\pi\varepsilon_0} \frac{q}{r^2} = \frac{1}{4\pi\varepsilon_0} \frac{q}{\left|\overline{r}\right|^2}$$

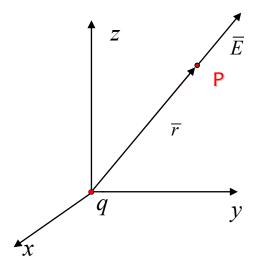
In this case, the direction of the electric field is from the origin to P, so it is given by: *r*

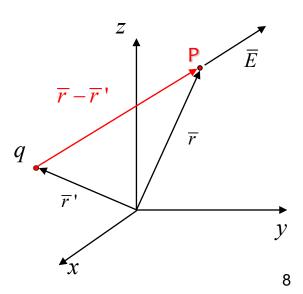
$$\overline{E} = \frac{1}{4\pi\varepsilon_0} \frac{q}{\left|\overline{r}\right|^2} \frac{\overline{r}}{\left|\overline{r}\right|} = \frac{q}{4\pi\varepsilon_0} \frac{\overline{r}}{\left|\overline{r}\right|^3}$$

- How can we express the electric field if the charge is not in the origin?
 - \overline{r} ' is used to identify the position of the "source"
 - *r* is used to identify the position of P (where you need to calculate the field)

We need to identify the distance and the direction from q to P direction: $\overline{r} - \overline{r}'$ distance: $|\overline{r} - \overline{r}'|$

$$\overline{E} = \frac{1}{4\pi\varepsilon_0} \frac{q}{\left|\overline{r} - \overline{r}\right|^2} \frac{\overline{r} - \overline{r}}{\left|\overline{r} - \overline{r}\right|} = \frac{q}{4\pi\varepsilon_0} \frac{\overline{r} - \overline{r}}{\left|\overline{r} - \overline{r}\right|^3}$$





- Assume that $\phi(\overline{r})$ is a continuous and derivable scalar field
- DEFINITION:

in a Cartesian coordinate system

$$grad\phi = \left(\frac{\partial\phi}{\partial x}, \frac{\partial\phi}{\partial y}, \frac{\partial\phi}{\partial z}\right) = \frac{\partial\phi}{\partial x}\hat{e}_x + \frac{\partial\phi}{\partial y}\hat{e}_y + \frac{\partial\phi}{\partial z}\hat{e}_z$$
(5)

IMPORTANT: the gradient of a scalar field is a vector field

EXERCISE: calculate the gradient of the vector field: $\phi = \frac{x^2}{4} + y^2$ and plot grad ϕ in the point *P*: (2,0) and in the point *Q*: (0,-1)

• Scalar field differential:

$$d\phi = grad\phi \cdot d\bar{r} \tag{6}$$

• Let's introduce :

- the amplitude of the position vector differential, ds, and

- the direction \hat{e} (\hat{e} is a unit vector, i.e. $|\hat{e}|=1$) Equations (6) and (7) give:

Directional derivative

$$\frac{d\phi}{ds} = grad\phi \cdot \hat{e}$$

The rate of variation of ϕ in a given direction corresponds to the component of the vector gradient in that direction

Answer to question (A)

 $d\overline{r} = \hat{e} ds$

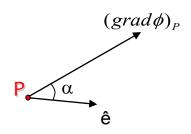
(7)

(8)

THEOREM 1 (4.1 in the textbook)

The direction of the maximum growth (rate of change) of a scalar field ϕ in the point P is the direction of the gradient in the point P. The maximum growth (rate of change) of ϕ per unit length is $|(grad\phi)_P|$

PROOF



a-let's calculate the derivative in the direction \hat{e} Eq. (8)

$$\frac{d\phi}{ds} = grad\phi \cdot \hat{e} = \left| grad\phi \right| \cos\alpha$$

b- this is maximum when:

 $\cos \alpha$ =1

which implies:

$$\alpha = 0$$
 (ê // grad ϕ) and $\frac{d\phi}{ds} = |_{\alpha}$

1 / gradø as

Answer to question (B)

THEOREM 2

If ϕ has a maximum or a minimum in the point P, then the gradient in P is zero.

