# SF 1684 Algebra and Geometry Lecture 5

Patrick Meisner

KTH Royal Institute of Technology

## Topics for Today

- Matrices as Vector Space: Addition and Scalar Multiplication
- Multiplying Matrices by Vectors
- Multiplying Two Matrices

### Row and Column Vectors

Recall we say that

$$\begin{array}{cccc} & & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & & \\ & & \\ & & & \\ & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & & \\ & &$$

is an  $m \times n$  matrix.

### Row and Column Vectors

Recall we say that

$$A = \begin{pmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & \cdots & a_{m,n} \end{pmatrix} - \mathcal{A} \quad \mathcal{A} \quad$$

is an  $m \times n$  matrix.

We will denote

$$\vec{r_i} := \begin{pmatrix} a_{i,1} & a_{i,2} & \dots & a_{i,n} \end{pmatrix}$$

as the *i*-th row vector of A and consider it as a " $1 \times n \text{ matrix}$ ".

### Row and Column Vectors

Recall we say that

$$A = \begin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & \dots & a_{m,n} \end{pmatrix}$$

$$\downarrow^{St} \ \ \downarrow \ \ \downarrow^{M} \ \$$

is an  $m \times n$  matrix.

We will denote

$$\vec{r_i} := \begin{pmatrix} a_{i,1} & a_{i,2} & \dots & a_{i,n} \end{pmatrix}$$

as the *i*-th row vector of A and consider it as a " $1 \times n$  matrix". Further, we will denote

$$ec{c_j} := egin{pmatrix} a_{1,j} \ a_{2,j} \ dots \ a_{m,j} \end{pmatrix}$$

as the *j*-th column vector of A and consider it as a " $m \times 1$  matrix".

We can then created three differing shorthand notations for the matrix A:

$$A = (a_{i,j})_{\substack{i=1,\dots,m\\j=1,\dots,n}}$$

We can then created three differing shorthand notations for the matrix A:

$$A = (a_{i,j})_{\substack{i=1,\dots,m\\j=1,\dots,n}} = \begin{pmatrix} \vec{r_1}\\ \vec{r_2}\\ \vdots\\ \vec{r_m} \end{pmatrix}$$

We can then created three differing shorthand notations for the matrix A:

$$A = (a_{i,j})_{\substack{i=1,\ldots,m\\j=1,\ldots,n}} = \begin{pmatrix} \vec{r}_1\\ \vec{r}_2\\ \vdots\\ \vec{r}_m \end{pmatrix} = \begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \ldots & \vec{c}_n \end{pmatrix}$$

We can then created three differing shorthand notations for the matrix A:

$$A = (a_{i,j})_{\substack{i=1,\ldots,m\\j=1,\ldots,n}} = \begin{pmatrix} \vec{r}_1\\\vec{r}_2\\\vdots\\\vec{r}_m \end{pmatrix} = \begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \ldots & \vec{c}_n \end{pmatrix}$$

To save space, and if it can be inferred from context, we will write just

$$(a_{i,j})_{i,j}$$
 or  $(a_{i,j})$  instead of  $(a_{i,j})_{\substack{i=1,\ldots,m\\j=1,\ldots,n}}$ 

Patrick Meisner (KTH) Lecture 5 4/28

## Matrices as Vector Spaces

### Theorem

The set of  $m \times n$  matrices form a vector space

## Matrices as Vector Spaces

#### Theorem

The set of  $m \times n$  matrices form a vector space with

• The zero matrix being

$$\begin{array}{ccccc}
 & \begin{pmatrix} 0 & 0 & \dots & 0 \\
\vdots & \vdots & \ddots & \vdots \\
0 & 0 & \dots & 0 \end{pmatrix}
\end{array}$$

2 Addition being done "coordinate-wise" Co Mponent -wise

$$(a_{i,j})_{i,j} + (b_{i,j})_{i,j} = (a_{i,j} + b_{i,j})_{i,j}$$

③ Scalar multiplication also being done "coordinate-wise" < → P Such ~ i@

$$c(a_{i,j})_{i,j}=(ca_{i,j})_{i,j}$$

$$A = \begin{pmatrix} 1 & 3 & 7 \\ 2 & 5 & 11 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 3 & 7 \\ 2 & 5 & 11 \end{pmatrix} \qquad B = \begin{pmatrix} 5 & -2 & 0 \\ -9 & 2 & 2 \end{pmatrix}$$

$$A = \begin{pmatrix} \frac{1}{2} & \frac{3}{5} & \frac{7}{11} \end{pmatrix} \qquad B = \begin{pmatrix} \frac{5}{2} & -\frac{2}{2} & \frac{0}{2} \end{pmatrix}$$

