

SF 1684 Algebra and Geometry

Lecture 13

Patrick Meisner

KTH Royal Institute of Technology

Topics for Today

- ① Dimension Theorem
- ② Rank Theorem
- ③ Pivot Theorem

Nullity and Dimension Theorem

Nullity and Dimension Theorem

Definition

We will define the **nullity** of matrix A to be $\text{nullity}(A) = \dim(\text{null}(A))$.

$$\text{nullity}(A) = \dim(\text{null}(A)) = \# \text{ free variables in RREF of } A.$$

Nullity and Dimension Theorem

Definition

We will define the **nullity** of matrix A to be $\text{nullity}(A) = \dim(\text{null}(A))$.

Theorem (Dimension Theorem)

Let A be an $m \times \underline{n}$ matrix, then

$$\text{rk}(A) + \text{nullity}(A) = n \approx \text{\# of columns of } A.$$

Nullity and Dimension Theorem

Definition

We will define the **nullity** of matrix A to be $\text{nullity}(A) = \dim(\text{null}(A))$.

Theorem (Dimension Theorem)

Let A be an $m \times n$ matrix, then

$$\text{rk}(A) + \text{nullity}(A) = n$$

Proof.

Indeed, we know that

$$\begin{aligned} n &= \text{number of columns} \\ &= \text{number of leading ones} + \text{number of free variable} \\ &= \text{rk}(A) + \dim(\text{null}(A)) = \text{rk}(A) + \text{nullity}(A) \end{aligned}$$

Definition

For any subspace W of $\mathbb{R}^n$, we define the **perp space** of W , denote $W^\perp$, to be the set of all vectors whose dot product with every vector in W is 0:

Definition

For any subspace W of $\mathbb{R}^n$, we define the **perp space** of W , denote $W^\perp$, to be the set of all vectors whose dot product with every vector in W is 0:

$$W^\perp = \{ \vec{v} \in \mathbb{R}^n : \vec{v} \cdot \vec{w} = 0 \text{ for all } \vec{w} \in W \}$$

Definition

For any subspace W of $\mathbb{R}^n$, we define the **perp space** of W , denote $W^\perp$, to be the set of all vectors whose dot product with every vector in W is 0:

$$W^\perp = \{\vec{v} \in \mathbb{R}^n : \vec{v} \cdot \vec{w} = 0 \text{ for all } \vec{w} \in W\}$$

It is called the perp space because everything in $W^\perp$ is orthogonal (or perpendicular) to everything in W .

Perp Space

Definition

For any subspace W of $\mathbb{R}^n$, we define the **perp space** of W , denote $W^\perp$, to be the set of all vectors whose dot product with every vector in W is 0:

$$W^\perp = \{\vec{v} \in \mathbb{R}^n : \vec{v} \cdot \vec{w} = 0 \text{ for all } \vec{w} \in W\}$$

It is called the perp space because everything in $W^\perp$ is orthogonal (or perpendicular) to everything in W .

Theorem

For any subspace W of $\mathbb{R}^n$, $W^\perp$ is also a subspace of $\mathbb{R}^n$.

Proof: $u, v \in W^\perp \quad u+v \in W^\perp \Leftrightarrow (u+v) \cdot \vec{w} = 0 \text{ for all } \vec{w} \in W$
 $(u+v) \cdot w = u \cdot w + v \cdot w = 0 + 0 = 0 \text{ for all } w \in W$ & so $u+v \in W^\perp$
 $cu \in W^\perp \text{ \& } c \in \mathbb{R} \quad \text{then } cu \in W^\perp \Leftrightarrow (cu) \cdot w = 0 \text{ for all } w \in W$
 $(cu) \cdot w = c(u \cdot w) = c(0) = 0 \text{ for } w \in W$ & so $cu \in W^\perp$

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$.

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$.

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x}$$

for all $t \in \mathbb{R}$

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n$$

$$a = \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

for all $t \in \mathbb{R}$.

$$\text{for } t=1: \quad a_1x_1 + \cdots + a_nx_n = 0 \quad *$$

$\Uparrow$

equation for hyperplane with
normal $\vec{a}$.

Moreover if $*$ then $(\vec{a}t) \cdot \vec{x} = 0$ for all t .