PROOF

From Equation (8):

$$\frac{d\phi}{ds} = \operatorname{grad}\phi \cdot \hat{e}$$

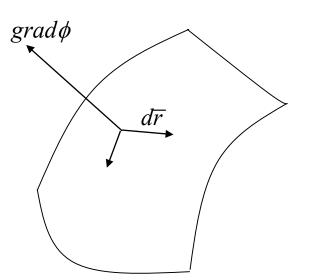
 ϕ has a maximum or a minimum in P $\Rightarrow d\phi/ds=0$

using equation (8), $d\phi/ds=0$ implies grad $\phi=0$

THEOREM 3 (4.2 in the textbook)

The gradient of a scalar field $\phi(x,y,z)$ in the point P is orthogonal to the level surface $\phi=c$ in P.

PROOF



- a- Let's do a small movement $d\overline{r}$ along the level surface
- b-Remember that on the level surface ϕ is constant:

dφ=0

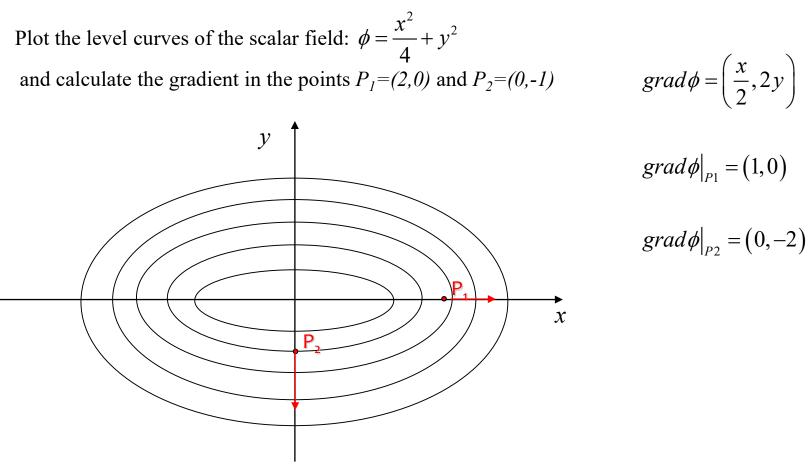
c- Then, using equation (6):

 $d\phi = grad\phi \cdot d\overline{r} = 0$

- d- This implies that $grad\phi$ is perpendicular to $d\overline{r}$
- e- $grad\phi$ is perpendicular to each $d\overline{r}$ on the level surface $grad\phi$ is perpendicular to the level surface

2D-EXAMPLE

- Theorems 1, 2 and 3 are valid also in two dimensions.
- $grad\phi$ is a vector field that:
 - in each point is orthogonal to the level curve in that point and
 - always points along the direction in which the height grows faster



ELECTROSTATIC POTENTIAL AND ELECTRIC FIELD

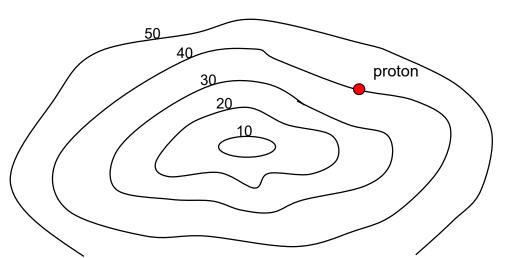
- Consider an electrostatic potential $V(\overline{r})$
- The electric field produced by $V(\overline{r})$ is: $\overline{E}(\overline{r}) = -grad V(\overline{r})$

(see the TET course for details)

• The force produced by $\overline{E}(\overline{r})$ on an electric charge q is: $\overline{F}(\overline{r}) = q\overline{E} = -q \operatorname{grad} V(\overline{r})$

EXERCISE:

• Consider a proton in an electrostatic potential:



In which direction will the proton move?

ELECTROSTATIC POTENTIAL AND ELECTRIC FIELD

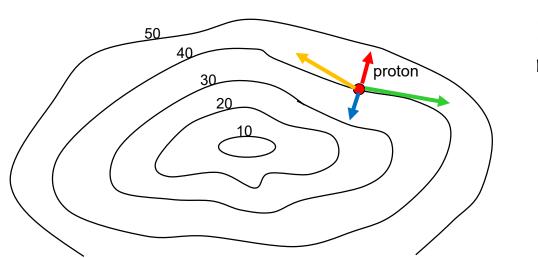
- Consider an electrostatic potential $V(\overline{r})$
- The electric field produced by $V(\overline{r})$ is: $\overline{E}(\overline{r}) = -grad V(\overline{r})$

(see the TET course for details)

• The force produced by $\overline{E}(\overline{r})$ on an electric charge q is: $\overline{F}(\overline{r}) = q\overline{E} = -q \operatorname{grad} V(\overline{r})$

EXERCISE:

• Consider a proton in an electrostatic potential:



In which direction will the proton move?