$$A + B = \begin{pmatrix} \frac{6}{2} & \frac{1}{7} & \frac{7}{13} \end{pmatrix}$$

$$A = \begin{pmatrix} \frac{1}{2} & \frac{3}{5} & \frac{7}{11} \end{pmatrix} \qquad B = \begin{pmatrix} 5 & -2 & 0 \\ -9 & 2 & 2 \end{pmatrix}$$
$$A + B = \begin{pmatrix} 6 & 1 & 7 \\ -7 & 7 & 13 \end{pmatrix} \qquad 2A = \begin{pmatrix} \frac{2}{4} & \frac{6}{10} & \frac{14}{22} \end{pmatrix}$$

$$A = \begin{pmatrix} \frac{1}{2} & \frac{3}{5} & \frac{7}{11} \end{pmatrix} \qquad B = \begin{pmatrix} \frac{5}{-9} & \frac{-2}{2} & \frac{0}{2} \end{pmatrix}$$

$$A + B = \begin{pmatrix} 6 & 1 & 7 \\ -7 & 7 & 13 \end{pmatrix} \qquad 2A = \begin{pmatrix} 2 & 6 & 14 \\ 4 & 10 & 22 \end{pmatrix}$$

$$A - 2B = \begin{pmatrix} \frac{-9}{20} & \frac{7}{1} & \frac{7}{1} \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & 3 & 7 \\ 2 & 5 & 11 \end{pmatrix} \qquad B = \begin{pmatrix} 5 & -2 & 0 \\ -9 & 2 & 2 \end{pmatrix}$$

$$A + B = \begin{pmatrix} 6 & 1 & 7 \\ -7 & 7 & 13 \end{pmatrix} \qquad 2A = \begin{pmatrix} 2 & 6 & 14 \\ 4 & 10 & 22 \end{pmatrix}$$

$$A - 2B = \begin{pmatrix} -9 & 7 & 7 \\ 20 & 1 & 7 \end{pmatrix} \qquad \frac{1}{2}B = \begin{pmatrix} 2.5 & -1 & 0 \\ -4.5 & 1 & 1 \end{pmatrix} \quad \text{for the first points}$$

$$A = \begin{pmatrix} 1 & 3 & 7 \\ 2 & 5 & 11 \end{pmatrix} \qquad B = \begin{pmatrix} 5 & -2 & 0 \\ -9 & 2 & 2 \end{pmatrix}$$

$$A + B = \begin{pmatrix} 6 & 1 & 7 \\ -7 & 7 & 13 \end{pmatrix} \qquad 2A = \begin{pmatrix} 2 & 6 & 14 \\ 4 & 10 & 22 \end{pmatrix}$$

$$A - 2B = \begin{pmatrix} -9 & 7 & 7 \\ 20 & 1 & 7 \end{pmatrix} \qquad \frac{1}{2}B = \begin{pmatrix} 2.5 & -1 & 0 \\ -4.5 & 1 & 1 \end{pmatrix}$$

CAUTION!!!!!!

$$A = \begin{pmatrix} 3 & 7 \\ 2 & 5 & 11 \end{pmatrix} \qquad B = \begin{pmatrix} 5 & -2 & 0 \\ -9 & 2 & 2 \end{pmatrix}$$

$$A + B = \begin{pmatrix} 6 & 1 & 7 \\ -7 & 7 & 13 \end{pmatrix} \qquad 2A = \begin{pmatrix} 2 & 6 & 14 \\ 4 & 10 & 22 \end{pmatrix}$$

$$A - 2B = \begin{pmatrix} -9 & 7 & 7 \\ 20 & 1 & 7 \end{pmatrix} \qquad \frac{1}{2}B = \begin{pmatrix} 2.5 & -1 & 0 \\ -4.5 & 1 & 1 \end{pmatrix}$$

#### CAUTION!!!!!!

You can only add matrices of the same dimension!

$$A = \begin{pmatrix} 1 & 3 & 7 \\ 2 & 5 & 11 \end{pmatrix} \qquad B = \begin{pmatrix} 5 & -2 & 0 \\ -9 & 2 & 2 \end{pmatrix}$$

$$A + B = \begin{pmatrix} 6 & 1 & 7 \\ -7 & 7 & 13 \end{pmatrix} \qquad 2A = \begin{pmatrix} 2 & 6 & 14 \\ 4 & 10 & 22 \end{pmatrix}$$

$$A - 2B = \begin{pmatrix} -9 & 7 & 7 \\ 20 & 1 & 7 \end{pmatrix} \qquad \frac{1}{2}B = \begin{pmatrix} 2.5 & -1 & 0 \\ -4.5 & 1 & 1 \end{pmatrix}$$

#### CAUTION!!!!!!

You can only add matrices of the same dimension! That is, if

$$C = \begin{pmatrix} 1 & 3 & 3 \\ 2 & 5 & -2 \\ 7 & 11 & 21 \end{pmatrix}$$

then it does not even make sense to consider things like A + C or 2C + 5B!