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

We often just write $\vec{a}^\perp$ for $L^\perp$

$$\vec{a}^\perp = L^\perp$$

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

We often just write $\vec{a}^\perp$ for $L^\perp$.

What is the perp space of all of $\mathbb{R}^n$?

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

We often just write $\vec{a}^\perp$ for $L^\perp$.

What is the perp space of all of $\mathbb{R}^n$? It would have to be the set of vectors that is orthogonal (perpendicular) to all vectors in $\mathbb{R}^n$.

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

We often just write $\vec{a}^\perp$ for $L^\perp$.

What is the perp space of all of $\mathbb{R}^n$? It would have to be the set of vectors that is orthogonal (perpendicular) to all vectors in $\mathbb{R}^n$. And so in particular, would need to be the orthogonal to the standard vectors e_i for all i .

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix} \quad \dots$$

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

We often just write $\vec{a}^\perp$ for $L^\perp$.

What is the perp space of all of $\mathbb{R}^n$? It would have to be the set of vectors that is orthogonal (perpendicular) to all vectors in $\mathbb{R}^n$. And so in particular, would need to be the orthogonal to the standard vectors e_i for all i . Hence if $\vec{x} \in (\mathbb{R}^n)^\perp$, then

$$0 = \vec{e}_i \cdot \vec{x}$$

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

We often just write $\vec{a}^\perp$ for $L^\perp$.

What is the perp space of all of $\mathbb{R}^n$? It would have to be the set of vectors that is orthogonal (perpendicular) to all vectors in $\mathbb{R}^n$. And so in particular, would need to be the orthogonal to the standard vectors e_i for all i . Hence if $\vec{x} \in (\mathbb{R}^n)^\perp$, then

$$0 = \vec{e}_i \cdot \vec{x} = 0 * x_1 + 0 * x_2 + \cdots + \underline{1 * x_i} + \cdots + 0 * x_n = x_i$$

for all i

Examples

Let $\vec{a}$ be a vector in $\mathbb{R}^n$, and $L = \{\vec{a}t : t \in \mathbb{R}\}$, be the line in $\mathbb{R}^n$ in the direction of $\vec{a}$. Then $L^\perp$ is the hyperplane in $\mathbb{R}^n$ with normal $\vec{a}$. Indeed, if $\vec{x} \in L^\perp$, then

$$0 = (\vec{a}t) \cdot \vec{x} = a_1tx_1 + a_2tx_2 + \cdots + a_n tx_n = t(a_1x_1 + a_2x_2 + \cdots + a_nx_n)$$

We often just write $\vec{a}^\perp$ for $L^\perp$. *It is enough to just check $\vec{a} \cdot \vec{x} = 0$
Note $\{\vec{a}\}$ is a basis for L*

What is the perp space of all of $\mathbb{R}^n$? It would have to be the set of vectors that is orthogonal (perpendicular) to all vectors in $\mathbb{R}^n$. And so in particular, would need to be the orthogonal to the standard vectors e_i for all i . Hence if $\vec{x} \in (\mathbb{R}^n)^\perp$, then *It is enough to check $e_i \cdot \vec{x} = 0$ for all i
and $\{e_1, \dots, e_n\}$ form a basis for $\mathbb{R}^n$*

$$0 = \vec{e}_i \cdot \vec{x} = 0 * x_1 + 0 * x_2 + \cdots + 1 * x_i + \cdots + 0 * x_n = x_i$$

And we see that $(\mathbb{R}^n)^\perp = \{\vec{0}\}$, the zero-subspace.

*If $\vec{x} = \vec{0}$ then
 $\vec{x} \cdot \vec{v} = 0$ for all $\vec{v} \in \mathbb{R}^n$*

Perp Space and Bases

Theorem

If W is a subspace of $\mathbb{R}^n$ with basis $\{\vec{b}_1, \dots, \vec{b}_k\}$, then $\vec{v} \in W^\perp$ if and only if $\vec{v} \cdot \vec{b}_i = 0$ for $i = 1, \dots, k$.

Proof: ($\Rightarrow$) If $\vec{v} \in W^\perp$ then $\vec{v} \cdot \vec{w} = 0$ for $\vec{w} \in W$
in particular $\vec{v} \cdot \vec{b}_i = 0$ for all i as $\vec{b}_i \in W$.

