

# Magnetic Resonance Imaging

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# Lärandemål 1/3

1. Vad som mäts med MR
2. Varför väte går att avbilda med MR och varför just väte är ett lämpligt ämne att avbilda
3. Vad som händer när en atomkärna med spinn placeras i ett starkt magnetfält och varför
4. Följderna av en förändring i det externa magnetfältet  $B_0$
5. Ingående delar i en MR-utrustning samt deras funktion
6. RF-pulsens roll för generering av MR-signal

# Lärandemål 2/3

7. MR-signalens uppkomst och utseende samt hur den detekteras
8. Hur kontrast skapas i MR-bilder
9. Hur parameterval i MR-utrustningen samt vävnadsegenskaper påverkar kontrasten i bilden
10. Hur MR-signalen lokaliseras i x, y – och z-led
11. Hur bildkvaliteten kan förbättras i en MR-bild
12. Vad som bestämmer temporal och spatiell upplösning i en MR-bild

# Lärandemål 3/3

- 13. Hur spin-echosekvensen fungerar samt översiktligt känna till att det finns andra pulssekvenser
- 14. Säkerhetaspekter kopplat till MR-avbildning
- 15. Den kliniska nyttan av MR-avbildning samt redogöra för vilka kliniska situationer som MR är en lämplig avbildningsmetod
- 16. Vilka artefakter som kan uppstå vid MR-avbildning och hur de uppstår
- 17. MR-teknikens styrkor och svagheter jämförelse med andra tekniker?



# Part I

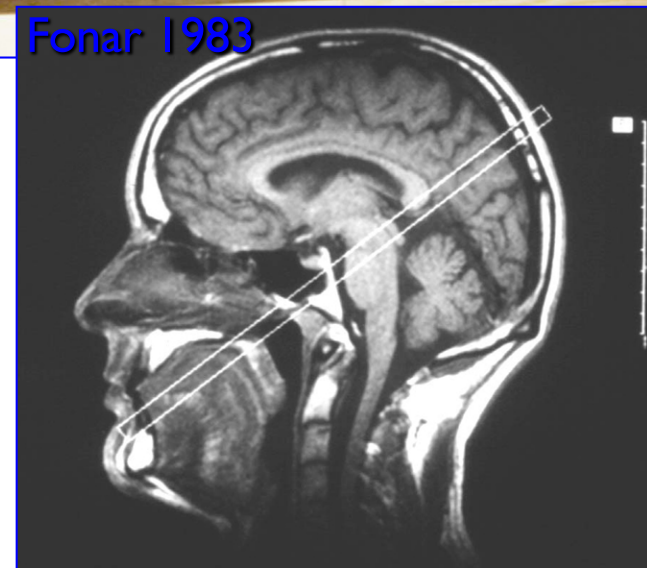
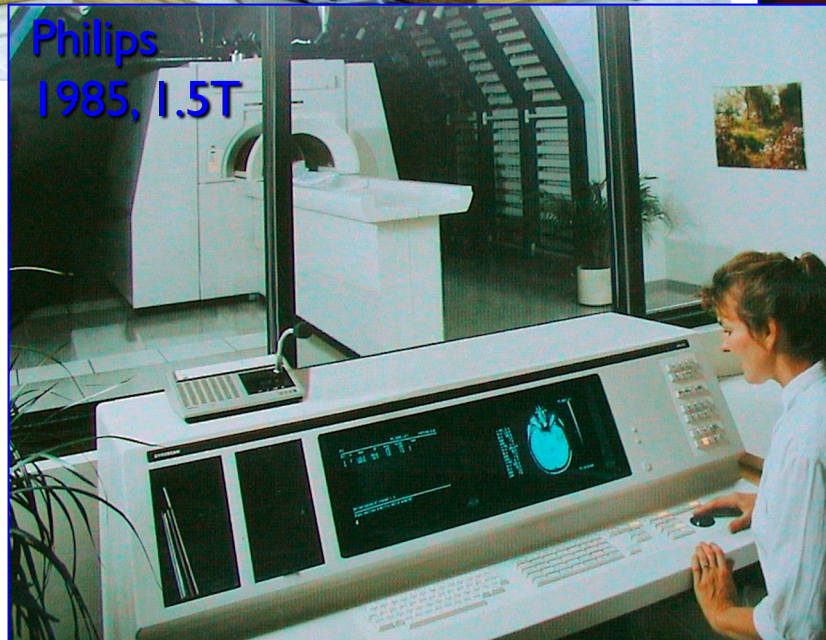
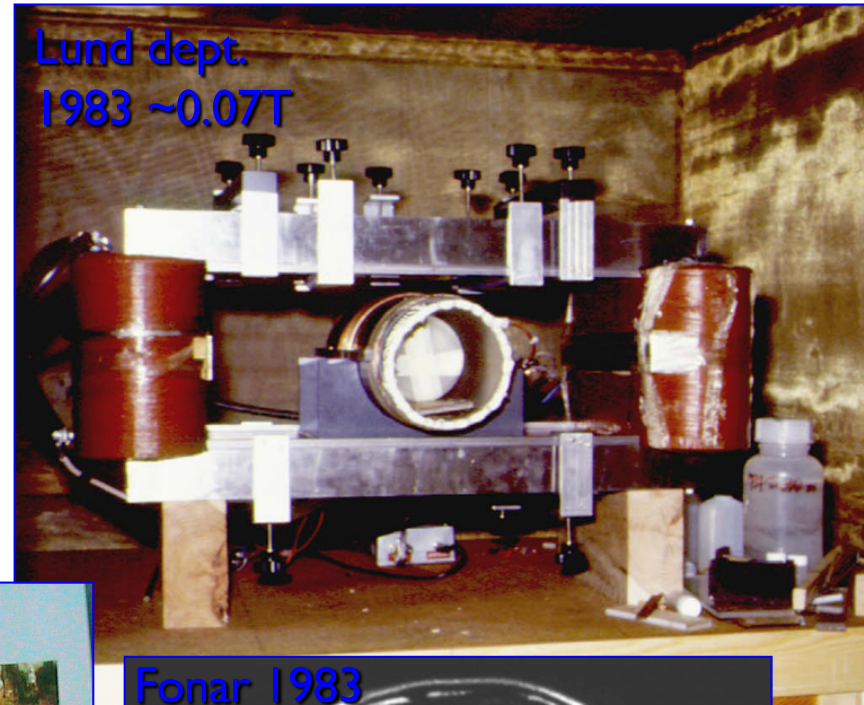
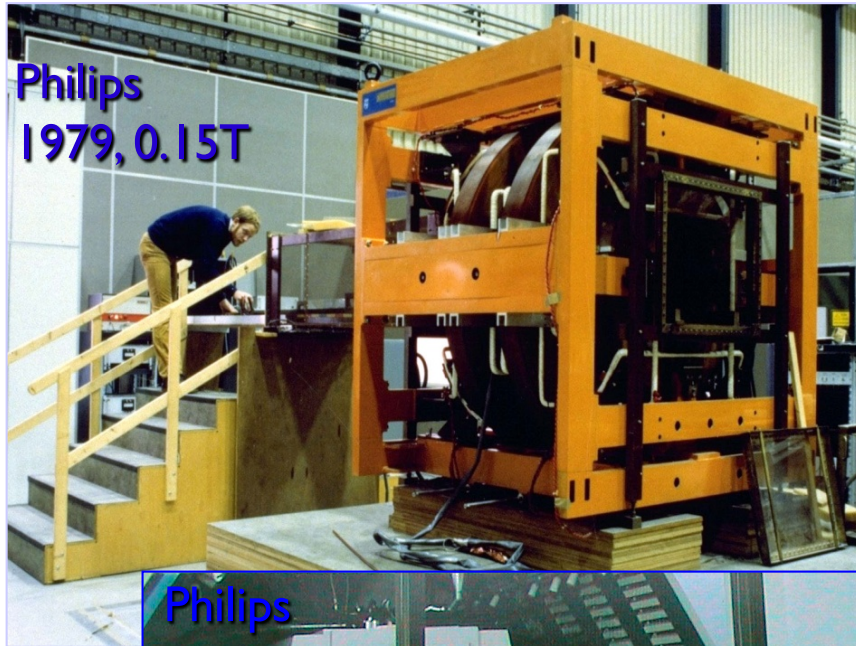
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# Introduction

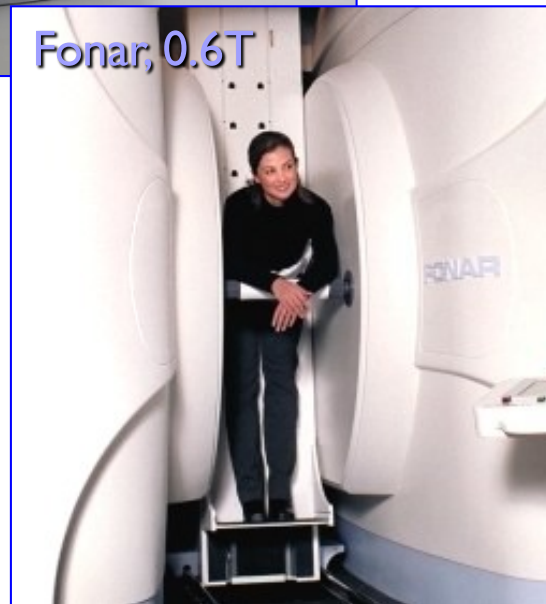
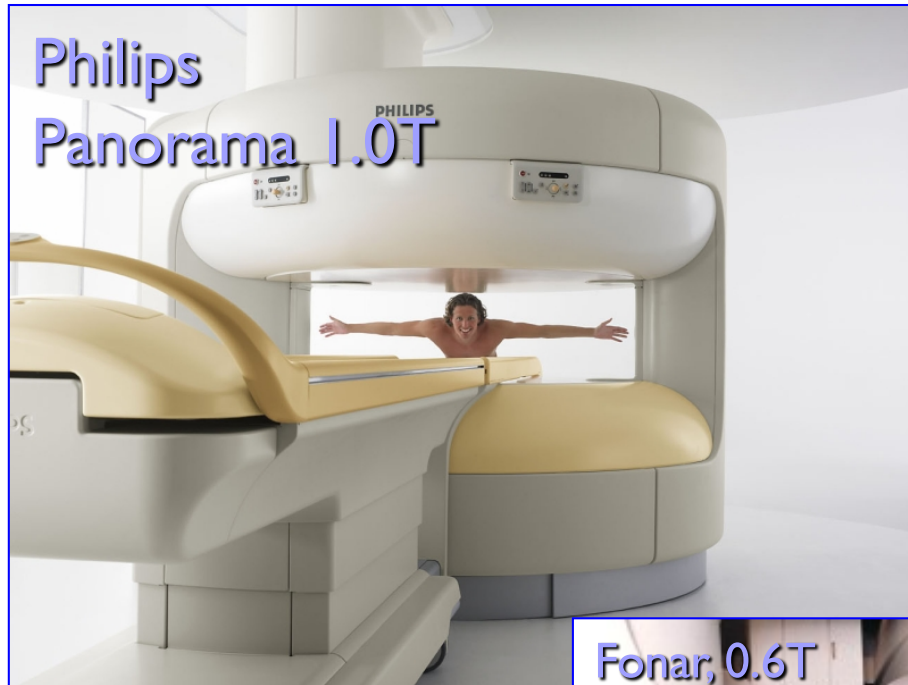
- Non-invasive
- No ionizing radiation or other known dangers
  - Scan and rescan patients for follow-up
  - Scan healthy volunteers
- Excellent soft-tissue contrast
  - Not density-based like X-ray
- Versatile
  - Measure blood flow, diffusion, cardiac motion, molecular content, metabolism
  - Many technological advances based on software