Patrick Meisner (KTH) Lecture 5 6/28

## Multiplication of Matrices

We have defined addition of matrices "coordinate-wise", so it is tempting to define multiplication of matrices the same way.

## Multiplication of Matrices

We have defined addition of matrices "coordinate-wise", so it is tempting to define multiplication of matrices the same way. That is, if A and B are  $m \times n$  matrices, then it is tempting to define

$$A * B = (a_{i,j})_{i,j} * (b_{i,j})_{i,j} = (a_{i,j}b_{i,j})_{i,j}$$

## Multiplication of Matrices

We have defined addition of matrices "coordinate-wise", so it is tempting to define multiplication of matrices the same way. That is, if A and B are  $m \times n$  matrices, then it is tempting to define

$$A * B = (a_{i,j})_{i,j} * (b_{i,j})_{i,j} = (a_{i,j}b_{i,j})_{i,j}$$

However, we must remember that we are interested in matrices in relation to solving systems of linear equations.

As it turns out defining the multiplication of matrices in this way does not help us understand this.

A  $1\times 1$  matrix would be something of the form

$$A = (a), a \in \mathbb{R}$$

A  $1 \times 1$  matrix would be something of the form

$$A = (a), a \in \mathbb{R}$$

That is, a  $1 \times 1$  matrix is, essentially, just an element of  $\mathbb{R}$ , a scalar.

Patrick Meisner (KTH) Lecture 5 8/28

A  $1 \times 1$  matrix would be something of the form

$$A = (a), a \in \mathbb{R}$$

That is, a  $1 \times 1$  matrix is, essentially, just an element of  $\mathbb{R}$ , a scalar.

Therefore, there is no real way to multiply them except for the naive way.

That is, if A = (a) and X = (x) it must be that

$$A * X = (ax)$$

However, since X=(x) is essentially just an element of  $\mathbb{R}=\mathbb{R}^1$ , we can view it as vector:  $X=\vec{x}=[x]$ .

However, since X=(x) is essentially just an element of  $\mathbb{R}=\mathbb{R}^1$ , we can view it as vector:  $X=\vec{x}=[x]$ .

Thus we can define how to multiply a  $1 \times 1$  matrix  $\underline{A} = (\underline{a})$  with a vector in  $\mathbb{R}^1$ ,  $\vec{x} = [x]$ :

$$A * \vec{x} = \begin{bmatrix} \underline{ax} \end{bmatrix} = (\alpha x)$$

However, since X=(x) is essentially just an element of  $\mathbb{R}=\mathbb{R}^1$ , we can view it as vector:  $X=\vec{x}=[x]$ .

Thus we can define how to multiply a  $1 \times 1$  matrix  $\underline{A = (a)}$  with a vector in  $\mathbb{R}^1$ ,  $\vec{x} = [x]$ :

$$A * \vec{x} = [ax]$$

We want to relate this back to solving linear equations.

$$(Alb) \rightarrow \bar{\alpha} \bar{x} = b$$

$$A*\bar{x}$$

$$(Alb) \rightarrow A*\bar{x} = \bar{b}$$

However, since X=(x) is essentially just an element of  $\mathbb{R}=\mathbb{R}^1$ , we can view it as vector:  $X=\vec{x}=[x]$ .

Thus we can define how to multiply a  $1 \times 1$  matrix A = (a) with a vector in  $\mathbb{R}^1$ ,  $\vec{x} = [x]$ :

$$A * \vec{x} = [ax]$$

We want to relate this back to solving linear equations. So if  $\vec{b} = [b]$ , is a vector in  $\mathbb{R}^1$ , then we see that  $\vec{x} = [x]$  solves to the  $1 \times 2$  augmented matrix  $(A|\vec{b}) = (a|b)$  if and only if ax = b.

However, since X=(x) is essentially just an element of  $\mathbb{R}=\mathbb{R}^1$ , we can view it as vector:  $X=\vec{x}=[x]$ .

Thus we can define how to multiply a  $1 \times 1$  matrix A = (a) with a vector in  $\mathbb{R}^1$ ,  $\vec{x} = [x]$ :

$$A * \vec{x} = [ax]$$

We want to relate this back to solving linear equations. So if  $\vec{b} = [b]$ , is a vector in  $\mathbb{R}^1$ , then we see that  $\vec{x} = [x]$  solves to the  $1 \times 2$  augmented matrix  $(A|\vec{b}) = (a|b)$  if and only if ax = b.