($\Leftarrow$) Suppose $\vec{v} \cdot \vec{b}_i = 0$ for all $i = 1, \dots, k$. Let $\vec{w} \in W$ then
can write $\vec{w} = t_1 \vec{b}_1 + \dots + t_k \vec{b}_k$.

$$\begin{aligned}\vec{v} \cdot \vec{w} &= \vec{v} \cdot (t_1 \vec{b}_1 + \dots + t_k \vec{b}_k) = t_1 (\vec{v} \cdot \vec{b}_1) + \dots + t_k (\vec{v} \cdot \vec{b}_k) \\ &= t_1 \cdot 0 + \dots + t_k \cdot 0 = 0\end{aligned}$$

& so $\vec{v} \in W^\perp$

□

Perp Space and Null Space

Corollary

If W is a subspace of $\mathbb{R}^n$ with basis $\{\vec{b}_1, \dots, \vec{b}_k\}$, then $W^\perp$ is the null space of the matrix whose rows are the $\vec{b}_i$.

proof:

$$B = \begin{bmatrix} \vec{b}_1 \\ \vdots \\ \vec{b}_k \end{bmatrix}$$

$$x \in \text{null}(B) \Leftrightarrow B\vec{x} = \vec{0}$$

$$\Leftrightarrow \begin{bmatrix} \vec{b}_1 \\ \vdots \\ \vec{b}_k \end{bmatrix} \vec{x} = \vec{0}$$

$$\Leftrightarrow \begin{bmatrix} \vec{b}_1 \cdot \vec{x} \\ \vdots \\ \vec{b}_k \cdot \vec{x} \end{bmatrix} = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$\Leftrightarrow \vec{b}_i \cdot \vec{x} = 0 \text{ for all } i$$

$$\Leftrightarrow x \in W^\perp$$

Aside: Commonly we want to consider the matrix A with the columns of the basis vectors.
 $A = [\vec{b}_1, \dots, \vec{b}_k]$. But notice

$B = A^T$. Then we conclude

that $W^\perp = \text{null}(A^T)$

Perp Space and Dimension Theorem

Theorem

If W is a subspace of $\mathbb{R}^n$, then $n = \dim(W) + \dim(W^\perp)$.

Prove: Suppose W has a basis $b_1 \dots b_k$

Let $B = \begin{bmatrix} b_1 \\ \vdots \\ b_k \end{bmatrix}$. I know that since $b_1 \dots b_k$ are linearly independent, then every row will have a leading 1.

$$B \rightarrow \begin{bmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{bmatrix} \Rightarrow \text{rk}(B) = k = \dim W$$

from previous $\dim W^\perp = \text{nullity}(B)$

Dimension thm: $n = \text{rk}(B) + \text{nullity}(B) = \dim W + \dim W^\perp$.

Rank Theorem

Recall the column space of a matrix $\text{col}(A)$, is the spanning set of the column vectors of A .

Rank Theorem

Recall the column space of a matrix $\text{col}(A)$, is the spanning set of the column vectors of A . We define the row space of a matrix, $\text{row}(A)$ to be the spanning set of the row vectors of A .

Rank Theorem

Recall the column space of a matrix $\text{col}(A)$, is the spanning set of the column vectors of A . We define the row space of a matrix, $\text{row}(A)$ to be the spanning set of the row vectors of A .

Theorem (Rank Theorem)

The row space and column space of a matrix have the same dimension.

Rank Theorem

Recall the column space of a matrix $\text{col}(A)$, is the spanning set of the column vectors of A . We define the row space of a matrix, $\text{row}(A)$ to be the spanning set of the row vectors of A .

Theorem (Rank Theorem)

The row space and column space of a matrix have the same dimension.

Theorem (Rank Theorem)

If A is an $m \times n$ matrix, then

$$\text{col}(A^T) = \text{row}(A)$$

$$\text{rk}(A) = \text{rk}(A^T)$$

$$\begin{aligned} \text{rk}(A) &= \dim(\text{col}(A)) \implies \\ \text{rk}(A^T) &= \dim(\text{col}(A^T)) = \dim(\text{row}(A)) \end{aligned}$$

Sketch of Proof

We will sketch the proof that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$.

Sketch of Proof

We will sketch the proof that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$. To prove equality, it then is enough to replace A with A^T .