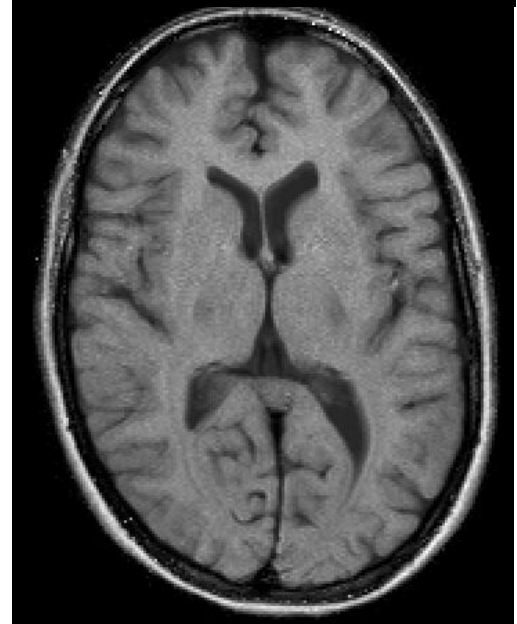
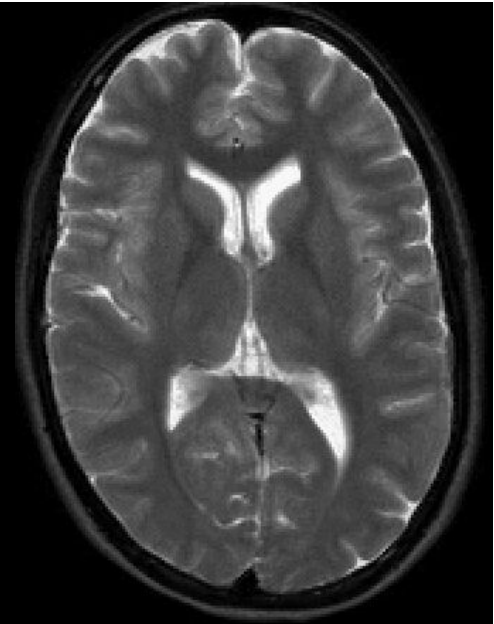
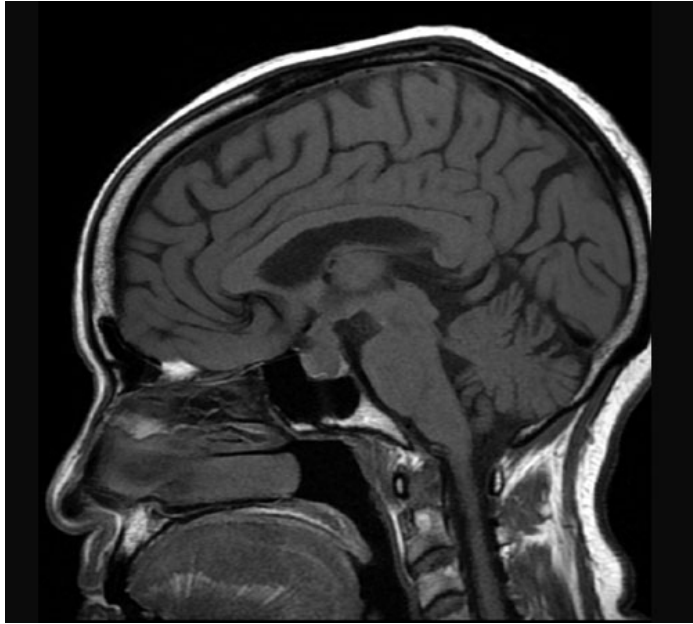
# MRI then...





...and now





# Nuclear Magnetic Resonance

- 1946: Discovery of NMR
  - Felix Bloch and Edward Purcell
- 1970: First NMR imaging experiments
  - “Zeugmatography” by Lauterbur and Damadian

Nobel Prize winners



I.I. Rabi 1944



W. Pauli 1945



F. Bloch 1952



E.M. Purcell 1952



# Spin

## 1.2.5 The Pauli principle

The spin of particles has profound consequences. The *Pauli principle*<sup>1</sup> states:

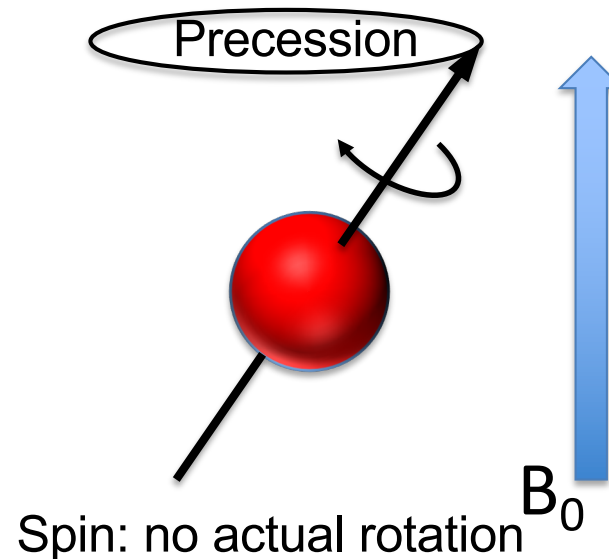
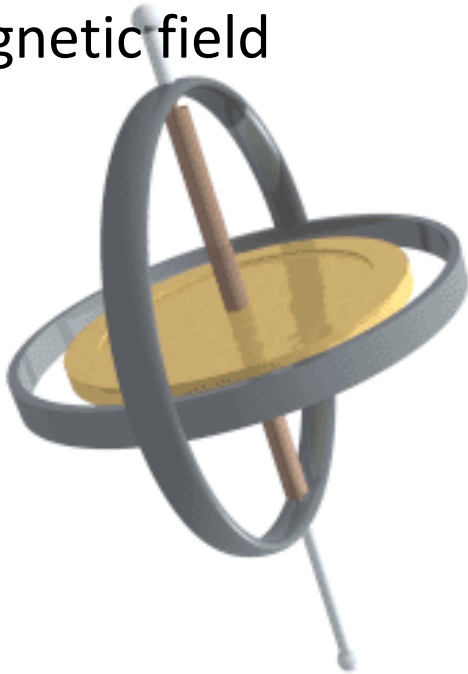
*two fermions may not have identical quantum states.*

Since the electron is a fermion, this has major consequences for atomic and molecular structure. For example, the periodic system, the stability of the chemical bond, and the conductivity of metals, may all be explained by allowing electrons to fill up available quantum states, at each stage pairing up electrons with opposite spin before proceeding to the next level. This is called the *Aufbau principle* of matter, and is explained in standard textbooks on atomic and molecular structure (see *Further Reading*).

The everyday fact that one's body does not collapse spontaneously into a black hole depends on the spin-1/2 of the electron.

# Nuclear magnetic moment and precession

- Atomic nuclei with odd mass number or odd charge number have non-zero **spin**
  - Magnetic moment, angular momentum
- The magnetic moment **precesses** in the presence of a magnetic field



**The name of the game**



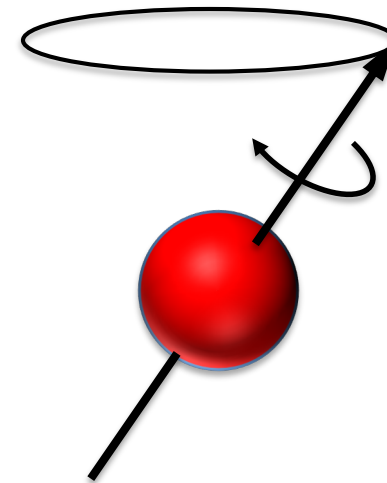
# Larmor frequency

- Precession frequency proportional to spin magnetic moment and magnetic field

$$f_0 = \gamma B_0$$

$\gamma$  Gyromagnetic ratio

$B_0$  External magnetic field



$^1\text{H}$  at  $B_0=1.5\text{T}$ :

$$\gamma = 42.58 \text{ MHz / T}$$

$$f_0 = 64 \text{ MHz}$$

# Quantization misconception

- Not only two possible states
  - Superposition of eigenstates:  $\psi(t) = a(t)\psi_a + b(t)\psi_b$
- Quantization only occurs when measuring a single spin
- MRI always consider many spins, and can keep the continuous, non-quantized representation.

## Geometrical Representation of the Schrödinger Equation for Solving Maser Problems

RICHARD P. FEYNMAN AND FRANK L. VERNON, JR., *California Institute of Technology, Pasadena, California*

AND

ROBERT W. HELLWARTH, *Microwave Laboratory, Hughes Aircraft Company, Culver City, California*

(Received September 18, 1956)

beam, such that the wave function for any one individual

$$\psi(t) = a(t)\psi_a + b(t)\psi_b$$

single system corresponding to the energies  $W + \hbar\omega_0/2$  and  $W - \hbar\omega_0/2$  respectively.  $W$  is the mean energy of the two levels determined by velocities and internal interactions which remain unchanged.  $W$  will be taken as the zero of energy for each system.  $\omega_0$  is the resonant angular frequency associated with a transition between the two levels and is always taken positive.

It is usual to solve Schrödinger's equation with some perturbation  $V$  for the complex coefficients  $a(t)$  and  $b(t)$ , and from them calculate the physical properties of the system. However, the mathematics is not always transparent and the complex coefficients do not give directly the values of real physical observables. Neither is it sufficient to know only the real magnitudes of  $a$  and  $b$ , i.e., the level populations and transition probabilities, when coherent processes are involved. We propose instead to take advantage of the fact that the phase of  $\psi(t)$  has no influence so that only three real numbers are needed to completely specify  $\psi(t)$ . We

construct a 3-vector

$$\begin{aligned} r_1 &\equiv ab^* + ba^* \\ r_2 &\equiv i(ab^* - ba^*) \\ r_3 &\equiv aa^* - bb^* \end{aligned} \quad (2)$$

(\*) all depend on time

equation which gives

$$i\hbar da/dt = a[(\hbar\omega_0/2) + V_{aa}] + bV_{ab} \quad (3)$$

and similar equations for  $db/dt$ ,  $da^*/dt$ ,  $db^*/dt$ . The subscripts on  $V$  indicate the usual matrix elements.  $V_{aa} = V_{bb} = 0$  for most all cases of interest, and whenever these can be neglected compared to  $\hbar\omega_0/2$ ,  $V$  need be neither small nor of short duration for the results to be exact. Using Eqs. (3) to find the differential equation for

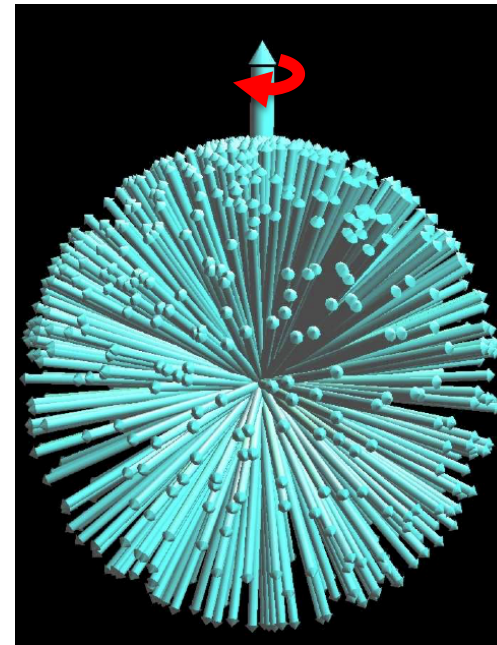
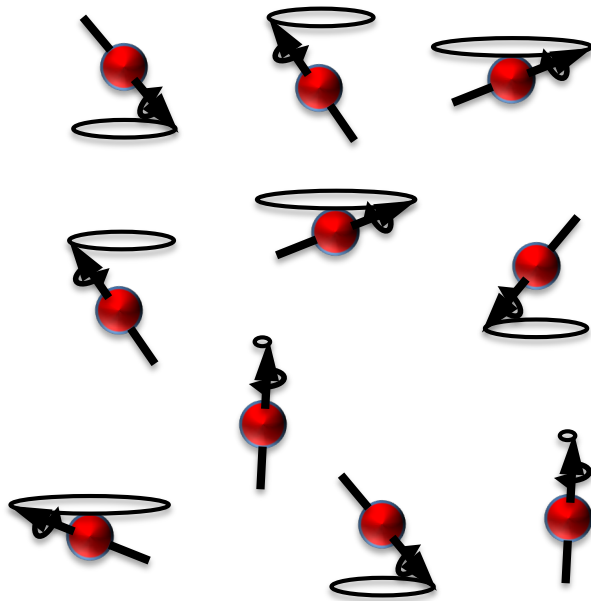
$$d\mathbf{r}/dt = \boldsymbol{\omega} \times \mathbf{r} \quad (4)$$

where  $\boldsymbol{\omega}$  is defined by the three real components:

$$\begin{aligned} \omega_1 &\equiv (V_{ab} + V_{ba})/\hbar \\ \omega_2 &\equiv i(V_{ab} - V_{ba})/\hbar \\ \omega_3 &\equiv \omega_0 \end{aligned} \quad (5)$$