### Conclusion

If A is a  $1 \times 1$  matrix and  $\vec{b}$  is a vector in  $\mathbb{R}^1$ , then a vector  $\vec{x}$  in  $\mathbb{R}^1$  solves the augmented matrix  $(A|\vec{b})$  if and only

$$A * \vec{x} = \vec{b}$$

We want to generalize this conclusion to any matrix.

We want to generalize this conclusion to any matrix.

#### Want

For any matrix A and any vector  $\vec{x}$ , we want to define  $A * \vec{x}$  such that  $\vec{x}$  solves the augmented matrix  $(A|\vec{b})$  if and only if  $A * \vec{x} = \vec{b}$ .

We want to generalize this conclusion to any matrix.

#### Want

For any matrix A and any vector  $\vec{x}$ , we want to define  $A * \vec{x}$  such that  $\vec{x}$  solves the augmented matrix  $(A|\vec{b})$  if and only if  $A * \vec{x} = \vec{b}$ .

CAUTION!!!!!!

We want to generalize this conclusion to any matrix.

#### Want

For any matrix A and any vector  $\vec{x}$ , we want to define  $A * \vec{x}$  such that  $\vec{x}$ solves the augmented matrix  $(A|\vec{b})$  if and only if  $A*\vec{x}=\vec{b}$ .

If A is an  $m \times n$  matrix then it corresponds to a system of linear equations in *n* variables.

Lecture 5 10 / 28

We want to generalize this conclusion to any matrix.

#### Want

For any matrix A and any vector  $\vec{x}$ , we want to define  $A * \vec{x}$  such that  $\vec{x}$  solves the augmented matrix  $(A|\vec{b})$  if and only if  $A * \vec{x} = \vec{b}$ .

#### CAUTION!!!!!!

If A is an  $m \times n$  matrix then it corresponds to a system of linear equations in n variables. Thus, in order for  $\vec{x}$  to solve the augmented matrix  $(A|\vec{b})$ ,  $\vec{x}$  must be in  $\mathbb{R}^{n}$ ?

We want to generalize this conclusion to any matrix.

## Want

For any matrix A and any vector  $\vec{x}$ , we want to define  $A*\vec{x}$  such that  $\vec{x}$  solves the augmented matrix  $(A|\vec{b})$  if and only if  $A*\vec{z} = \vec{b}$ .

#### CAUTION!!!!!!

If A is an  $m \times \widehat{m}$  matrix then it corresponds to a system of linear equations in n variables. Thus, in order for  $\vec{x}$  to solve the augmented matrix  $(A|\vec{b})$ ,  $\vec{x}$  must be in  $\mathbb{R}^{\widehat{n}}$ !

So, we would NOT be able to define the multiplication of a  $3 \times 2$  matrix by a vector in  $\mathbb{R}^5$  in this way.

Patrick Meisner (KTH) Lecture 5 10 / 28

So, given an augmented matrix

$$(A|\vec{b}) := egin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,n} & b_1 \ a_{2,1} & a_{2,2} & \dots & a_{2,n} & b_2 \ dots & dots & \ddots & dots & dots \ a_{m,1} & a_{m,2} & \dots & a_{m,n} & b_m \end{pmatrix}$$

So, given an augmented matrix

$$(A|\vec{b}) := egin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,n} & b_1 \ a_{2,1} & a_{2,2} & \dots & a_{2,n} & b_2 \ dots & dots & \ddots & dots & dots \ a_{m,1} & a_{m,2} & \dots & a_{m,n} & b_m \end{pmatrix}$$

we recall that a vector 
$$\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$
 in  $\mathbb{R}^n$  solves the augmented matrix if

Patrick Meisner (KTH) Lecture 5 11/28

So, given an augmented matrix

$$(A|\vec{b}) := egin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,n} & b_1 \ a_{2,1} & a_{2,2} & \dots & a_{2,n} & b_2 \ dots & dots & \ddots & dots & dots \ a_{m,1} & a_{m,2} & \dots & a_{m,n} & b_m \end{pmatrix}$$

we recall that a vector  $\vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$  in  $\mathbb{R}^n$  solves the augmented matrix if 

Patrick Meisner (KTH) Lecture 5 11 / 28

# Multiplying Matrices by Vectors Definition

## **Definition**

Given an  $m \times (n)$  matrix and a vector in  $\mathbb{R}^{(n)}$ 

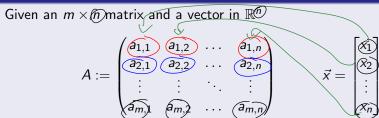
$$A := \begin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1}_{\widehat{\mathcal{D}}} \\ a_{2,1} & a_{2,2} & \dots & a_{2}_{\widehat{\mathcal{D}}} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & \dots & a_{m,n} \end{pmatrix} \qquad \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{\widehat{\mathcal{D}}} \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

we **define**  $A * \vec{x}$  to be

# Multiplying Matrices by Vectors Definition

## **Definition**



we **define**  $A * \vec{x}$  to be

$$A * \vec{x} = \begin{bmatrix} a_{1,1}x_1 + a_{1,2}x_2 + \dots + a_{1,n}x_n \\ a_{2,1}x_1 + a_{2,2}x_2 + \dots + a_{2,n}x_n \\ \vdots \\ a_{m,1}x_1 + a_{m,2}x_2 + \dots + a_{m,n}x_n \end{bmatrix}$$