In particular this shows that

$$\dim(\text{row}(A)) = \dim(\text{col}(A^T)) \leq \dim(\text{row}(A^T)) = \dim(\text{col}(A))$$

now I have $\dim(\text{col}(A)) \leq \dim(\text{row}(A)) \leq \dim(\text{col}(A))$

So they must be equal

Sketch of Proof

We will sketch the proof that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$. To prove equality, it then is enough to replace A with A^T .

Let A be an $m \times n$ matrix. Then we know that $\text{col}(A)$ is a subspace of $\mathbb{R}^m$ and so $\dim(\text{col}(A)) \leq m$.

$$A = (c_1 \cdots c_n) \quad c_i \in \mathbb{R}^m$$

Sketch of Proof

We will sketch the proof that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$. To prove equality, it then is enough to replace A with A^T .

Let A be an $m \times n$ matrix. Then we know that $\text{col}(A)$ is a subspace of $\mathbb{R}^m$ and so $\dim(\text{col}(A)) \leq m$.

Moreover, we know that $\text{row}(A)$ is a subspace of $\mathbb{R}^n$ spanned by m vectors and so $\dim(\text{row}(A)) \leq m$.

$$A = \begin{bmatrix} a_{11} \\ \vdots \\ a_{m1} \end{bmatrix}$$

Sketch of Proof

We will sketch the proof that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$. To prove equality, it then is enough to replace A with A^T .

Let A be an $m \times n$ matrix. Then we know that $\text{col}(A)$ is a subspace of $\mathbb{R}^m$ and so $\dim(\text{col}(A)) \leq m$.

Moreover, we know that $\text{row}(A)$ is a subspace of $\mathbb{R}^n$ spanned by m vectors and so $\dim(\text{row}(A)) \leq m$. If $\dim(\text{row}(A)) = m$, then we get that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$.

Sketch of Proof

We will sketch the proof that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$. To prove equality, it then is enough to replace A with A^T .

Let A be an $m \times n$ matrix. Then we know that $\text{col}(A)$ is a subspace of $\mathbb{R}^m$ and so $\dim(\text{col}(A)) \leq m$.

Moreover, we know that $\text{row}(A)$ is a subspace of $\mathbb{R}^n$ spanned by m vectors and so $\dim(\text{row}(A)) \leq m$. If $\dim(\text{row}(A)) = m$, then we get that $\dim(\text{col}(A)) \leq \dim(\text{row}(A))$.

If $\dim(\text{row}(A)) < m$, then one row of A must be written as a linear combination of the rest. That is, there exists $c_1, \dots, c_{m-1}$ such that

$$\vec{r}_m = c_1 \vec{r}_1 + \dots + c_{m-1} \vec{r}_{m-1}$$

Sketch of Proof 2

We have

$$\vec{r}_m = c_1 \vec{r}_1 + \cdots c_{m-1} \vec{r}_{m-1}$$

Sketch of Proof 2

We have

$$\vec{r}_m = c_1 \vec{r}_1 + \cdots + c_{m-1} \vec{r}_{m-1}$$

$$\vec{r}_m \approx \begin{bmatrix} a_{m,1} \\ \vdots \\ a_{m,n} \end{bmatrix}$$

Looking at the j^{th} entry of the row vectors, we get

$$a_{m,j} = c_1 a_{1,j} + \cdots + c_{m-1} a_{m-1,j}$$

Sketch of Proof 2

We have

$$\vec{r}_m = c_1 \vec{r}_1 + \cdots c_{m-1} \vec{r}_{m-1}$$

Looking at the j^{th} entry of the row vectors, we get

$$a_{m,j} = c_1 a_{1,j} + \cdots + c_{m-1} a_{m-1,j}$$

and so each column vector

$$\vec{c}_j = \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{m,j} \end{bmatrix}$$

$$A = \begin{pmatrix} r_1 \\ \vdots \\ r_n \end{pmatrix} = \begin{pmatrix} c_{1,1} & \cdots & c_{1,n} \\ \vdots & & \vdots \\ c_{m,1} & \cdots & c_{m,n} \end{pmatrix}$$

