

SF 1684 Algebra and Geometry

Lecture 20

Patrick Meisner

KTH Royal Institute of Technology

Topics for Today

- ① Abstract Vector Space
- ② Linear Transformations of Abstract Vector Spaces
- ③ Isomorphisms of Abstract Vector Spaces

Axioms of a Vector Space

Recall from Lecture 1, that we defined a vector space as something that satisfies these axioms

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- ➒ (Distributivity) For every $c, d \in F$ and every $\vec{u}, \vec{v} \in V$,
 $(c + d) \cdot \vec{u} = c \cdot \vec{u} + d \cdot \vec{u}$ and $c \cdot (\vec{u} + \vec{v}) = c \cdot \vec{u} + c \cdot \vec{v}$

First Theorem

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Theorem

If \vec{v} is a vectors in a vector space V , and if k is a scalar, then

- ① $0\vec{v} = \vec{0}$
- ② $k\vec{0} = \vec{0}$
- ③ $(-1)\vec{v} = -\vec{v}$

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Now, we can begin to talk about the properties of vectors spaces we have dealt with. That is: linear dependence, subspaces, basis, linear transformations, etc...

Linear Dependence

Exercise

Let 1 denote the constant function that sends everything to 1 . Show that the set $\{1, \cos^2(x), \sin^2(x)\}$ is a linear **dependent** set of vectors in the vectors space of functions.

Three vectors are linearly dependent iff there exists $c_1, c_2, c_3 \neq 0$ such that $c_1 \vec{v}_1 + c_2 \vec{v}_2 + c_3 \vec{v}_3 = 0$

Can I find c_1, c_2, c_3 such that $*c_1 \cdot 1 + c_2 \cos^2 x + c_3 \sin^2 x = 0$
i.e. $*$ must be true for all x . ↑
the zero function

$$c_1 = -1, c_2 = 1, c_3 = 1$$

$$c_1 \cdot 1 + c_2 \cos^2 x + c_3 \sin^2 x = -1 + \cos^2 x + \sin^2 x = -1 + 1 = 0$$

↑
For all x

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Wronski's Test

If we have a set of functions from $\mathbb{R} \rightarrow \mathbb{R}$ given by

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then we define the **Wronskian of the functions** to be

$$W(x) := \det \left(\begin{pmatrix} f_1(x) & f_2(x) & \dots & f_n(x) \\ f_1'(x) & f_2'(x) & \dots & f_n'(x) \\ \vdots & \vdots & \ddots & \vdots \\ f_1^{(n-1)}(x) & f_2^{(n-1)}(x) & \dots & f_n^{(n-1)}(x) \end{pmatrix} \right)$$

Handwritten notes:

- $W(x)$ is underlined in blue.
- \det is circled in blue.
- Red arrow from $f_1(x)$ to "functions".
- Red arrow from $f_1'(x)$ to "derivative of functions".
- Red arrow from $f_1^{(n-1)}(x)$ to "(n-1)-st derivative function".
- A red bracket under the matrix is labeled with a red M .
- Red text "not derivative" is written near $W(x)$.

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Theorem (Wronski's Test)

A set of n functions from $\mathbb{R} \rightarrow \mathbb{R}$ are linearly independent if and only if the Wronskian of the functions is not identically zero.

Example of Wronski's Test

Exercise

Using that fact that if $f_1(x) = 1$, $f_2(x) = \cos^2(x)$ and $f_3(x) = \sin^2(x)$, then

$$f_1' = 0, f_1'' = 0, f_2' = -2 \sin(x) \cos(x), f_2'' = 2 \sin^2(x) - 2 \cos^2(x)$$

$$f_3' = 2 \sin(x) \cos(x), f_3'' = 2 \cos^2(x) - 2 \sin^2(x)$$

show that $\{f_1, f_2, f_3\}$ is linearly **dependent** by showing that the Wronskian is identically zero.