# Net magnetization

- Many spins result in a net magnetization;  $M$

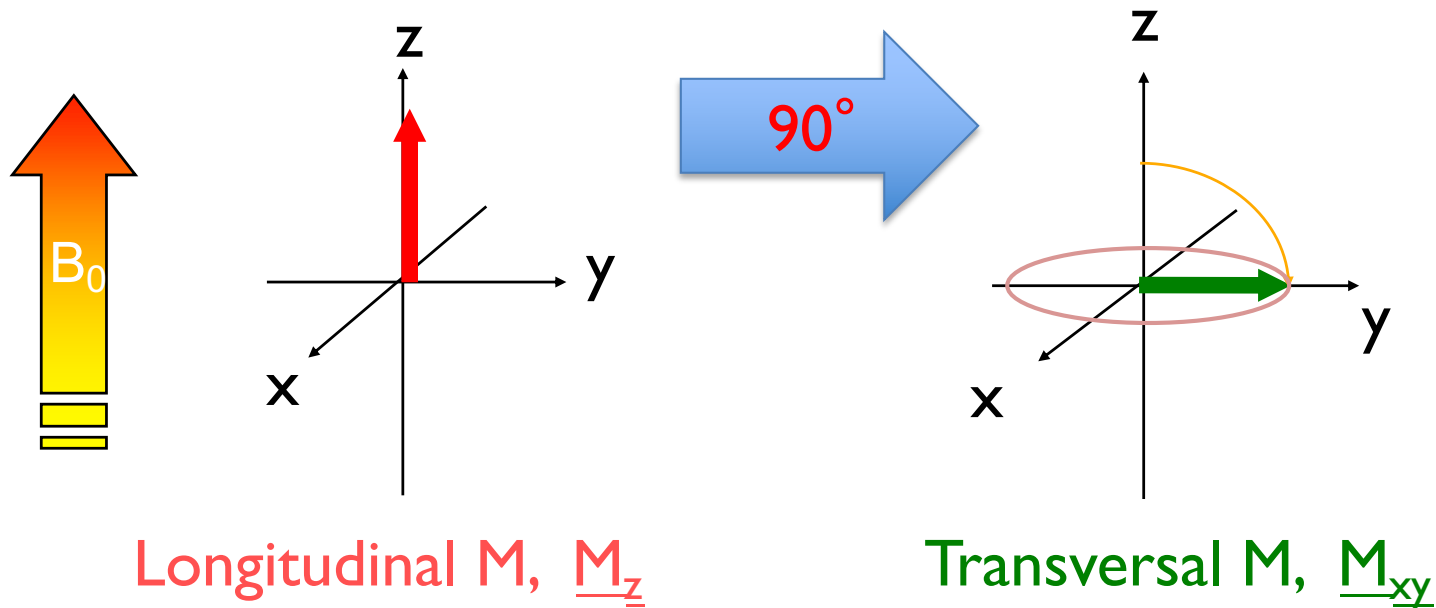


Typical conditions ( $^1\text{H}$  at  $B_0=1.5\text{T}$ ,  $37^\circ\text{C}$ ):  
polarization  $\sim 0.00001$  ( $10^{-5}$ )

Hanson L, Concepts Mag Reson, 2008

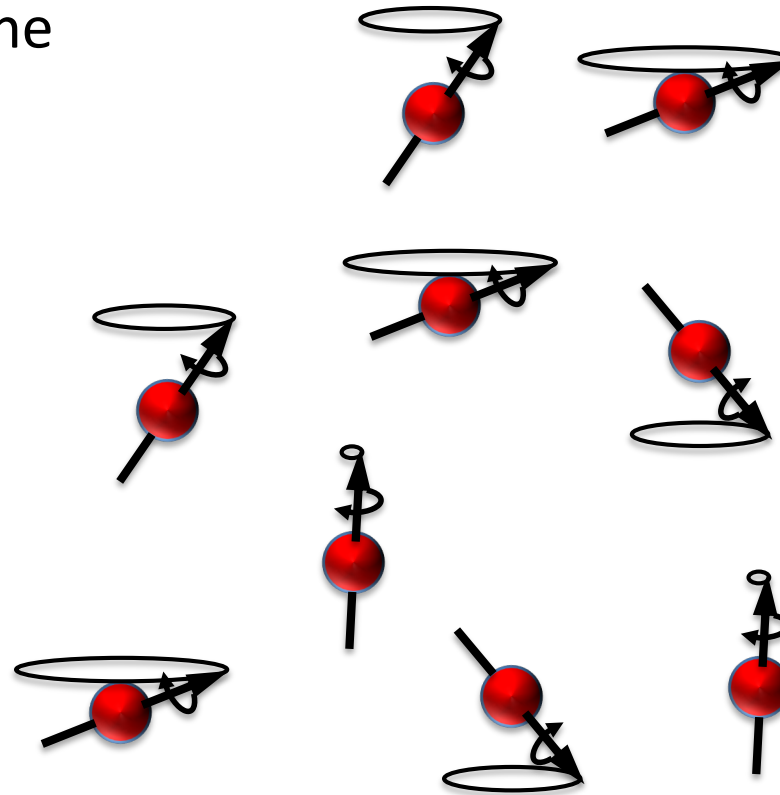
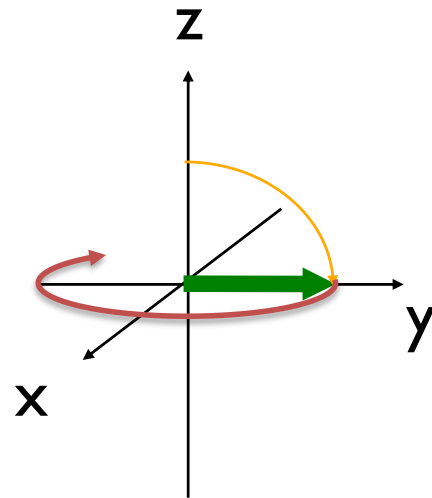
# RF Excitation

- Time varying magnetic field, with Larmor frequency
  - 50-150 MHz, “radio frequency band”
  - Not propagating radio wave
- Turns magnetization away from the z axis



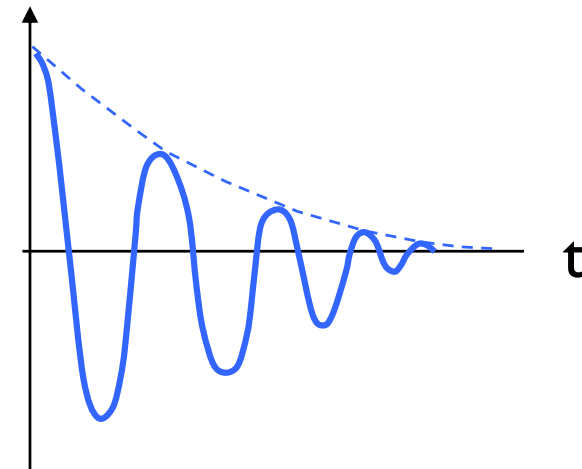
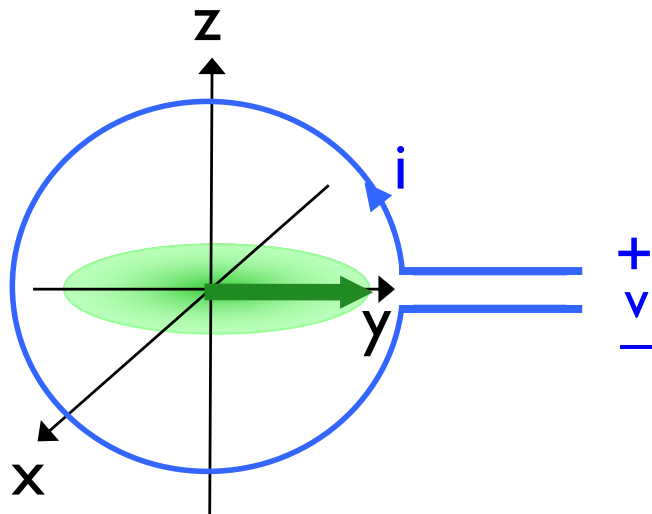
# Net magnetization precession

- After excitation, the net magnetization also precesses around the external magnetic field
- Precession frequency is the Larmor frequency



# Signal reception

- Time varying current  $\rightarrow$  creates a magnetic field
- Time varying magnetic field  $\rightarrow$  induces a current
- Rotating  $M_{xy}$  induces a current in a conducting loop

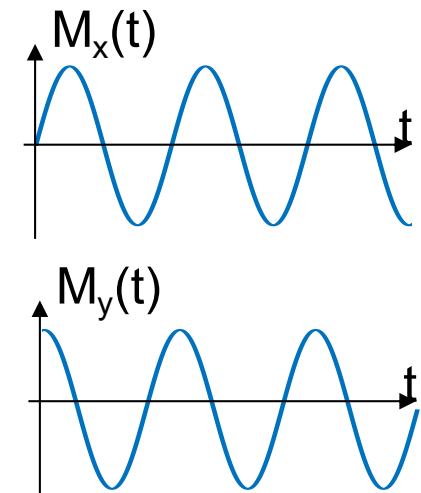
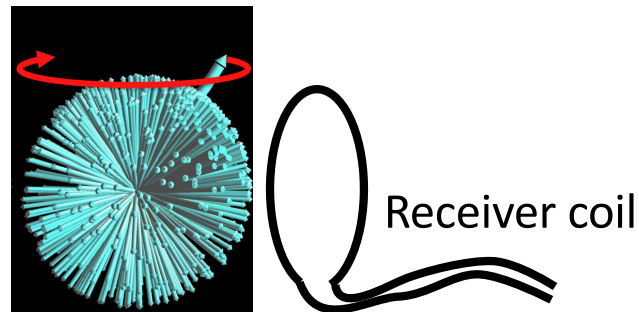