# Multiplying Matrices by Vectors Theorem

## Theorem

Given an  $m \times n$  matrix A and a vector  $\vec{b}$  in  $\mathbb{R}^m$ , then a vector  $\vec{x}$  in  $\mathbb{R}^n$  solves the augmented matrix (A|b) if and only if

$$A * \vec{x} = \vec{b}$$

## Proof.

# Multiplying Matrices by Vectors Theorem

## Theorem

Given an  $m \times n$  matrix A and a vector  $\vec{b}$  in  $\mathbb{R}^m$ , then a vector  $\vec{x}$  in  $\mathbb{R}^n$  solves the augmented matrix (A|b) if and only if

$$A * \vec{x} = \vec{b}$$

## Proof.

By construction.



# Multiplying Matrices by Vectors Theorem

## Theorem

Given an  $m \times n$  matrix A and a vector  $\vec{b}$  in  $\mathbb{R}^m$ , then a vector  $\vec{x}$  in  $\mathbb{R}^n$  solves the augmented matrix (A|b) if and only if

$$A * \vec{x} = \vec{b}$$

## Proof.

By construction.



Notation: from now on we will just write  $\overrightarrow{Ax}$  instead of  $\overrightarrow{Ax}$  to indicate the multiplication of a matrix by a vector in this way.

## Exercise

Calculate  $A\vec{x}$  in the following and interpret the result in terms of a solution to a system of linear equations

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, \vec{x} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

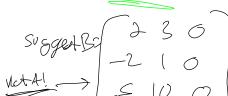
$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}, \vec{x} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$



# Extra Work Space

$$2) A= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \hat{x} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -1 \times 1 + 0 \times 0 + 1 \times 1 \\ -1 \times 0 + 0 \times 1 + 0 \times 1 \end{bmatrix} = \begin{bmatrix} 0 & 6 \\ 0 & 1 \end{bmatrix}$$





- **1** If A is an  $m \times n$  matrix then  $A\vec{x}$  only makes sense if  $\vec{x}$  is in  $\mathbb{R}^n$ .
- ② If A is an  $(n) \times (n)$  matrix and  $\vec{x}$  is in  $\mathbb{R}^{(n)}$  then  $A\vec{x}$  is a vector in  $\mathbb{R}^{(n)}$



- **1** If A is an  $m \times n$  matrix then  $A\vec{x}$  only makes sense if  $\vec{x}$  is in  $\mathbb{R}^n$ .
- ② If A is an  $m \times n$  matrix and  $\vec{x}$  is in  $\mathbb{R}^n$  then  $A\vec{x}$  is a vector in  $\mathbb{R}^m$ .

① We may have  $A\vec{x} = \vec{0}$  even if  $\vec{A}$  is not the zero matrix and  $\vec{x} \neq \vec{0}$ .

Patrick Meisner (KTH) Lecture 5 16/28

- **1** If A is an  $m \times n$  matrix then  $A\vec{x}$  only makes sense if  $\vec{x}$  is in  $\mathbb{R}^n$ .
- ② If A is an  $m \times n$  matrix and  $\vec{x}$  is in  $\mathbb{R}^n$  then  $A\vec{x}$  is a vector in  $\mathbb{R}^m$ .

**③** We may have  $A\vec{x} = \vec{0}$  even if A is not the zero matrix and  $\vec{x} \neq \vec{0}$ .

## Theorem

 $\vec{x}$  is a homogeneous solution to A if and only if  $A\vec{x} = \vec{0}$ .

$$\vec{x}$$
 is home if it colver (Alõkas  $A\vec{x} = \vec{o}$ 

# Multiplying Matrices by Vectors: Row Vectors Dot Product

#### Theorem

Recall that if  $A = (a_{i,j})$  is an  $m \times n$  matrix then the row vectors,  $\vec{r_i} = (a_{i,1} \ a_{i,2} \ \dots \ a_{i,n})$ , are vectors in  $\mathbb{R}^n$ .