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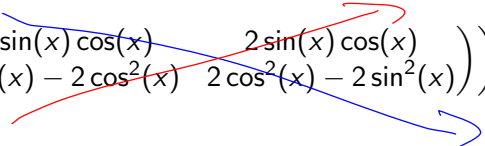
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Setting up the Wronskian, we see that

$$W(x) = \det \begin{pmatrix} \text{function} & \cos(x) & \sin(x) \\ \text{derivative} & -2 \sin(x) \cos(x) & 2 \sin(x) \cos(x) \\ \text{2nd deriv} & 2 \sin^2(x) - 2 \cos^2(x) & 2 \cos^2(x) - 2 \sin^2(x) \end{pmatrix}$$

Example of Wronski's Test 2

Expanding the determinant along the first column, we find that

$$W(x) = \det \left(\begin{pmatrix} -2 \sin(x) \cos(x) & 2 \sin(x) \cos(x) \\ 2 \sin^2(x) - 2 \cos^2(x) & 2 \cos^2(x) - 2 \sin^2(x) \end{pmatrix} \right)$$


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Subspaces of Abstract Vector Spaces

Definition

If W is a non empty subset of vectors in a vector space V that is itself a vector space under the same scalar multiplication and addition of V , then we call W a **subspace** of V .

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$$W_{n-1} = \{ \underbrace{a_0} + \underbrace{a_1x} + \underbrace{a_2x^2} + \cdots + \underbrace{a_{n-1}x^{n-1}} : a_i \in \mathbb{R} \}$$

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Linear Independent Polynomials

Exercise

Using the fact that if $f_j(x) = x^j$ then $f_m^{(m)}(x) = m!$ and $f_j^{(m)}(x) = 0$ if $j < m$, show that the set $\{f_0, f_1, \dots, f_{n-1}\}$ is linear independent for any n .

M2J

$$\{1, x, x^2, \dots, x^{n-1}\}$$

If there is a c_0, c_1, \dots, c_{n-1} s.t. $c_0 + c_1 x + \dots + c_{n-1} x^{n-1} = 0$

for all x

as function

$$\Rightarrow c_0, c_1, \dots, c_{n-1} = 0$$

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Using the fact, we see that the Wronskian of the vectors will be

$$W(x) = \det \begin{pmatrix} \overset{f_0}{1} & \overset{f_1}{x} & \overset{f_2}{x^2} & \overset{f_3}{x^3} & \dots & \overset{f_{n-1}}{x^{n-1}} \\ \underset{f_0'}{0} & \underset{f_1'}{1} & * & * & \dots & * \\ \underset{f_0''}{0} & \underset{f_1''}{0} & \underset{f_2''}{2} & * & \dots & * \\ \underset{f_0'''}{0} & \underset{f_1'''}{0} & \underset{f_2'''}{0} & \underset{f_3'''}{6} & \dots & * \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ \underset{f_0^{(n-1)}}{0} & \underset{f_1^{(n-1)}}{0} & \underset{f_2^{(n-1)}}{0} & \underset{f_3^{(n-1)}}{0} & \dots & (n-1)! \end{pmatrix} \begin{matrix} \text{--- function} \\ \text{--- derivative} \end{matrix}$$

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Using the fact, we see that the Wronskian of the vectors will be

$$W(x) = \det \begin{pmatrix} \underbrace{1}_{f_0} & x & x^2 & x^3 & \dots & x^{n-1} \\ 0 & \underbrace{1}_{f_1} & * & * & \dots & * \\ 0 & 0 & \underbrace{2}_{f_2} & * & \dots & * \\ 0 & 0 & 0 & \underbrace{6}_{f_3} & \dots & * \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & \underbrace{(n-1)!}_{f_{n-1}} \end{pmatrix}$$
$$= \underbrace{1} \times \underbrace{1} \times \underbrace{2} \times \underbrace{6} \times \dots \times \underbrace{(n-1)!}$$

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$$W(x) = \det \begin{pmatrix} \begin{pmatrix} 1 & x & x^2 & x^3 & \dots & x^{n-1} \\ 0 & 1 & * & * & \dots & * \\ 0 & 0 & 2 & * & \dots & * \\ 0 & 0 & 0 & 6 & \dots & * \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & (n-1)! \end{pmatrix} \end{pmatrix}$$
$$= 1 \times 1 \times 2 \times 6 \times \dots \times (n-1)! \neq 0$$

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Moreover, clearly any polynomials of degree at most $n - 1$ can be written as a linear combination of vectors in $\{1, x, x^2, \dots, x^{n-1}\}$ and so it is a spanning set.

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Thus, we may conclude that $\{1, x, x^2, \dots, x^{n-1}\}$ is a *basis* for the polynomials of degree at most $n - 1$.

Hence, if $W_{n-1} = \{a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1} : a_i \in \mathbb{R}\}$, then

$$\dim(W_{n-1})$$

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So we see that $\{1, x, x^2, \dots, x^{n-1}\}$ is a linearly independent set of vectors.

Moreover, clearly any polynomials of degree at most $n - 1$ can be written as a linear combination of vectors in $\{1, x, x^2, \dots, x^{n-1}\}$ and so it is a spanning set.