# Signal reception

- Faraday's law of induction

$$V(t) = -\frac{\partial \Phi}{\partial t}$$

$\Phi$  - Magnetic flux through coil  
 $V(t)$  - Induced voltage in coil

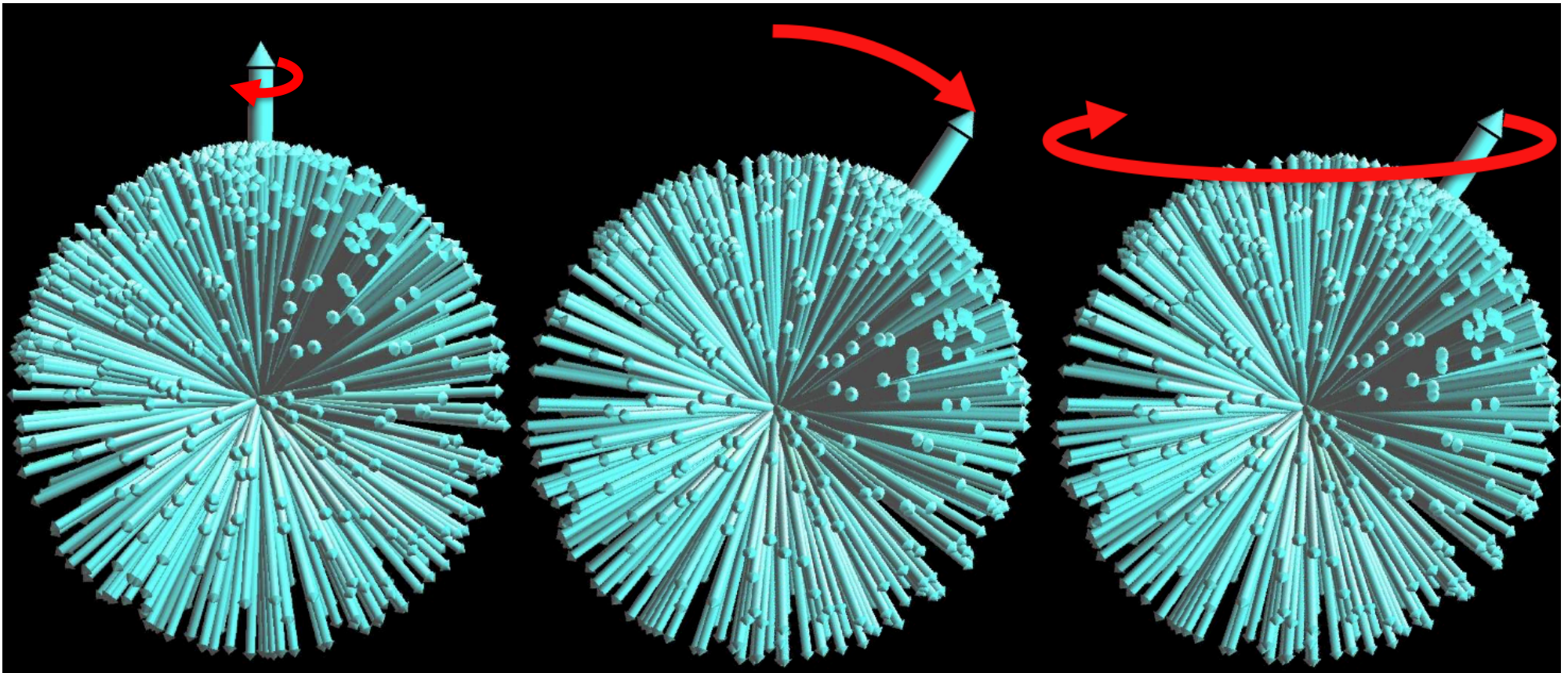


- Rotating  $M$  in  $xy$  plane induces a current in a conducting loop
- Signal is complex valued – proportional to  $M_x + iM_y$



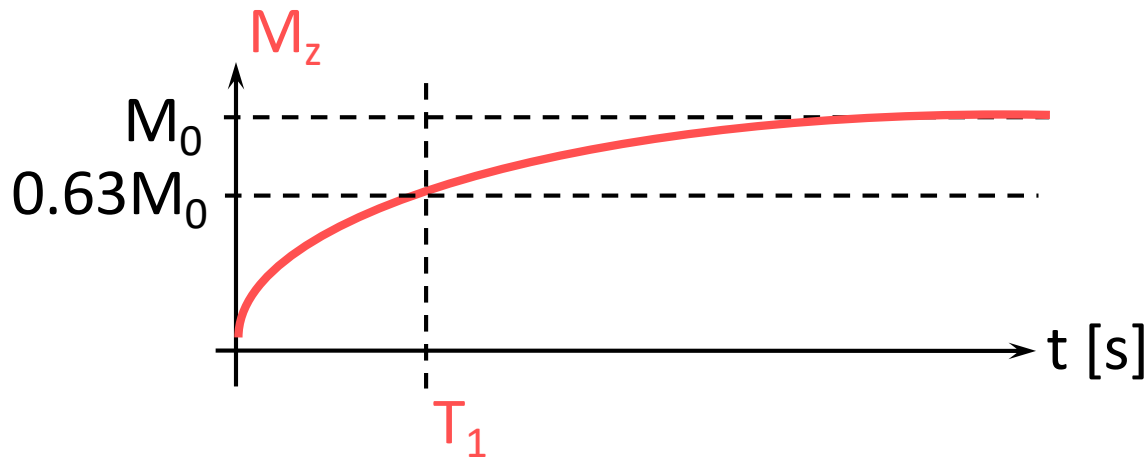
# RF excitation and precession

- RF excitation can be used to rotate magnetic moments
- Net magnetization rotates and precesses



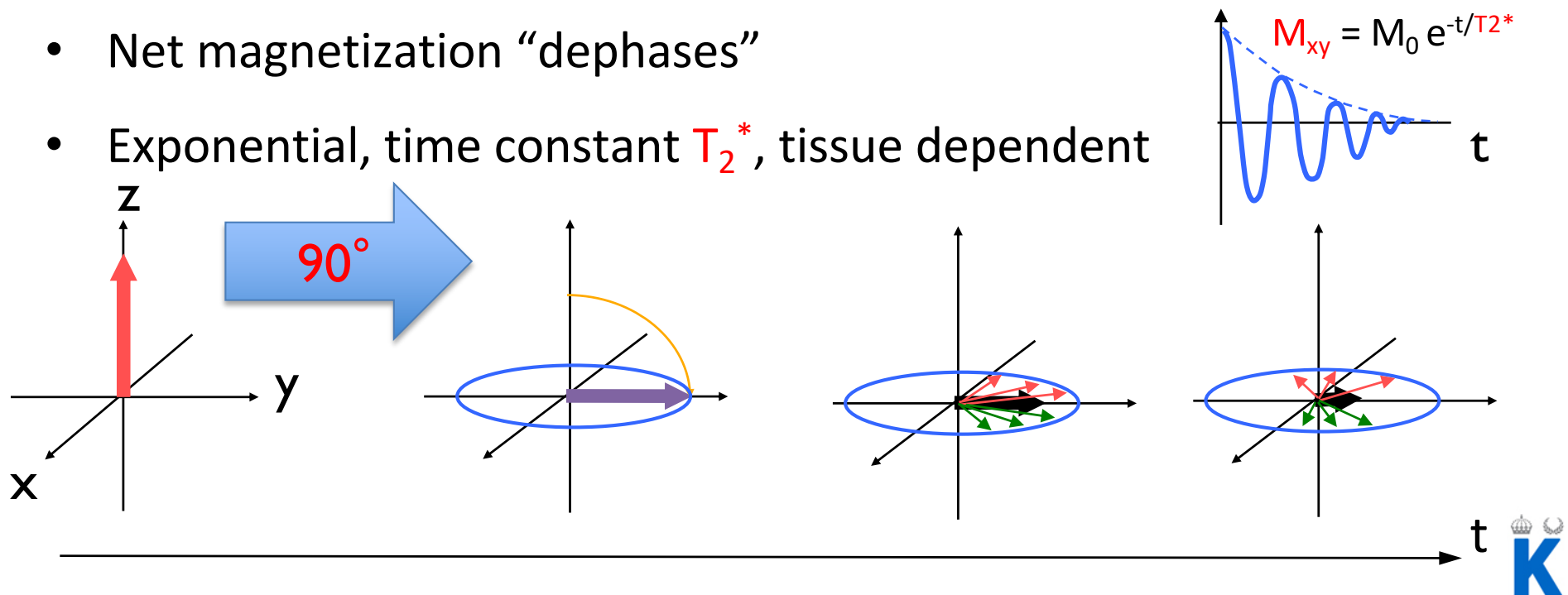
# $T_1$ relaxation

- After excitation, the system returns to equilibrium
- $M_z$  returns exponentially
  - $M_z = M_0 (1 - e^{-t/T_1})$
- Time constant:  $T_1$
- Tissue dependent, typically in the order of 1 s for blood at 1.5 T



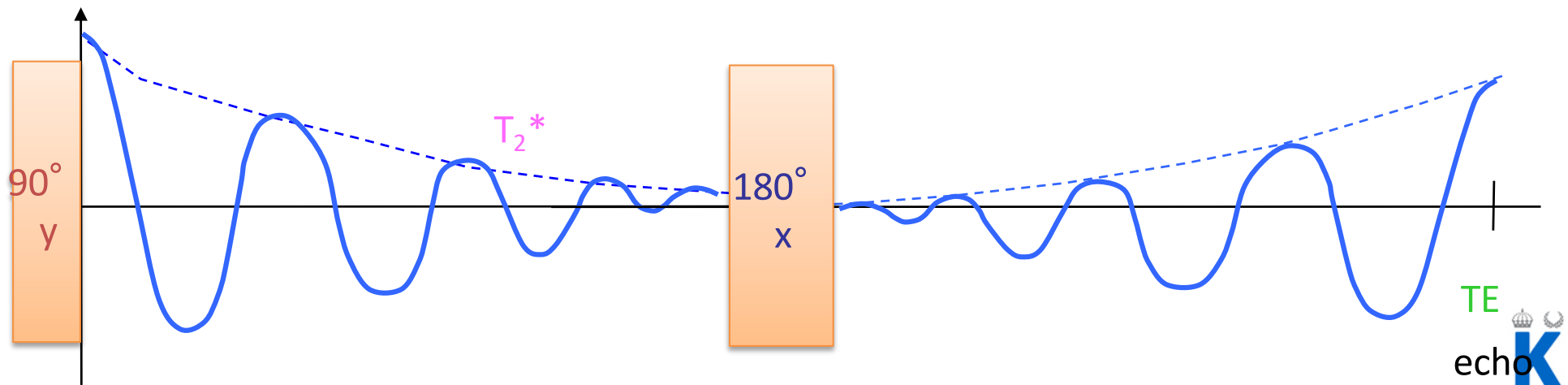
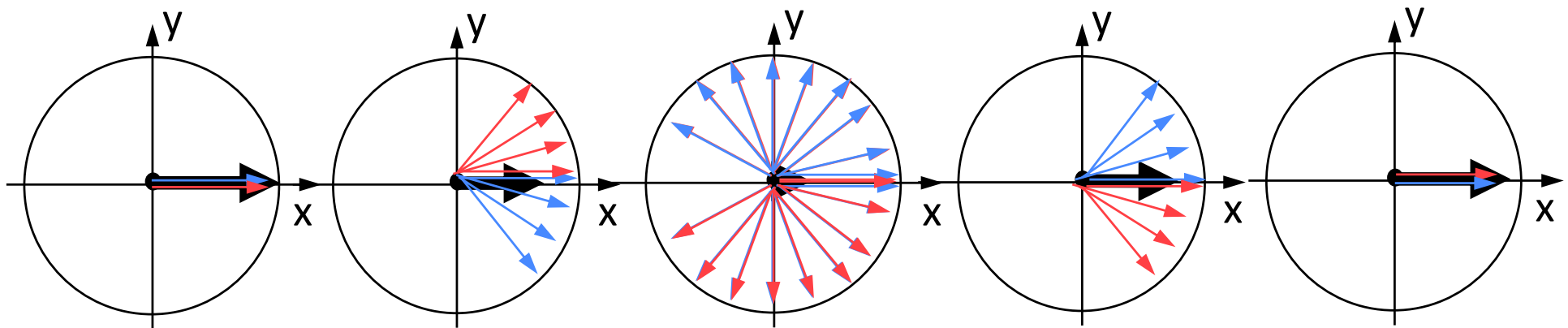
# $T_2^*$ relaxation

- Local variations of the magnetic field
  - Small magnetic field from surrounding electrons and nuclei
  - Non-homogeneous external magnetic field
- Varying magnetic field  $\rightarrow$  varying Larmor (precession) frequency
- Net magnetization “dephases”
- Exponential, time constant  $T_2^*$ , tissue dependent