#### Theorem

Recall that if  $A = (a_{i,j})$  is an  $m \times n$  matrix then the row vectors,  $\vec{r_i} = (a_{i,1} \ a_{i,2} \ \dots \ a_{i,n})$ , are vectors in  $\mathbb{R}^n$ . Then for any vectors  $\vec{x}$  in  $\mathbb{R}^n$ , we get

$$A\vec{x} = \begin{bmatrix} \vec{r}_1 \cdot \vec{x} \\ \vec{r}_2 \cdot \vec{x} \\ \vdots \\ \vec{r}_m \cdot \vec{x} \end{bmatrix}$$

$$A_{x}^{2} = \begin{pmatrix} q_{11} & q_{12} & --- & q_{1n} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \vdots \\ \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{11} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \ddots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \ddots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \ddots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \ddots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \ddots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \ddots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \ddots & \ddots & \chi_{n} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \chi_{n} & --+ & q_{2n} & \chi_{1} \end{pmatrix} = \begin{pmatrix} q_{11} & \chi_{1} + q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \\ \vdots & \chi_{n} & --+ & q_{2n} & \chi_{1} & --+ & q_{2n} & \chi_{1} \end{pmatrix}$$

# Linearity Properties

## Theorem (Linearity Properties)

If A is an  $m \times n$  matrix,  $\vec{x}$  and  $\vec{y}$  vectors in  $\mathbb{R}^n$  and c a scalar then

# Homogeneous Solutions are a Vector Space: Reproof

#### Theorem

Given a matrix A, the set of homogeneous solutions of A form a vector space. Equivalently, the following holds

- $\mathbf{0}$   $\vec{0}$  is a homogeneous solution
- ② If  $\vec{x}$  is a homogeneous solution and  $c \in \mathbb{R}$  then  $c\vec{x}$  is also a homogeneous solution
- **3** If  $\vec{x}$  and  $\vec{y}$  are homogeneous solutions than so is  $\vec{x} + \vec{y}$

$$0 \stackrel{?}{\wedge} \overline{0} = \begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix} \stackrel{?}{\wedge} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Suppose A is an  $m \times n$  matrix and B is a  $n \times \ell$  matrix.

Suppose A is an  $m \times n$  matrix and B is a  $n \times \ell$  matrix. We can write

$$B = (\vec{c}_1 \quad \vec{c}_2 \quad \dots \quad \vec{c}_\ell)$$

where the  $\vec{c_i}$  are the column vectors of B and so are vectors in  $\mathbb{R}^n$ .

Patrick Meisner (KTH) Lecture 5 20 / 28

Suppose A is an  $m \times \widehat{\mathfrak{D}}$  matrix and B is a  $\widehat{\mathfrak{D}} \times \ell$  matrix. We can write

$$B = \begin{pmatrix} \vec{c_1} & \vec{c_2} & \dots & \vec{c_\ell} \end{pmatrix}$$

where the  $\vec{c_i}$  are the column vectors of B and so are vectors in  $\mathbb{R}^{\mathbb{O}}$  Hence, we know how to multiply each  $\vec{c_i}$  by A.

Patrick Meisner (KTH) Lecture 5 20 / 28

Suppose A is an  $m \times n$  matrix and B is a  $n \times \ell$  matrix. We can write

$$B = \begin{pmatrix} \vec{c_1} & \vec{c_2} & \dots & \vec{c_\ell} \end{pmatrix}$$

where the  $\vec{c_i}$  are the column vectors of B and so are vectors in  $\mathbb{R}^n$ . Hence, we know how to multiply each  $\vec{c_i}$  by A. We now can think of multiplying B by A by distributing it:

## Definition

Let A be an  $m \times m$  matrix and B be a  $m \times \ell$  matrix with column vectors  $\vec{c}_1, \vec{c}_2, \ldots, \vec{c}_\ell$ , then we define

$$AB = A(\vec{c_1} \quad \vec{c_2} \quad \dots \quad \vec{c_\ell}) = (A\vec{c_1} \quad A\vec{c_2} \quad \dots \quad A\vec{c_\ell})$$

$$AB = A \begin{pmatrix} \vec{c_1} & \vec{c_2} & \dots & \vec{c_\ell} \end{pmatrix} = \begin{pmatrix} A\vec{c_1} & A\vec{c_2} & \dots & A\vec{c_\ell} \end{pmatrix}$$

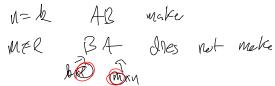
$$AB = A \begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \dots & \vec{c}_\ell \end{pmatrix} = \begin{pmatrix} A\vec{c}_1 & A\vec{c}_2 & \dots & A\vec{c}_\ell \end{pmatrix}$$

• If A is a  $m \times_{m}$  matrix and B is a  $k \times_{m} \ell$  matrix then the  $\vec{c_i}$  are in  $\mathbb{R}^k$  and hence AB only makes sense if n = k (i.e. the number of columns of A must be equal to the number of rows of B).