Thus, we may conclude that $\{1, x, x^2, \dots, x^{n-1}\}$ is a *basis* for the polynomials of degree at most $n - 1$.

Hence, if $W_{n-1} = \{a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1} : a_i \in \mathbb{R}\}$, then

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Infinite Dimensional Vector Space

However, what if we want to consider the set of polynomials of any degree $W = \{a_0 + a_1x + a_2x^2 + \cdots + a_nx^n : a_i \in \mathbb{R}, \underline{n \geq 0}\}$.

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Then we see that a basis for this would necessarily be all the powers x : $\{1, x, x^2, x^3, \dots\}$.

$\{1, x, x^2, \dots, x^n\}$ is linear independent for all n

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Moreover, since all polynomials are also functions, we see that the vector space of all functions from the reals to the reals is also infinite dimensional.

Question: what is the basis of all functions?

Unusual Vector Space

The vector space axioms do not suppose that the vector addition and scalar multiplication behave in a way that we are used to, only that they satisfy the properties of the axioms.

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Exercise

Let V be the set of positive real numbers but define vector addition and scalar multiplication by \mathbb{R} as follows:

$$\downarrow \quad \text{multiplication - w real numbers} \\ \underline{u \oplus v} = u \cdot v \text{ (vector addition)}$$

$k \in \mathbb{R}$

$$\begin{matrix} \leftarrow \uparrow & & \uparrow \\ k \otimes u = u^k \text{ (scalar multiplication by } \mathbb{R}) \end{matrix}$$

u, v are vectors
in V so
def u , in particular
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Show that these operations satisfy the axioms and hence makes V a vector space.

What is $\vec{0}$?
What is $(-u)$?

↑
Set of all
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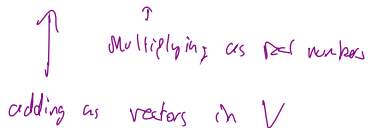
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adding as vectors in V
multiplying as real numbers

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So, in this vector space $\vec{0} = 1$.

$$\begin{array}{c} 2 \oplus 1 = 2 \cdot 1 = 2 \\ \uparrow \\ \text{adding in vector } \in V \end{array}$$

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$u \oplus (-u) = \vec{0}$
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definition of $-u$

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as a Set is the real numbers

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\uparrow addition of vectors \uparrow multiplication of real numbers

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$$(-2) = \frac{1}{2}$$

V is the set
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\uparrow
Scalar multiplication of vector in V

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definition of scalar multiplication

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Handwritten notes:
- A purple arrow points from "scalar multip" to (-1) .
- A purple arrow points from "real number" to u .
- A purple arrow points from "exponentiation" to u^{-1} .

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Solution 2

Axiom 7 - If k is a scalar, then $k \otimes (u \oplus v) = (k \otimes u) \oplus (k \otimes v)$.

$$k(u+v) = ku + kv$$

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↑
vector
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↑
real
number
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scalar multiplication real number exponentiation

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\uparrow \uparrow

real scalar
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Remark

Even though the set of element in V are the real numbers, V is **NOT** a subspace of \mathbb{R} or any other \mathbb{R}^n ! This is because in order to be a subspace, the vector addition and scalar multiplication must be the *same* in both spaces!! Clearly the vector addition and scalar multiplication in V and \mathbb{R} are different.

Linear Transformations Between Abstract Vector Spaces

Definition

If $T : V \rightarrow W$ is a function from a vector space V to a vector space W then T is called a **linear transformation** from V to W if the following properties hold for all vectors \vec{u}, \vec{v} and for all scalars c

- ① $T(c\vec{u}) = cT(\vec{u})$
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Theorem

If $T : V \rightarrow W$ is a linear transformation, then:

- ① $T(\vec{0}) = \vec{0}$
- ② $T(-\vec{u}) = -T(\vec{u})$
- ③ $T(\vec{u} - \vec{v}) = T(\vec{u}) - T(\vec{v})$

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Kernel and Range

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Theorem

If $T : V \rightarrow W$ is a linear transformation then $\ker(T)$ is subspace of V and $\text{ran}(T)$ is a subspace of W .