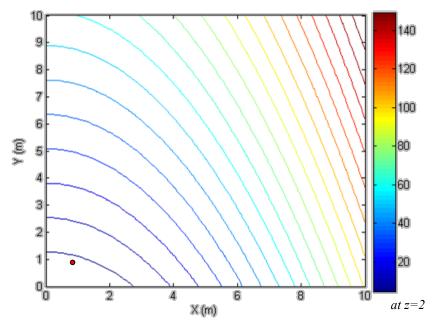
14

A mosquito is flying around in the room.

The temperature is described by the scalar field:

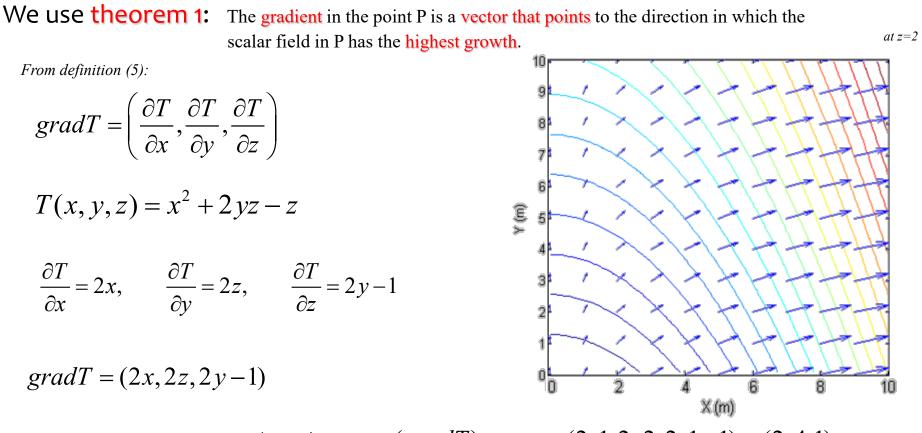
 $T(x,y,z)=x^2+2yz-z \quad [^{\circ}C]$

The mosquito is in the point P=(1,1,2)



- (a) In which direction the mosquito will fly to be in a warmer place as quick as possible?
- (b) How much the temperature changes in time if the mosquito flies with velocity 3m/s in direction (-2,2,1)?

(a) In which direction the mosquito will fly to be warm as quick as possible?



The mosquito is in P:(1,1,2) $(gradT)_{P=(1,1,2)} = (2 \cdot 1, 2 \cdot 2, 2 \cdot 1 - 1) = (2,4,1)$

The mosquito will fly in direction (2,4,1)

(b) How fast the temperature changes in time if the mosquito flies with velocity 3m/s in direction (-2,2,1)?

 $\frac{dT}{dt}$ where *t* is the time We must calculate Using equation (6): $\frac{dT}{dt} \stackrel{\downarrow}{=} gradT \cdot \frac{d\overline{r}}{dt} = gradT \cdot \hat{e}\frac{ds}{dt}$ where $\begin{cases} \frac{ds}{dt} = \left| \vec{v} \right| = \frac{3m}{s} \\ \hat{e} = \frac{\vec{v}}{\left| \vec{v} \right|} = \frac{(-2, 2, 1)}{\left| (-2, 2, 1) \right|} = \frac{(-2, 2, 1)}{\sqrt{(-2)^2 + 2^2 + 1^2}} = \frac{(-2, 2, 1)}{3} \end{cases} \implies \frac{d\vec{r}}{dt} = \frac{(-2, 2, 1)}{3} \cdot 3 = (-2, 2, 1)$

$$\frac{dT}{dt} = gradT \cdot \frac{d\bar{r}}{dt} = (2,4,1) \cdot (-2,2,1) = 5 \ [C/s]$$

WHICH STATEMENT IS WRONG?

1- A scalar field associates a real number to a point in space

2- The increase of a scalar field in a given direction can be calculated

with the directional derivative:
$$\frac{d\phi}{ds} = grad\phi \cdot \hat{e}$$

3- If ϕ is a scalar field, then

$$grad\phi = \left(\frac{\partial\phi}{\partial x}, \frac{\partial\phi}{\partial y}, \frac{\partial\phi}{\partial z}\right)$$
 in a spheric

in a spherical coordinate system

4- A vector field can be written as $\overline{A} = \overline{A}(x, y, z)$