Sketch of Proof 2

We have

$$\vec{r}_m = c_1 \vec{r}_1 + \cdots + c_{m-1} \vec{r}_{m-1}$$

Looking at the j^{th} entry of the row vectors, we get

$$a_{m,j} = c_1 a_{1,j} + \cdots + c_{m-1} a_{m-1,j}$$

and so each column vector

$$\vec{c}_j = \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{m,j} \end{bmatrix} = c_1 \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{1,j} \end{bmatrix} + \cdots + c_{m-1} \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{m-1,j} \end{bmatrix}$$

Sketch of Proof 2

We have

$$\vec{r}_m = c_1 \vec{r}_1 + \cdots + c_{m-1} \vec{r}_{m-1}$$

Looking at the j^{th} entry of the row vectors, we get

$$a_{m,j} = c_1 a_{1,j} + \cdots + c_{m-1} a_{m-1,j}$$

and so each column vector

$$\vec{c}_j = \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{m,j} \end{bmatrix} = c_1 \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{1,j} \end{bmatrix} + \cdots + c_{m-1} \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{m-1,j} \end{bmatrix}$$

can be written as a linear combination of $m - 1$ vectors and so $\dim(\text{col}(A)) \leq m - 1$.

$$\text{col}(A) \subseteq \text{span}(v_1, \dots, v_{n-1})$$

Sketch of Proof 2

We have

$$\vec{r}_m = c_1 \vec{r}_1 + \cdots + c_{m-1} \vec{r}_{m-1}$$

Looking at the j^{th} entry of the row vectors, we get

$$a_{m,j} = c_1 a_{1,j} + \cdots + c_{m-1} a_{m-1,j}$$

and so each column vector

$$\vec{c}_j = \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{m,j} \end{bmatrix} = c_1 \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{1,j} \end{bmatrix} + \cdots + c_{m-1} \begin{bmatrix} a_{1,j} \\ \vdots \\ a_{m-1,j} \end{bmatrix}$$

can be written as a linear combination of $m - 1$ vectors and so $\dim(\text{col}(A)) \leq m - 1$.

Fundamental Spaces of a Matrix

If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix and so applying the dimension and rank theorems to A^T we get

$$m = \text{rk}(A^T) + \text{nullity}(A^T)$$

Fundamental Spaces of a Matrix

If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix and so applying the dimension and rank theorems to A^T we get

$$m = \text{rk}(A^T) + \text{nullity}(A^T) = \text{rk}(A) + \text{nullity}(A^T)$$

Fundamental Spaces of a Matrix

If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix and so applying the dimension and rank theorems to A^T we get

$$m = \text{rk}(A^T) + \text{nullity}(A^T) = \text{rk}(A) + \text{nullity}(A^T)$$

Therefore, knowing the rank of the matrix immediately tells us the dimensions of these four fundamental spaces of a matrix.

Fundamental Spaces of a Matrix

If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix and so applying the dimension and rank theorems to A^T we get

$$m = \text{rk}(A^T) + \text{nullity}(A^T) = \text{rk}(A) + \text{nullity}(A^T)$$

Therefore, knowing the rank of the matrix immediately tells us the dimensions of these four fundamental spaces of a matrix.

Theorem

If A is an $m \times n$ matrix with rank k , then

$$\dim(\text{row}(A)) = k$$

Fundamental Spaces of a Matrix

If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix and so applying the dimension and rank theorems to A^T we get

$$m = \text{rk}(A^T) + \text{nullity}(A^T) = \text{rk}(A) + \text{nullity}(A^T)$$

Therefore, knowing the rank of the matrix immediately tells us the dimensions of these four fundamental spaces of a matrix.

Theorem

If A is an $m \times n$ matrix with rank k , then

$$\dim(\text{row}(A)) = k \qquad \dim(\text{null}(A)) = n - k$$

Fundamental Spaces of a Matrix

If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix and so applying the dimension and rank theorems to A^T we get

$$m = \text{rk}(A^T) + \text{nullity}(A^T) = \text{rk}(A) + \text{nullity}(A^T)$$

Therefore, knowing the rank of the matrix immediately tells us the dimensions of these four fundamental spaces of a matrix.

Theorem

If A is an $m \times n$ matrix with rank k , then

$$\dim(\text{row}(A)) = k$$

$$\dim(\text{null}(A)) = n - k$$

$$\dim(\text{col}(A)) = k$$

Fundamental Spaces of a Matrix

If A is an $m \times n$ matrix, then A^T is an $n \times m$ matrix and so applying the dimension and rank theorems to A^T we get

$$m = \text{rk}(A^T) + \text{nullity}(A^T) = \text{rk}(A) + \text{nullity}(A^T)$$

Therefore, knowing the rank of the matrix immediately tells us the dimensions of these four fundamental spaces of a matrix.