One-to-one and Onto

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The difference in bijection & isomorphism
comes into play when considering finite dimensional
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Any n -dimensional vector space defined over the reals is isomorphic to \mathbb{R}^n .

in particular finite dimensional



Proof.

with scalars that are the reals

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Let V be an n -dimensional vectors space. Then there is a basis for V : $B = \{\vec{v}_1, \dots, \vec{v}_n\}$. Then the linear transformation defined by

$$T(\underline{a_1 \vec{v}_1 + a_2 \vec{v}_2 + \dots + a_n \vec{v}_n}) = \underline{a_1 \vec{e}_1} + \underline{a_2 \vec{e}_2} + \dots + \underline{a_n \vec{e}_n} \in \mathbb{R}^n$$

is an isomorphism.

check: that this is a linear transformation \square
if one-to-one and onto

Examples

Let $V = \{f : \mathbb{R} \rightarrow \mathbb{R}\}$ and let x_1, x_2, \dots, x_n be any set of real numbers.

Examples

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Exercise: prove this is linear

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If all the x_i were distinct then the range would be all of \mathbb{R}^n . So it would be onto.

Suppose $x_1 = x_2$ then $f(x_1) = f(x_2)$ and therefore can not
anything in \mathbb{R}^n with different 1st & 2nd coordinate.

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Handwritten notes:

$$\begin{aligned} f(x) &= 1 \\ f(x_1) &= 1 \\ f(x_2) &= 1 - \end{aligned}$$
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Matrix of Evaluation Function

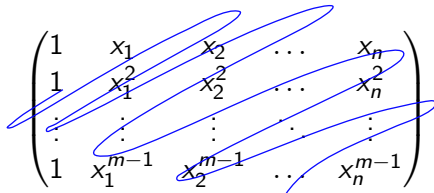
Thus we see that T can be given by the matrix

$$\begin{pmatrix} 1 & x_1 & x_2 & \dots & x_n \\ 1 & x_1^2 & x_2^2 & \dots & x_n^2 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_1^{m-1} & x_2^{m-1} & \dots & x_n^{m-1} \end{pmatrix}$$

$$\begin{matrix} T(1) & T(x) & T(x^2) & \dots & T(x^{n-1}) \\ \downarrow & \downarrow & \downarrow & & \downarrow \\ \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} & \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} & \begin{bmatrix} x_1^2 \\ \vdots \\ x_n^2 \end{bmatrix} & \dots & \begin{bmatrix} x_1^{n-1} \\ \vdots \\ x_n^{n-1} \end{bmatrix} \end{matrix}$$

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The matrix is a square matrix with m rows and $n+1$ columns. The first column contains all 1s. The subsequent columns contain powers of x_1, x_2, \dots, x_n . Specifically, the j -th column (for $j \geq 1$) contains $x_1^j, x_2^j, \dots, x_n^j$. Blue diagonal lines are drawn from the top-left to the bottom-right, passing through the elements $(1,1)$, $(2,2)$, $(3,3)$, $(4,4)$, and $(m, m+1)$.

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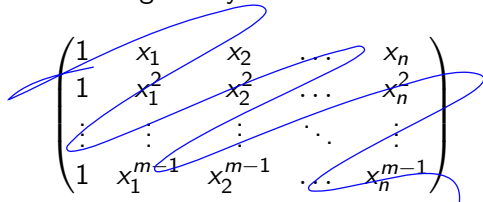
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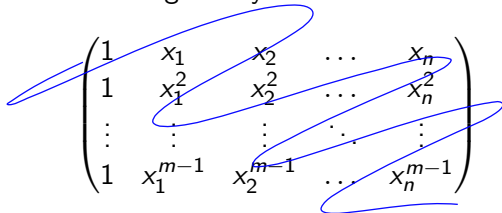

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For any real number $c_1, c_2, \dots, c_n, x_1, x_2, \dots, x_n$ you can find a polynomial of degree n such that

Conclusion About Polynomials

for all $\vec{c} \in \mathbb{R}^n$ I can find $f \in \mathcal{P}_n$ s.t.
 $T(f) = \vec{c}$

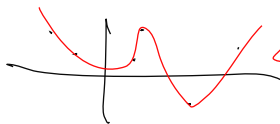
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For any real number $c_1, c_2, \dots, c_n, x_1, x_2, \dots, x_n$ you can find a polynomial of degree n such that

$$f(x_1) = c_1, f(x_2) = c_2, \dots, f(x_n) = c_n$$

$(x_1, c_1), (x_2, c_2), \dots, (x_n, c_n)$ as points in the plane



← can find poly $p(x)$ that goes through all the points

More Examples

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*Take a polynomial of degree n and
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array of zeroes

Final Example

The trace function from the $n \times n$ square matrices to \mathbb{R} is also a linear transformation:

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