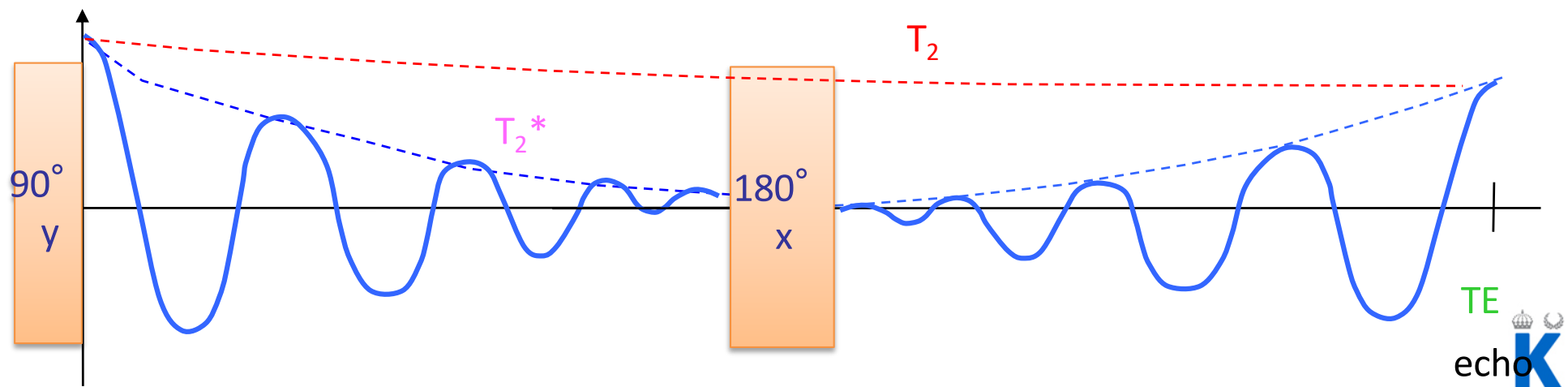
# The spin-echo pulse sequence

- Dephasing due to time-constant local variations can be refocused using an  $180^\circ$  pulse



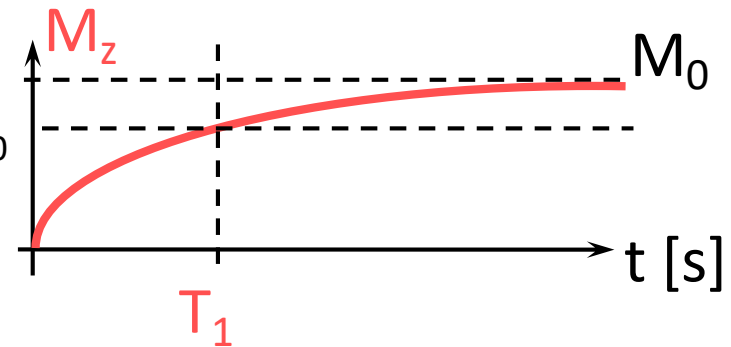
# $T_2$ and $T_2^*$ relaxation

- Time-constant magnetic field variations can be refocused
  - Magnetic field inhomogeneities
- Time-varying variations cannot
  - Small magnetic field from surrounding electrons and nuclei
- Spin-echo pulse sequence not always applicable (no refocusing possible)
  - $T_2^*$  is *apparent*  $T_2$

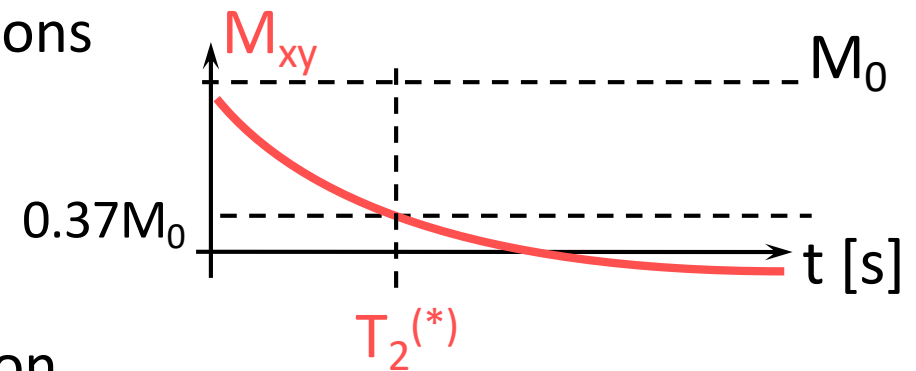


# Relaxation summary

- $T_1$ : Longitudinal relaxation
  - Recovery of  $M_z$  to equilibrium



- $T_2$ : Transverse relaxation
  - Dynamic magnetic field variations
  - Reduction of  $M_{xy}$  magnitude due to dephasing
  - Unavoidable

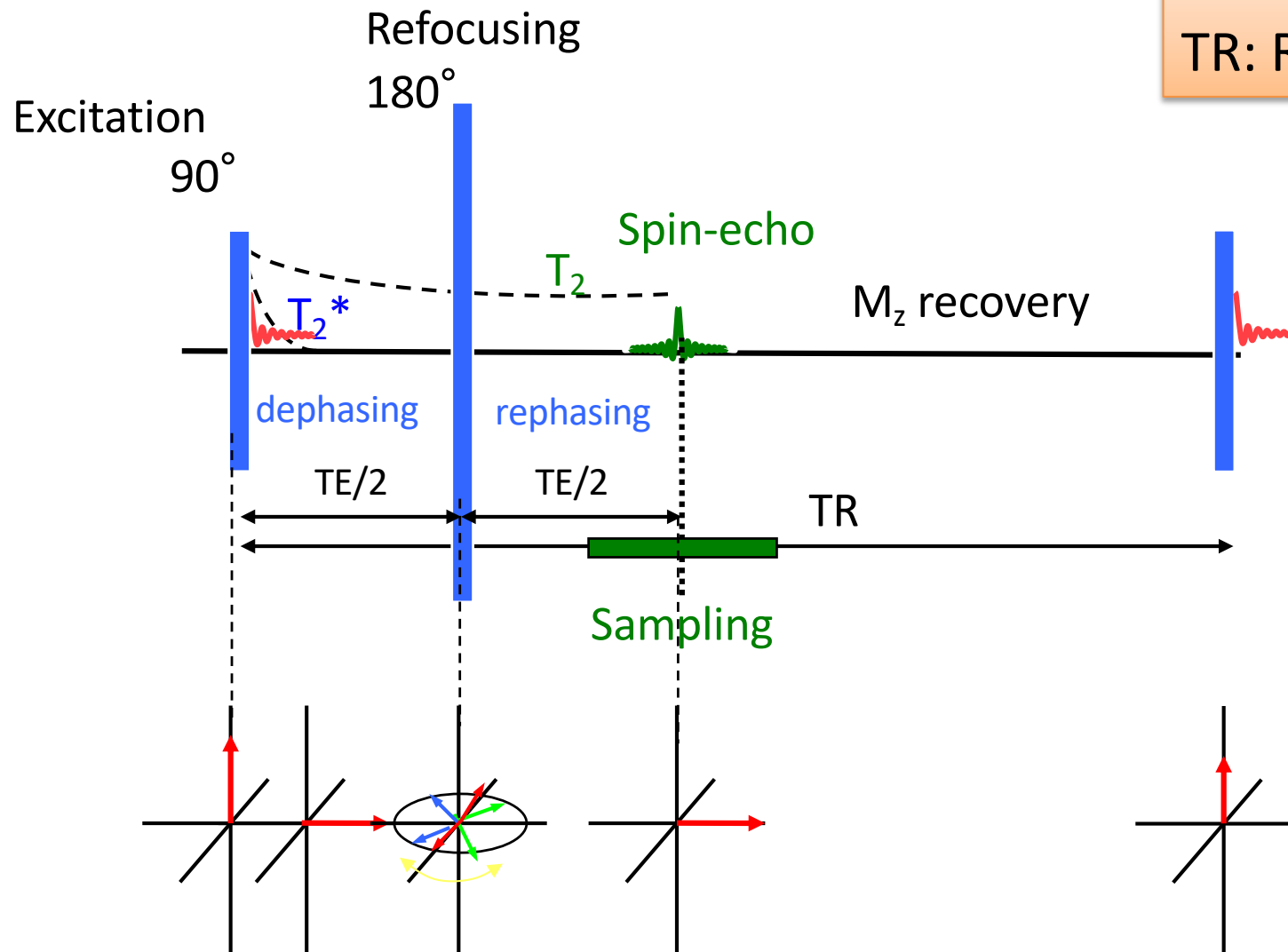


- $T_2^*$ : Apparent transverse relaxation
  - Static *and* Dynamic magnetic field variations
  - If static variations are not refocused, it manifests as apparent  $T_2$
- $T_2^* < T_2 < T_1$

# $T_1$ and $T_2$ values at 1.5 T

Tissue type	$T_1$	$T_2$
CSF	2500 ms	1000 ms
White brain matter	780 ms	90 ms
Gray brain matter	920 ms	100 ms
Blood	1200 ms	360 ms
Myocardium	880 ms	75 ms
Fat	260 ms	110 ms