Theorem

If A is an $m \times n$ matrix with rank k , then

$$\dim(\text{row}(A)) = k$$

$$\dim(\text{null}(A)) = n - k$$

$$\dim(\text{col}(A)) = k$$

$$\dim(\text{null}(A^T)) = m - k$$

Consistency and Rank

Theorem

If $A\vec{x} = \vec{b}$ is a linear system of m equations in n unknowns, then the following statements are equivalent

- 1 $A\vec{x} = \vec{b}$
- 2 $\vec{b}$ is in the column space of A
- 3 The coefficient matrix A and the augmented matrix $(A|\vec{b})$ have the same rank.

Full Rank

Definition

An $m \times n$ is said to have **full column rank** if its column vectors are linearly independent

Full Rank

Definition

An $m \times n$ is said to have **full column rank** if its column vectors are linearly independent and it is said to have **full row rank** if its row vectors are linearly independent.

Full Rank

Definition

An $m \times n$ is said to have **full column rank** if its column vectors are linearly independent and it is said to have **full row rank** if its row vectors are linearly independent.

Theorem

Let A be an $m \times n$ matrix.

- 1 A has full column rank if and only if the column vectors form a basis for the column space if and only if $\text{rk}(A) = n$
- 2 A has full row rank if and only if the row vectors form a basis for the row space if and only if $\text{rk}(A) = m$

Full Column Rank and Solutions

Theorem

If A is an $m \times n$ matrix then the following are equivalent

- ① $A\vec{x} = 0$ has only the trivial solution
- ② $A\vec{x} = \vec{b}$ has at most one solution for every $\vec{b} \in \mathbb{R}^m$
- ③ A has full column rank

Over- and Underdetermined

Theorem

Let A be an $m \times n$ matrix.

- 1 If $m > n$, then the system $A\vec{x} = \vec{b}$ is inconsistent for some vector $\vec{b}$ in $\mathbb{R}^m$. This is called **overdetermined**.
- 2 If $m < n$, then for every vector $\vec{b}$ in $\mathbb{R}^m$ the system $A\vec{x} = \vec{b}$ is either inconsistent or has infinitely many solutions. This is called **underdetermined**.

Pivot Theorem

Theorem

Pivot Theorem The pivot columns of a nonzero matrix A form a basis for the column space of A .

Pivot Theorem

Theorem

Pivot Theorem The pivot columns of a nonzero matrix A form a basis for the column space of A .

Example:

$$A = \begin{pmatrix} 7 & 1 & 9 & 6 \\ 5 & 3 & 11 & 2 \\ 7 & 2 & 11 & 5 \\ 7 & -2 & 3 & 9 \\ 0 & 1 & 2 & -1 \end{pmatrix}$$

Pivot Theorem

Theorem

Pivot Theorem The pivot columns of a nonzero matrix A form a basis for the column space of A .

Example:

$$A = \begin{pmatrix} 7 & 1 & 9 & 6 \\ 5 & 3 & 11 & 2 \\ 7 & 2 & 11 & 5 \\ 7 & -2 & 3 & 9 \\ 0 & 1 & 2 & -1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Pivot Theorem

Theorem

Pivot Theorem The pivot columns of a nonzero matrix A form a basis for the column space of A .

Example:

$$A = \begin{pmatrix} 7 & 1 & 9 & 6 \\ 5 & 3 & 11 & 2 \\ 7 & 2 & 11 & 5 \\ 7 & -2 & 3 & 9 \\ 0 & 1 & 2 & -1 \end{pmatrix} \Rightarrow \begin{pmatrix} 1 & 0 & 1 & 1 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

And so a basis for the column space of A would be

$$\left\{ \begin{bmatrix} 7 \\ 5 \\ 7 \\ 7 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 3 \\ 2 \\ -2 \\ 1 \end{bmatrix} \right\}$$

Algorithm for Finding Basis of $\text{col}(A)$

This allows us to create an algorithm for finding a basis for the span of vectors:

Algorithm for Finding Basis of $\text{col}(A)$

This allows us to create an algorithm for finding a basis for the span of vectors:

Let $W = \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ then:

Algorithm for Finding Basis of $\text{col}(A)$

This allows us to create an algorithm for finding a basis for the span of vectors:

Let $W = \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ then:

- 1 Form the matrix A whose columns are $\vec{v}_1, \dots, \vec{v}_k$

Algorithm for Finding Basis of $\text{col}(A)$

This allows us to create an algorithm for finding a basis for the span of vectors:

Let $W = \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ then:

- 1 Form the matrix A whose columns are $\vec{v}_1, \dots, \vec{v}_k$
- 2 Reduce the matrix A to row echelon form.

Algorithm for Finding Basis of $\text{col}(A)$

This allows us to create an algorithm for finding a basis for the span of vectors:

Let $W = \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ then:

- ① Form the matrix A whose columns are $\vec{v}_1, \dots, \vec{v}_k$
- ② Reduce the matrix A to row echelon form.
- ③ The columns with the leading ones will correspond to vectors in the basis.

Algorithm for Finding Basis of $\text{col}(A)$

This allows us to create an algorithm for finding a basis for the span of vectors:

Let $W = \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ then:

- ① Form the matrix A whose columns are $\vec{v}_1, \dots, \vec{v}_k$
- ② Reduce the matrix A to row echelon form.
- ③ The columns with the leading ones will correspond to vectors in the basis.
- ④ To find the other vectors as a linear combination of your basis, reduce A further to RREF.

Algorithm for Finding Basis of $\text{col}(A)$

This allows us to create an algorithm for finding a basis for the span of vectors:

Let $W = \text{span}\{\vec{v}_1, \dots, \vec{v}_k\}$ then:

- 1 Form the matrix A whose columns are $\vec{v}_1, \dots, \vec{v}_k$
- 2 Reduce the matrix A to row echelon form.
- 3 The columns with the leading ones will correspond to vectors in the basis.
- 4 To find the other vectors as a linear combination of your basis, reduce A further to RREF.

See example in the slides of last lecture.

Fundamental Matrix Spaces Bases

We now see that by reducing A to REF or RREF we can find bases for the row space, the column space and the null space.

Fundamental Matrix Spaces Bases

We now see that by reducing A to REF or RREF we can find bases for the row space, the column space and the null space. Namely:

- 1 The non-zero rows of the REF of A form a basis for $\text{row}(A)$

Fundamental Matrix Spaces Bases

We now see that by reducing A to REF or RREF we can find bases for the row space, the column space and the null space. Namely:

- 1 The non-zero rows of the REF of A form a basis for $\text{row}(A)$
- 2 The pivot columns of the REF of A correspond to a basis for $\text{col}(A)$

Fundamental Matrix Spaces Bases

We now see that by reducing A to REF or RREF we can find bases for the row space, the column space and the null space. Namely:

- 1 The non-zero rows of the REF of A form a basis for $\text{row}(A)$
- 2 The pivot columns of the REF of A correspond to a basis for $\text{col}(A)$
- 3 The canonical solutions to $A\vec{x} = \vec{0}$ can readily be seen from $R\vec{x} = 0$ where R is the RREF of A . Moreover, these form a basis for $\text{null}(A)$.

Fundamental Matrix Spaces Bases

We now see that by reducing A to REF or RREF we can find bases for the row space, the column space and the null space. Namely:

- 1 The non-zero rows of the REF of A form a basis for $\text{row}(A)$
- 2 The pivot columns of the REF of A correspond to a basis for $\text{col}(A)$
- 3 The canonical solutions to $A\vec{x} = \vec{0}$ can readily be seen from $R\vec{x} = 0$ where R is the RREF of A . Moreover, these form a basis for $\text{null}(A)$.

The last remaining fundamental space of a matrix is $\text{null}(A^T)$. This can also be determined by finding the REF.

Algorithm for Basis of $\text{null}(A^T)$

If A is an $m \times n$ matrix, then the following procedure produces a basis for $\text{null}(A^T)$.

Algorithm for Basis of $\text{null}(A^T)$

If A is an $m \times n$ matrix, then the following procedure produces a basis for $\text{null}(A^T)$.