Patrick Meisner (KTH) Lecture 5 21 / 28

$$AB = A \begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \dots & \vec{c}_\ell \end{pmatrix} = \begin{pmatrix} A\vec{c}_1 & A\vec{c}_2 & \dots & A\vec{c}_\ell \end{pmatrix}$$

- If A is a  $m \times n$  matrix and B is a  $k \times \ell$  matrix then the  $\vec{c_i}$  are in  $\mathbb{R}^k$  and hence AB only makes sense if n = k (i.e. the number of columns of A must be equal to the number of rows of B).
- 2 It is very possible that AB makes sense while BA does not even make sense!



$$AB = A \begin{pmatrix} \vec{c_1} & \vec{c_2} & \dots & \vec{c_\ell} \end{pmatrix} = \begin{pmatrix} A\vec{c_1} & A\vec{c_2} & \dots & A\vec{c_\ell} \end{pmatrix}$$

- If A is a  $m \times n$  matrix and B is a  $k \times \ell$  matrix then the  $\vec{c_i}$  are in  $\mathbb{R}^k$  and hence AB only makes sense if n = k (i.e. the number of columns of A must be equal to the number of rows of B).
- ② It is very possible that AB makes sense while BA does not even make sense!
- § Since  $\vec{c_i}$  are vectors in  $\mathbb{R}^n$ , the  $A\vec{c_i}$  are vectors in  $\mathbb{R}^m$  and so AB is an  $m \times \ell$  matrix.

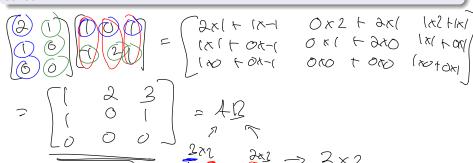


Patrick Meisner (KTH) Lecture 5 21/28

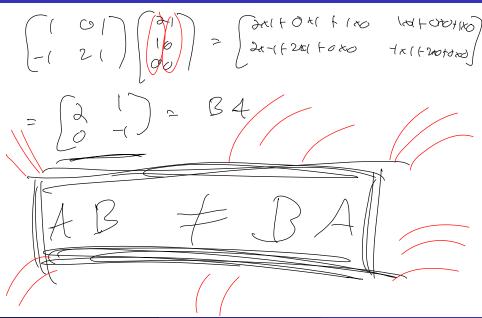
## Exercise

$$A = \begin{pmatrix} 2 & 1 \\ 1 & 0 \\ 0 & 0 \end{pmatrix} \qquad B = \begin{pmatrix} 1 & 0 & 1 \\ -1 & 2 & 1 \end{pmatrix} \qquad C = \begin{pmatrix} 2 & 1 \end{pmatrix}$$

Computer AB, AC, BA, BC, CA and CB or state that they don't make sense



# Extra Work Space



# Multiplying Matrices: Row Vector, Column Vector Dot **Product**

#### Theorem

Let A be an  $m \times n$  matrix with row vectors  $\vec{r}_1, \vec{r}_2, \dots, \vec{r}_m$  and B be an  $n \times \ell$  matrix with column vectors  $\vec{c}_1, \vec{c}_2, \dots, \vec{c}_\ell$ . Then

$$AB = \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_m \end{pmatrix} \begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \dots & \vec{c}_\ell \end{pmatrix} = (\vec{r}_i \cdot \vec{c}_j)_{i=1,\dots,m}.$$

$$\vec{c}_j = 1,\dots,\ell$$

$$\vec{$$

# Multiplying Matrices: Row Vector, Column Vector Dot Product

#### Theorem

Let A be an  $m \times n$  matrix with row vectors  $\vec{r_1}, \vec{r_2}, \ldots, \vec{r_m}$  and B be an  $n \times \ell$  matrix with column vectors  $\vec{c_1}, \vec{c_2}, \ldots, \vec{c_\ell}$ . Then

$$AB = \begin{pmatrix} \vec{r}_1 \\ \vec{r}_2 \\ \vdots \\ \vec{r}_m \end{pmatrix} \begin{pmatrix} \vec{c}_1 & \vec{c}_2 & \dots & \vec{c}_\ell \end{pmatrix} = (\vec{r}_i \cdot \vec{c}_j)_{\substack{i=1,\dots,m \\ j=1,\dots,\ell}}.$$

That is, the (i,j)-th entry of the  $m \times \ell$  matrix AB is  $\vec{r_i} \cdot \vec{c_i}$ .

## Proof.

Follows from the similar theorem about matrices multiplied by vectors and the definition of matrix multiplication.