# Spin-echo pulse sequence

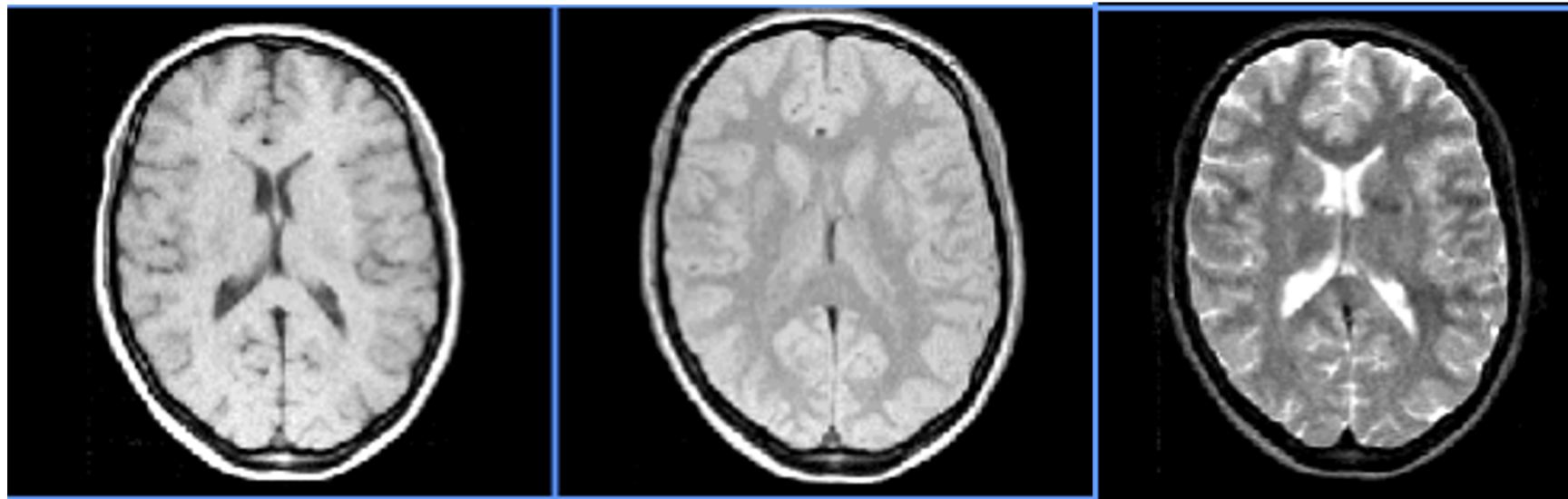


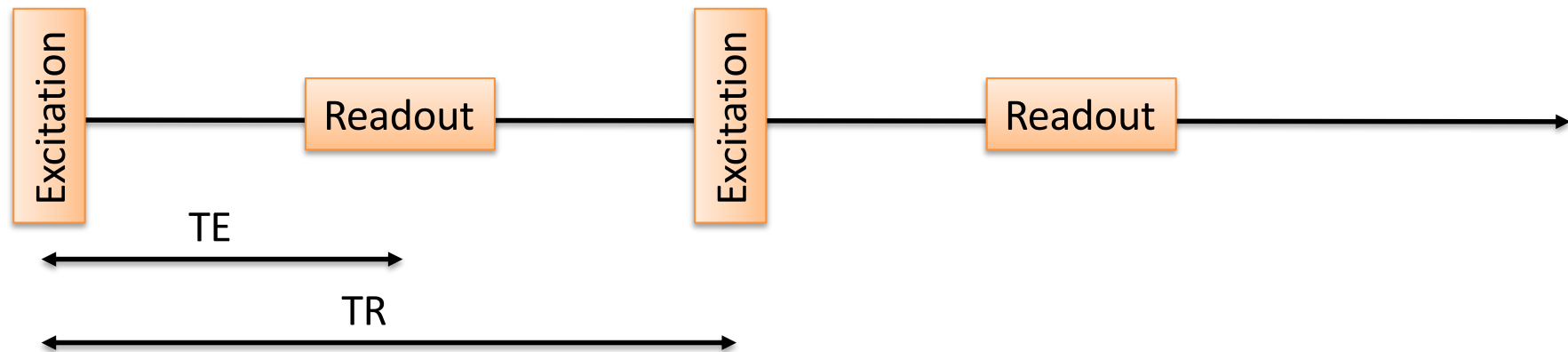
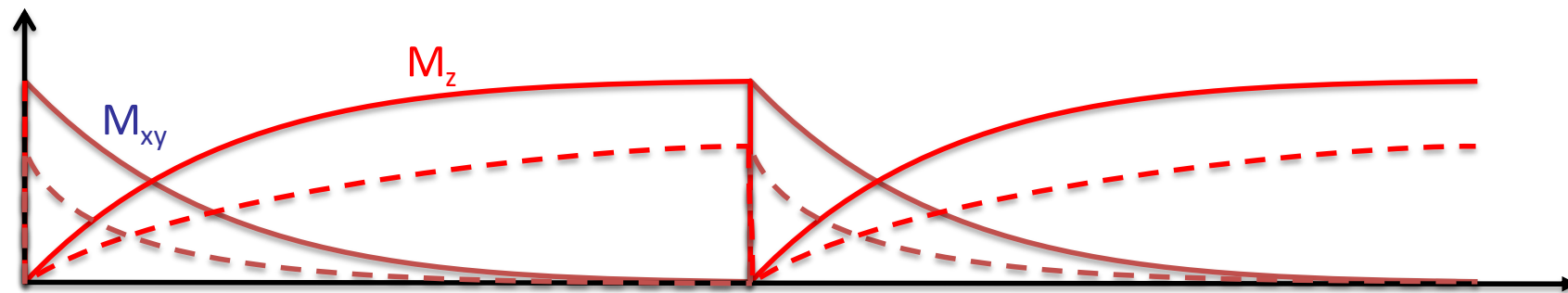
TE: Echo time  
TR: Repetition time



# Image contrast

- By modifying pulse sequence timing (TE and TR), different image contrasts can be obtained
  - Tissue dependent  $T_1$
  - Tissue dependent  $T_2$

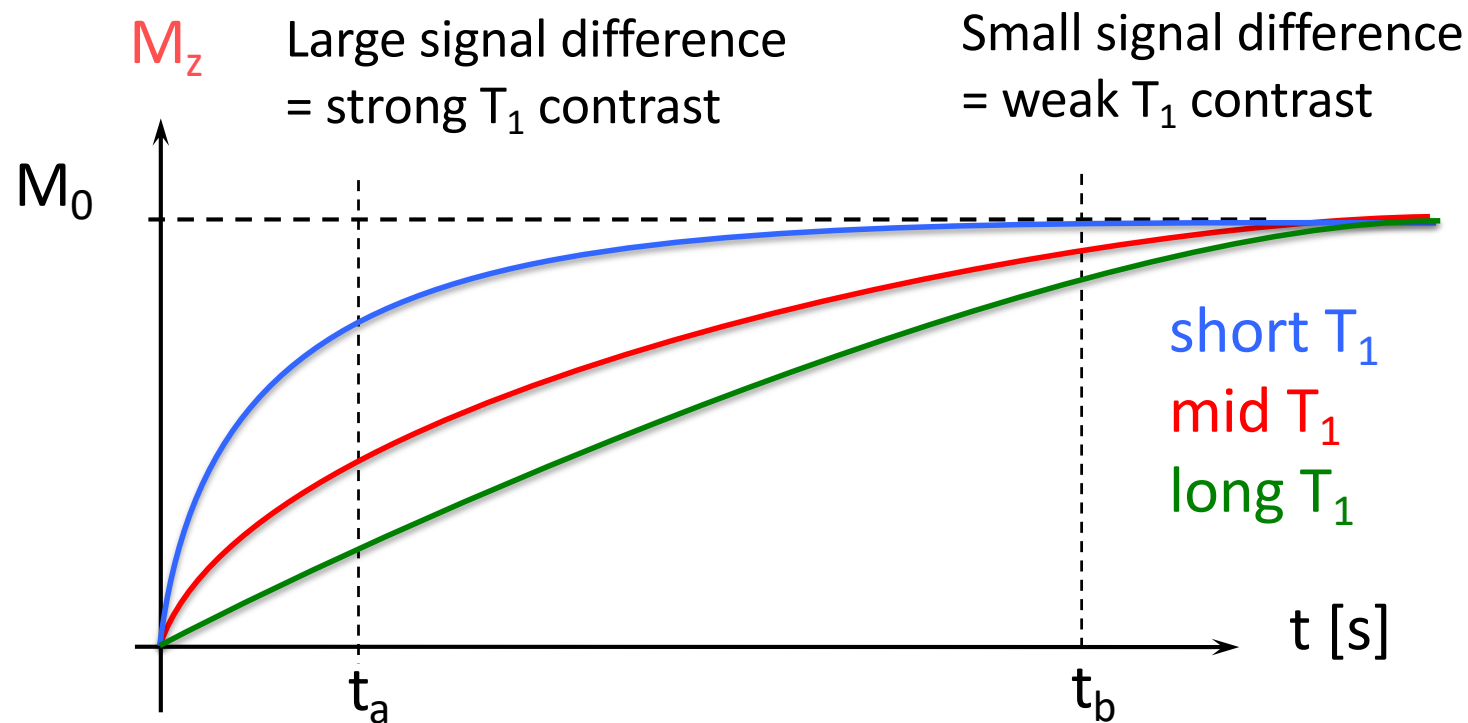




By adjusting TE and TR, signal magnitude will vary depending on  $T_1$  and  $T_2$

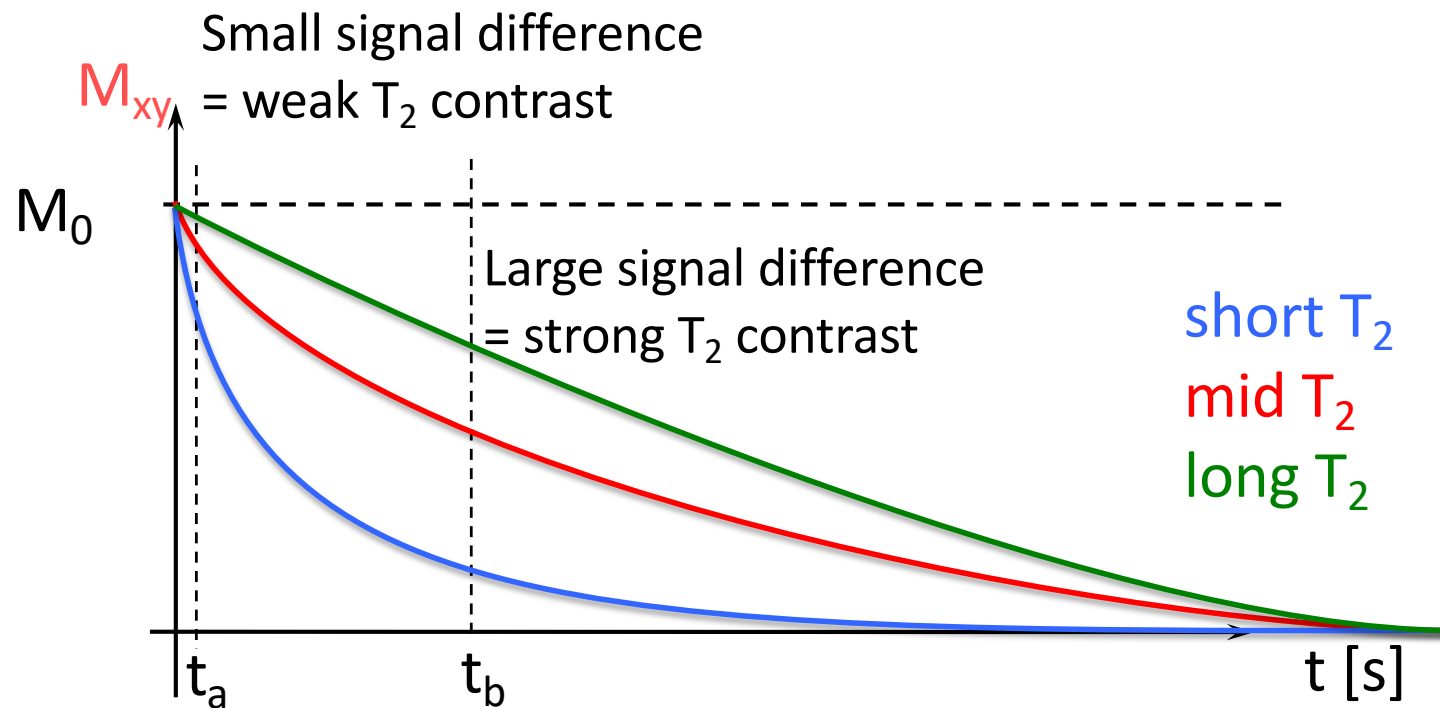
# $T_1$ contrast

- Different tissues have different  $T_1$  relaxation times
- $T_1$  contrast depend on sequence timing
  - Time after excitation (how much signal is *recovered*)



# $T_2$ contrast

- Different tissues have different  $T_2$  relaxation times
- $T_2$  contrast depend on sequence timing
  - Time after excitation (how much signal has *dephased*)

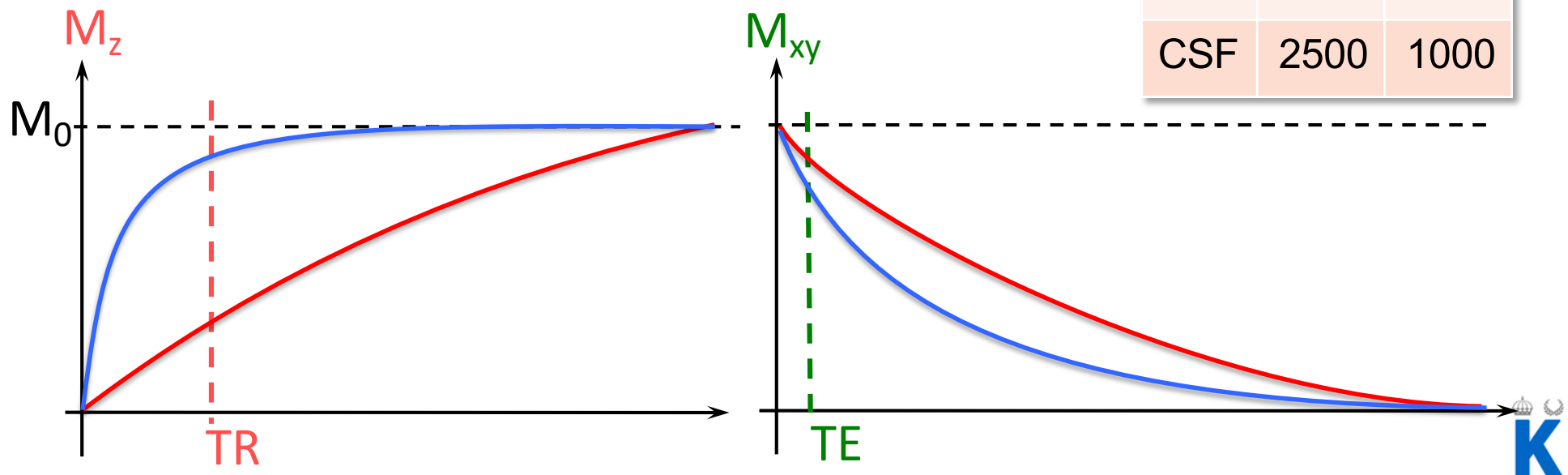


# $T_1$ weighting

- Short **TR**: maximizes  $T_1$  contrast
- Short **TE**: minimizes  $T_2$  contrast
- TE cannot be made infinitely short