- 1 Adjoin the $m \times m$ identity matrix I_m to A to create the augmented matrix $(A|I_m)$

Algorithm for Basis of $\text{null}(A^T)$

If A is an $m \times n$ matrix, then the following procedure produces a basis for $\text{null}(A^T)$.

- 1 Adjoin the $m \times m$ identity matrix I_m to A to create the augmented matrix $(A|I_m)$
- 2 Row reduce $(A|I_m)$ to $(U|E)$ where U is the REF of A

Algorithm for Basis of $\text{null}(A^T)$

If A is an $m \times n$ matrix, then the following procedure produces a basis for $\text{null}(A^T)$.

- 1 Adjoin the $m \times m$ identity matrix I_m to A to create the augmented matrix $(A|I_m)$
- 2 Row reduce $(A|I_m)$ to $(U|E)$ where U is the REF of A
- 3 We know that U may have some rows of zeroes. So repartition $(U|E)$ into $\left(\begin{array}{c|c} V & E_1 \\ 0 & E_2 \end{array} \right)$

Algorithm for Basis of $\text{null}(A^T)$

If A is an $m \times n$ matrix, then the following procedure produces a basis for $\text{null}(A^T)$.

- 1 Adjoin the $m \times m$ identity matrix I_m to A to create the augmented matrix $(A|I_m)$
- 2 Row reduce $(A|I_m)$ to $(U|E)$ where U is the REF of A
- 3 We know that U may have some rows of zeroes. So repartition $(U|E)$ into $\left(\begin{array}{c|c} V & E_1 \\ 0 & E_2 \end{array} \right)$
- 4 The row vectors of E_2 now form a basis for $\text{null}(A^T)$.

Example

Find $\text{null}(A^T)$ for

$$A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 \\ 2 & -6 & 9 & -1 & 8 & 2 \\ 2 & -6 & 9 & -1 & 9 & 7 \\ -1 & 3 & 4 & 2 & -5 & -4 \end{bmatrix}$$

Example

Find $\text{null}(A^T)$ for

$$A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 \\ 2 & -6 & 9 & -1 & 8 & 2 \\ 2 & -6 & 9 & -1 & 9 & 7 \\ -1 & 3 & 4 & 2 & -5 & -4 \end{bmatrix}$$

Step 1: Adjoin I_4 to A :

$$(A|I_4)$$

Example

Find $\text{null}(A^T)$ for

$$A = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 \\ 2 & -6 & 9 & -1 & 8 & 2 \\ 2 & -6 & 9 & -1 & 9 & 7 \\ -1 & 3 & 4 & 2 & -5 & -4 \end{bmatrix}$$

Step 1: Adjoin I_4 to A :

$$(A|I_4) = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 & 1 & 0 & 0 & 0 \\ 2 & -6 & 9 & -1 & 8 & 2 & 0 & 1 & 0 & 0 \\ 2 & -6 & 9 & -1 & 9 & 7 & 0 & 0 & 1 & 0 \\ -1 & 3 & 4 & 2 & -5 & -4 & 0 & 0 & 0 & 1 \end{bmatrix}$$

Example Continued

Step 2: Row reduce A to REF

$$(U|E) = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 3 & -2 & 6 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 5 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

Example Continued

Step 2: Row reduce A to REF

$$(U|E) = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 3 & -2 & 6 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 5 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

Step 3: Repartition it into

$$\left(\begin{array}{c} V \\ 0 \end{array} \middle| \begin{array}{c} E_1 \\ E_2 \end{array} \right) = \begin{bmatrix} 1 & -3 & 4 & -2 & 5 & 4 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 3 & -2 & 6 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 5 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

Example Continued

Step 2: Row reduce A to REF

$$(U|E) = \left[\begin{array}{cccccccccc} 1 & -3 & 4 & -2 & 5 & 4 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 3 & -2 & 6 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 5 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right]$$

Step 3: Repartition it into

$$\left(\begin{array}{c} V \\ 0 \end{array} \middle| \begin{array}{c} E_1 \\ E_2 \end{array} \right) = \left[\begin{array}{cccccccccc} 1 & -3 & 4 & -2 & 5 & 4 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 3 & -2 & 6 & -2 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 5 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 1 \end{array} \right]$$

Hence, we see that $\{(1, 0, 0, 1)\}$ is a basis for $\text{null}(A^T)$.