Patrick Meisner (KTH) Lecture 5 24/28

# Diagonal Matrices

## **Definition**

We call an  $n \times n$  matrix  $D = (d_{i,j})$  diagonal if  $d_{i,j} = 0$  whenever  $i \neq j$ :

$$D = \begin{pmatrix} d_{1,1} & 0 & \dots & 0 \\ \hline 0 & d_{2,2} & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_{n,n} \end{pmatrix}$$

# Multiplying a Matrix by a Diagonal Matrix on the Right

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix}$$

and A is an  $m \times n$  matrix with entries  $a_{i,j}$ ,

# Multiplying a Matrix by a Diagonal Matrix on the Right

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix}$$
where  $d_n$  is with entries  $a_{i,i}$ , then

and A is an  $m \times n$  matrix with entries  $a_{i,j}$ , then

$$AD = \begin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,n} \\ a_{2,1} & a_{2,2} & \dots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & \dots & a_{m,n} \end{pmatrix} \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix}$$

# Multiplying a Matrix by a Diagonal Matrix on the Right

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix}$$

and A is an  $m \times n$  matrix with entries  $a_{i,j}$ , then

$$AD = \begin{pmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,n} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m,1} & a_{m,2} & \cdots & a_{m,n} \end{pmatrix} \begin{pmatrix} d_1 & 0 & \cdots & 0 \\ d_2 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & d_n \end{pmatrix}$$

$$= \begin{pmatrix} d_1 a_{1,1} & d_2 a_{1,2} & \cdots & d_n a_{1,n} \\ d_1 a_{2,1} & d_2 a_{2,2} & \cdots & d_n a_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ d_1 a_{m,1} & d_2 a_{m,2} & \cdots & d_n a_{m,n} \end{pmatrix}$$

Patrick Meisner (KTH) Lecture 5 26 / 28

# Multiplying a Matrix by a Diagonal Matrix on the Left

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_m \end{pmatrix}$$

and A is an  $n \times m$  matrix with entries  $a_{i,j}$ ,

# Multiplying a Matrix by a Diagonal Matrix on the Left

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_{\underline{m}} \end{pmatrix}$$

and A is an  $n \times m$  matrix with entries  $a_{i,j}$ , then

$$DA = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix} \begin{pmatrix} a_{1,1} & a_{1,2} & \dots & a_{1,m} \\ a_{2,1} & a_{2,2} & \dots & a_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n,1} & a_{n,2} & \dots & a_{n,m} \end{pmatrix}$$

# Multiplying a Matrix by a Diagonal Matrix on the Left

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_m \end{pmatrix}$$

and A is an  $n \times m$  matrix with entries  $a_{i,j}$ , then

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix} \quad \text{and} \quad E = \begin{pmatrix} e_1 & 0 & \dots & 0 \\ 0 & e_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e_n \end{pmatrix}$$

$$\mathsf{E} = egin{pmatrix} \mathsf{e}_1 & \mathsf{0} & \dots & \mathsf{0} \ \mathsf{0} & \mathsf{e}_2 & \dots & \mathsf{0} \ dots & dots & \ddots & dots \ \mathsf{0} & \mathsf{0} & \dots & arepsilon_1 \end{pmatrix}$$

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix} \quad \text{and} \quad E = \begin{pmatrix} e_1 & 0 & \dots & 0 \\ 0 & e_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e_n \end{pmatrix}$$

$$E = \begin{pmatrix} e_1 & 0 & \dots & 0 \\ 0 & e_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e_n \end{pmatrix}$$

then

$$DE = egin{pmatrix} d_1e_1 & 0 & \dots & 0 \ 0 & d_2e_2 & \dots & 0 \ dots & dots & \ddots & dots \ 0 & 0 & \dots & d_ne_n \end{pmatrix}$$

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix} \quad \text{and} \quad E = \begin{pmatrix} e_1 & 0 & \dots & 0 \\ 0 & e_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e_n \end{pmatrix}$$

then

$$DE = \begin{pmatrix} d_1e_1 & 0 & \dots & 0 \\ 0 & d_2e_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_ne_n \end{pmatrix} = \begin{pmatrix} e_1d_1 & 0 & \dots & 0 \\ 0 & e_2d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e_nd_n \end{pmatrix}$$

Patrick Meisner (KTH) Lecture 5 28 / 28

Let

$$D = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_n \end{pmatrix} \quad \text{and} \quad E = \begin{pmatrix} e_1 & 0 & \dots & 0 \\ 0 & e_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e_n \end{pmatrix}$$

then

$$DE = \begin{pmatrix} d_1e_1 & 0 & \dots & 0 \\ 0 & d_2e_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & d_ne_n \end{pmatrix} = \begin{pmatrix} e_1d_1 & 0 & \dots & 0 \\ 0 & e_2d_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & e_nd_n \end{pmatrix} = ED$$

but this is a very special