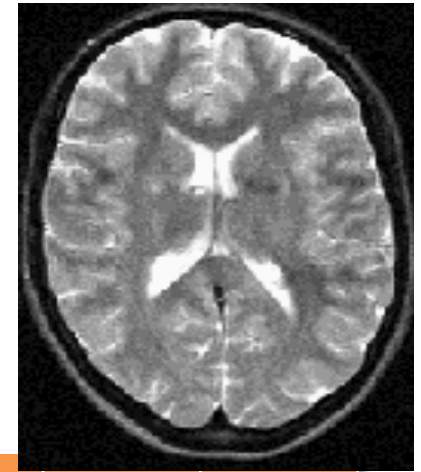


	$T_1$	$T_2$
WM	780	90
GM	920	100
CSF	2500	1000

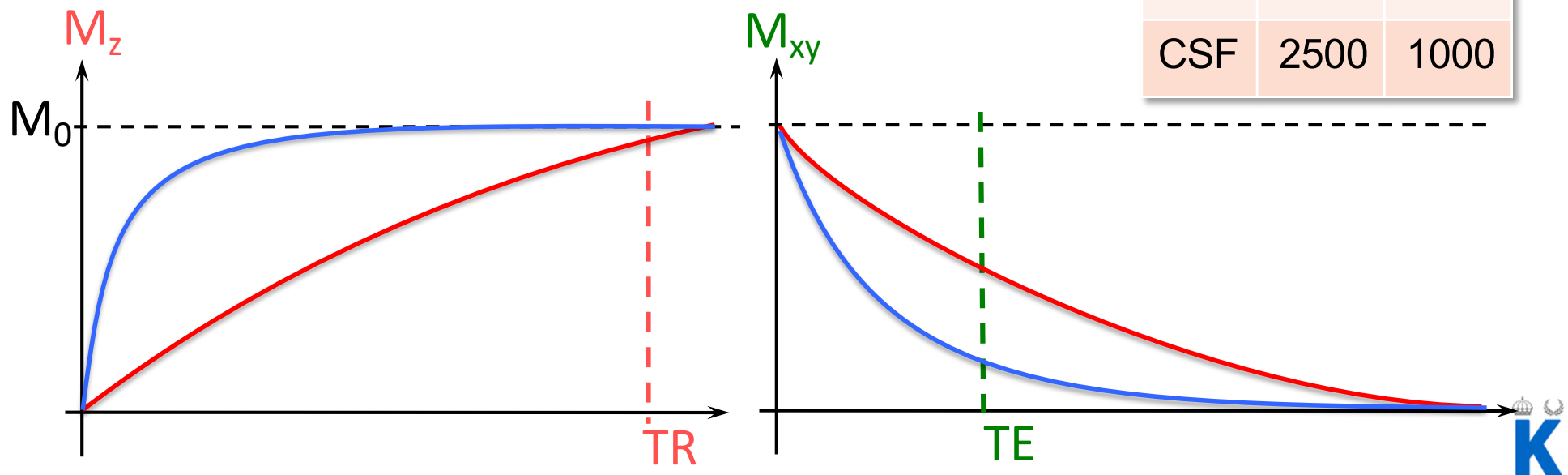


# T<sub>2</sub> weighting

- Long **TR**: minimizes **T<sub>1</sub>** contrast
- Long **TE**: maximizes **T<sub>2</sub>** contrast
- Too long TE and all signal is lost

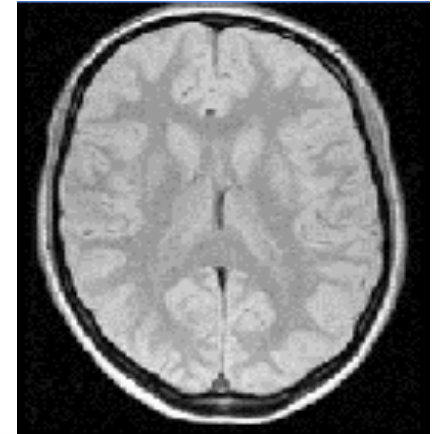


	T <sub>1</sub>	T <sub>2</sub>
WM	780	90
GM	920	100
CSF	2500	1000

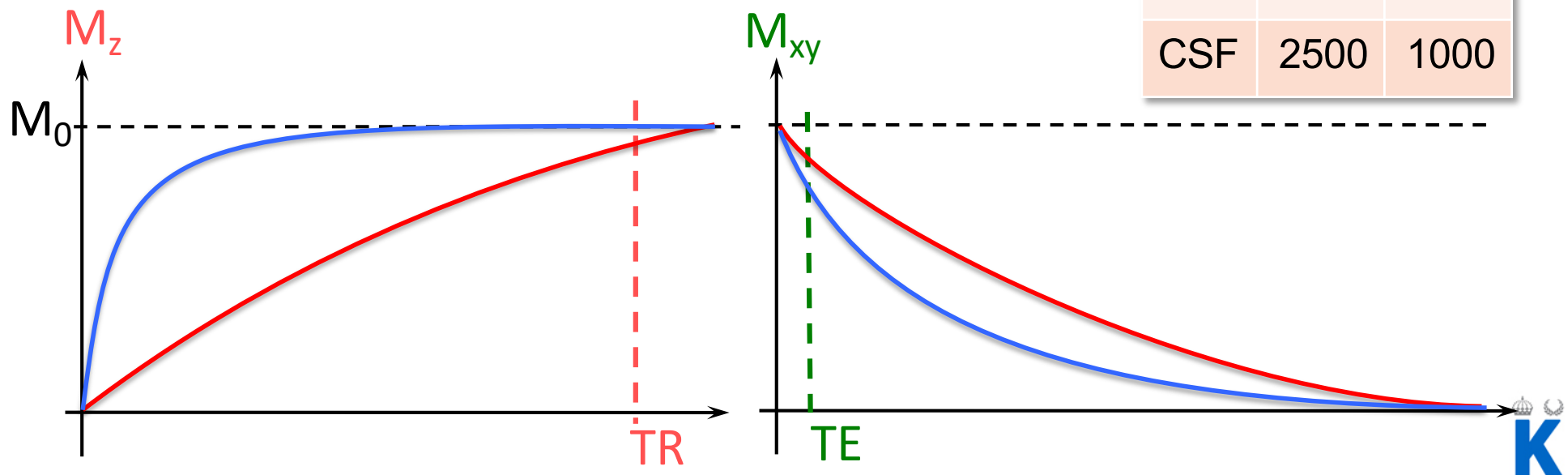


# Proton Density (PD) weighting

- Long **TR**: minimizes **T<sub>1</sub>** contrast
- Short **TE**: minimizes **T<sub>2</sub>** contrast
- Remaining contrast depends on proton density



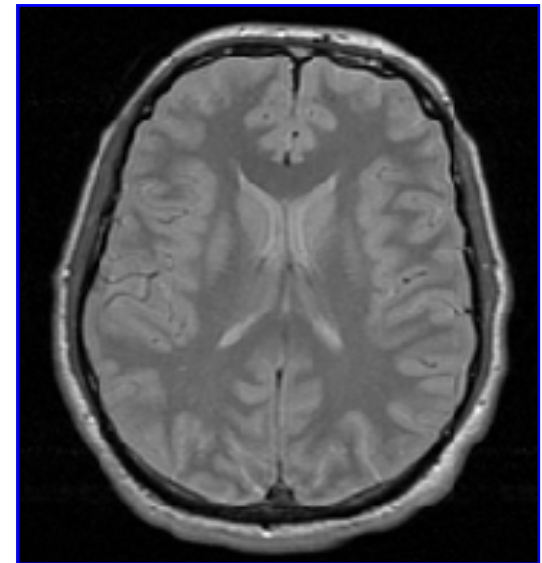
	T <sub>1</sub>	T <sub>2</sub>
WM	780	90
GM	920	100
CSF	2500	1000





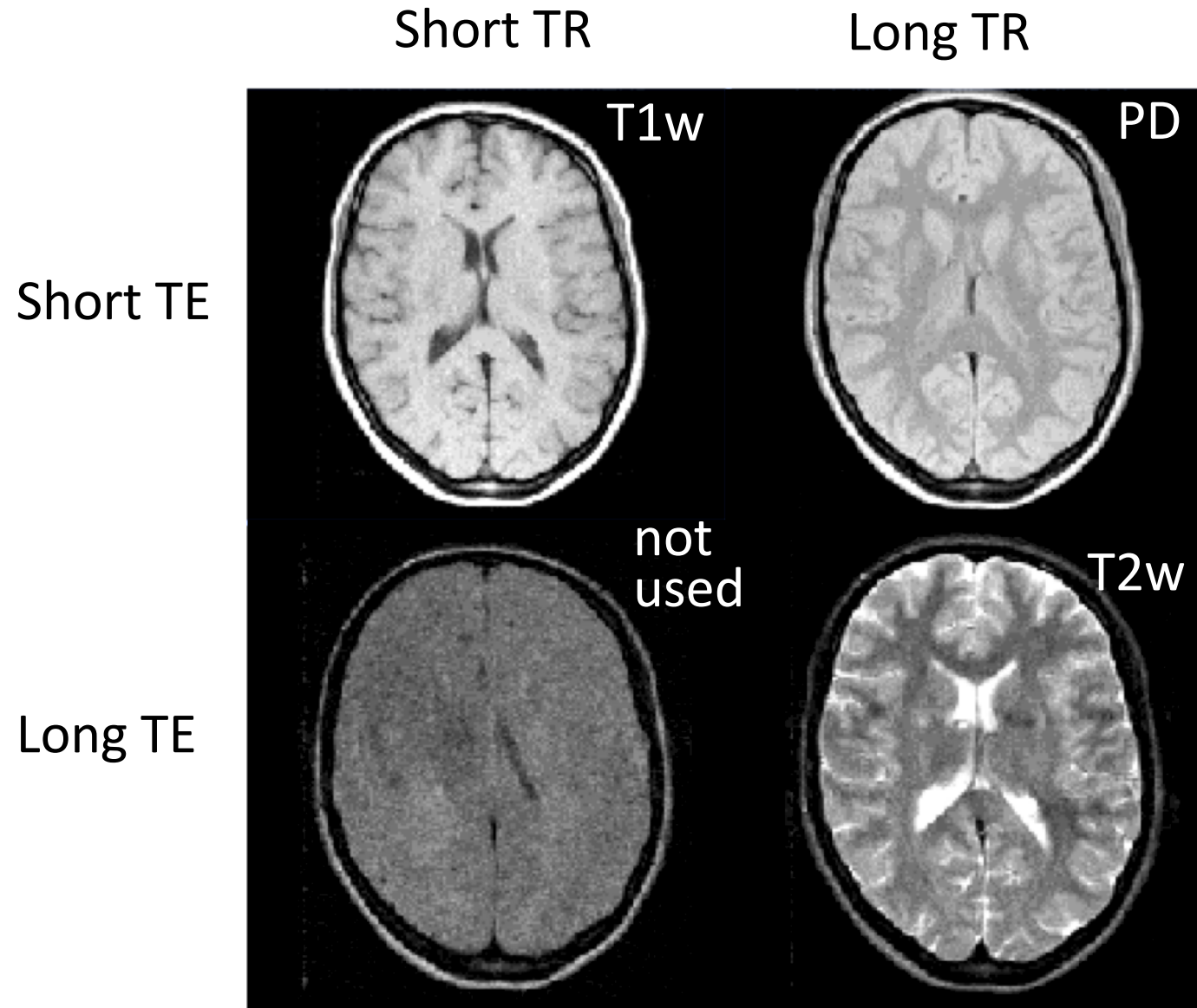
# Proton Density (PD)

- The signal magnitude depends on the number of hydrogen nuclei (protons) in the tissue
  - -> Proton density weighting
- Different tissues have different proton densities
  - fluids: ~95 %
  - fat and water-based tissues 65-85 %
- Generally weak contrast images



Peter Jezzard

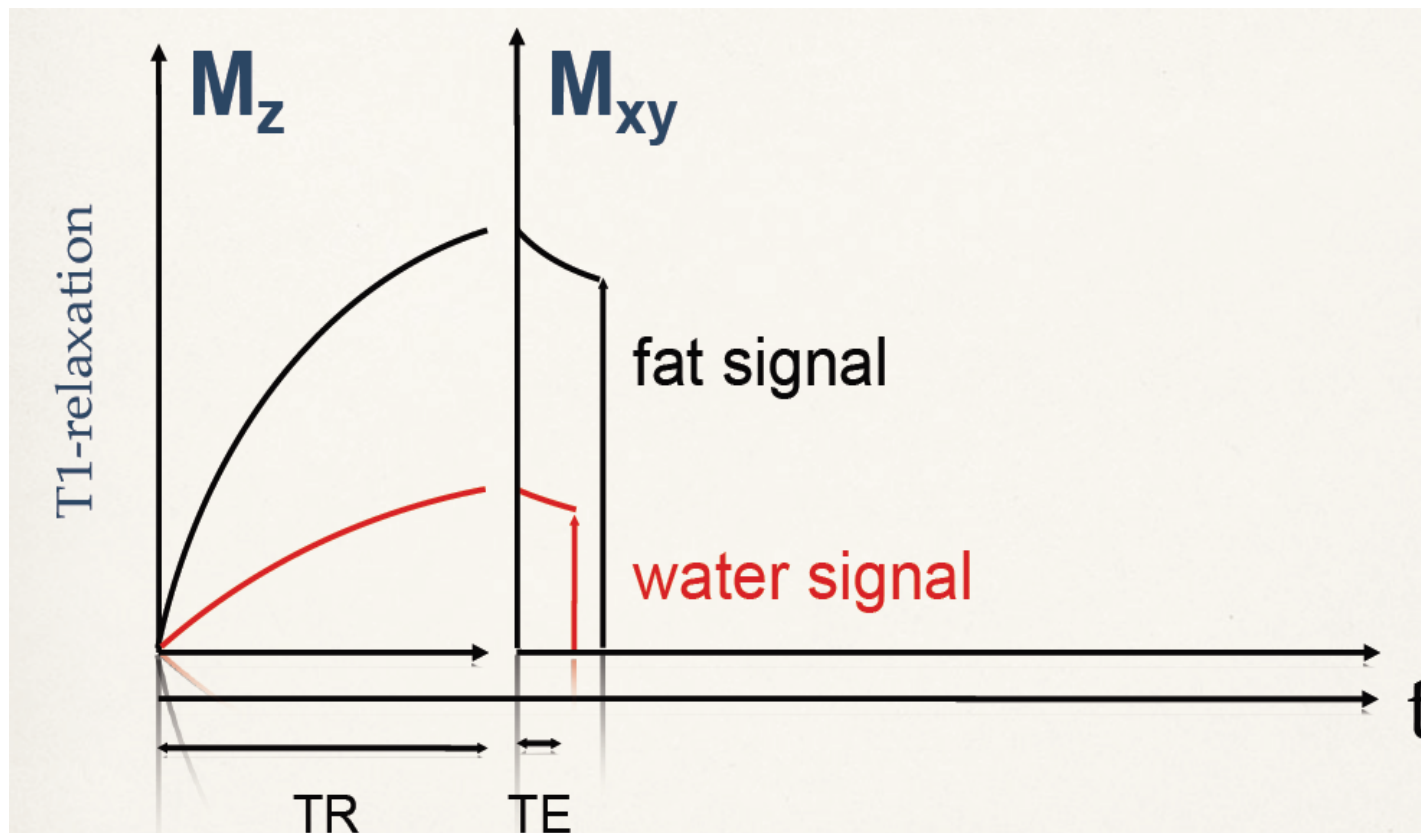
# Contrast weightings



	T <sub>1</sub>	T <sub>2</sub>
WM	780	90
GM	920	100
CSF	2500	1000

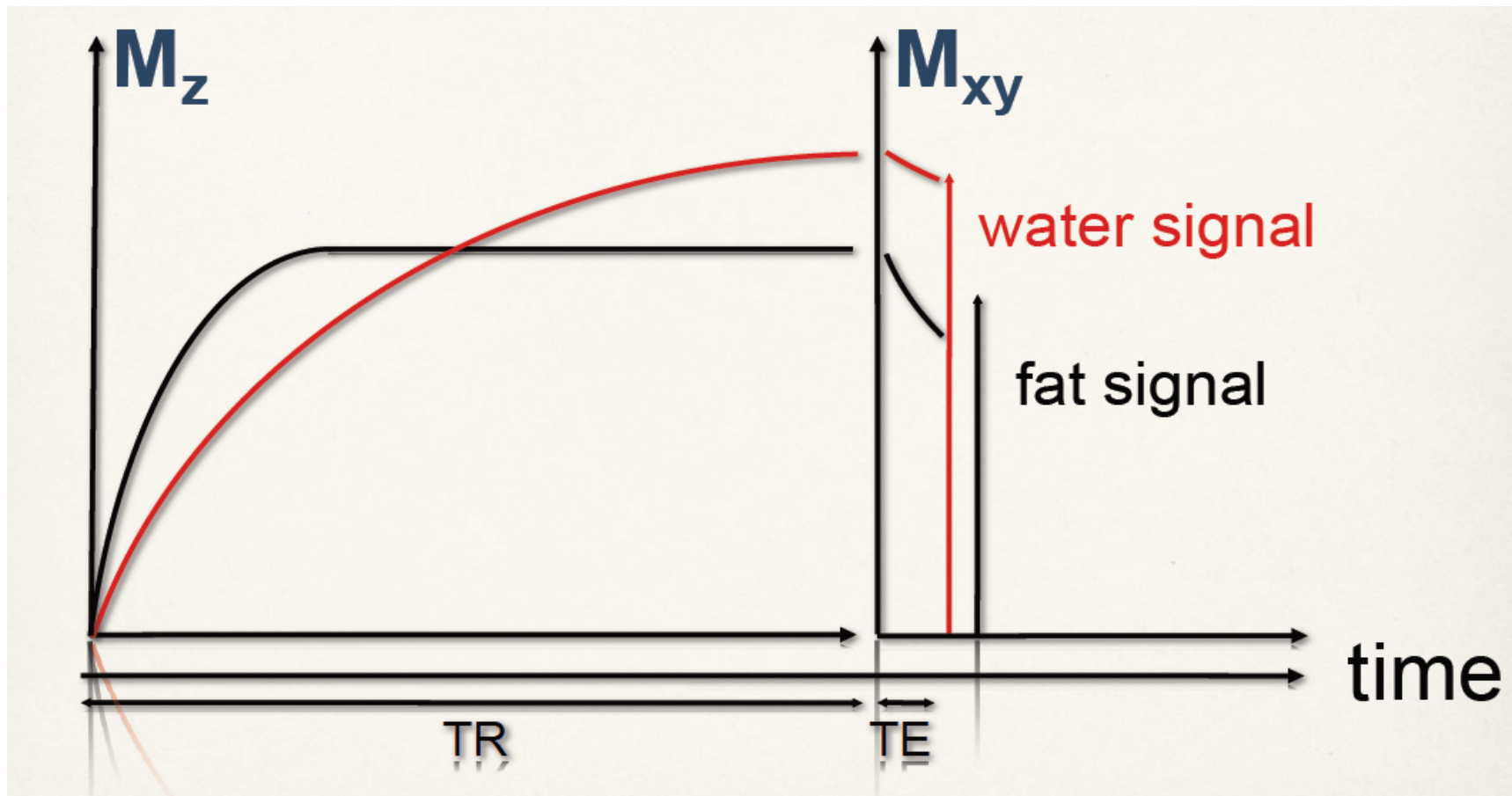
# Contrast weighting quiz 1/3

- TE = <15 ms (short), TR = 400-600 ms (short)
- Water dark, fat bright - T1-weighted



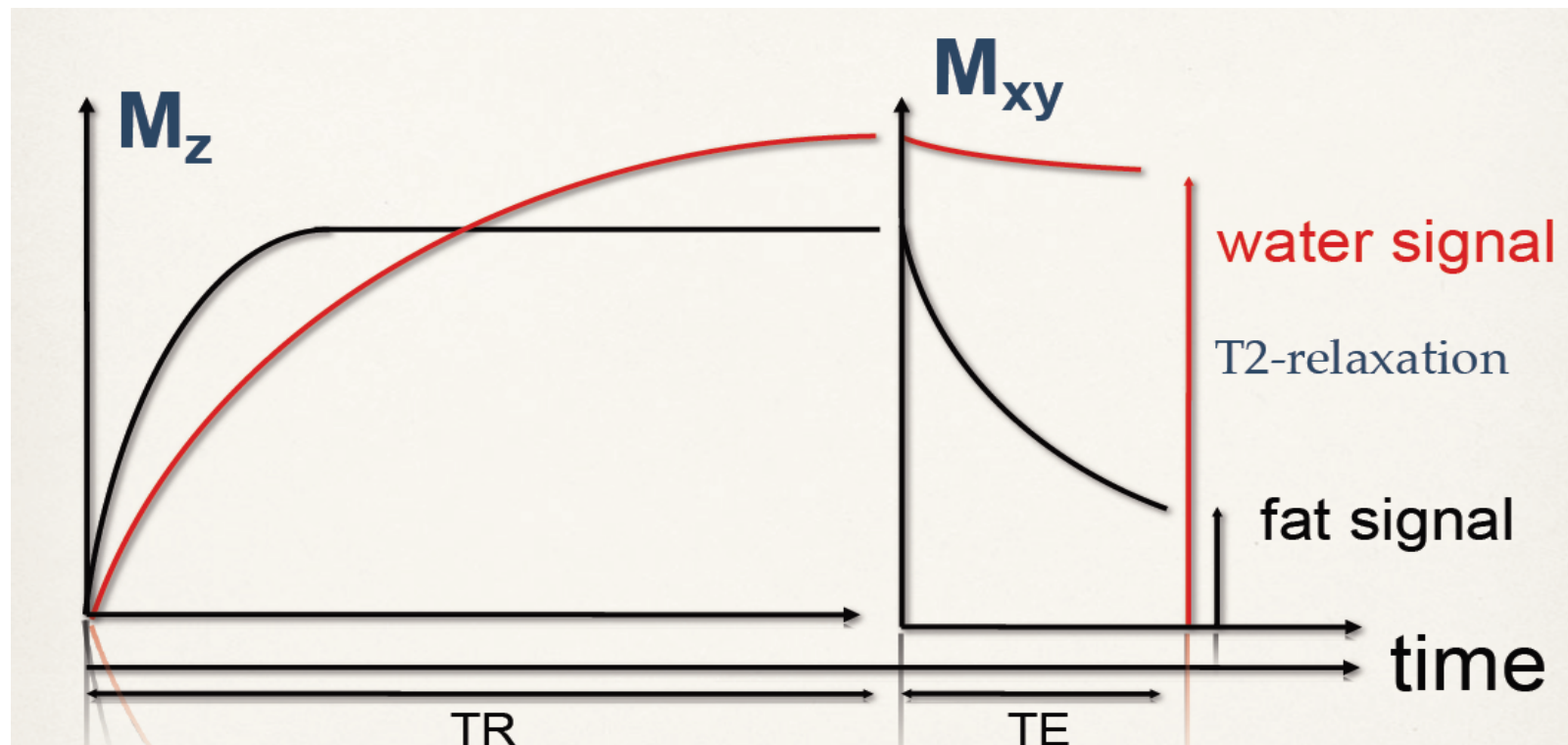
# Contrast weighting quiz 2/3

- TE = <15 ms (short), TR > 4000 ms (long)
- Proton density weighted



# Contrast weighting quiz 3/3

- TE = 80-90 ms (long), TR > 4000 ms (long)
- Water bright, fat dark – T<sub>2</sub> weighted

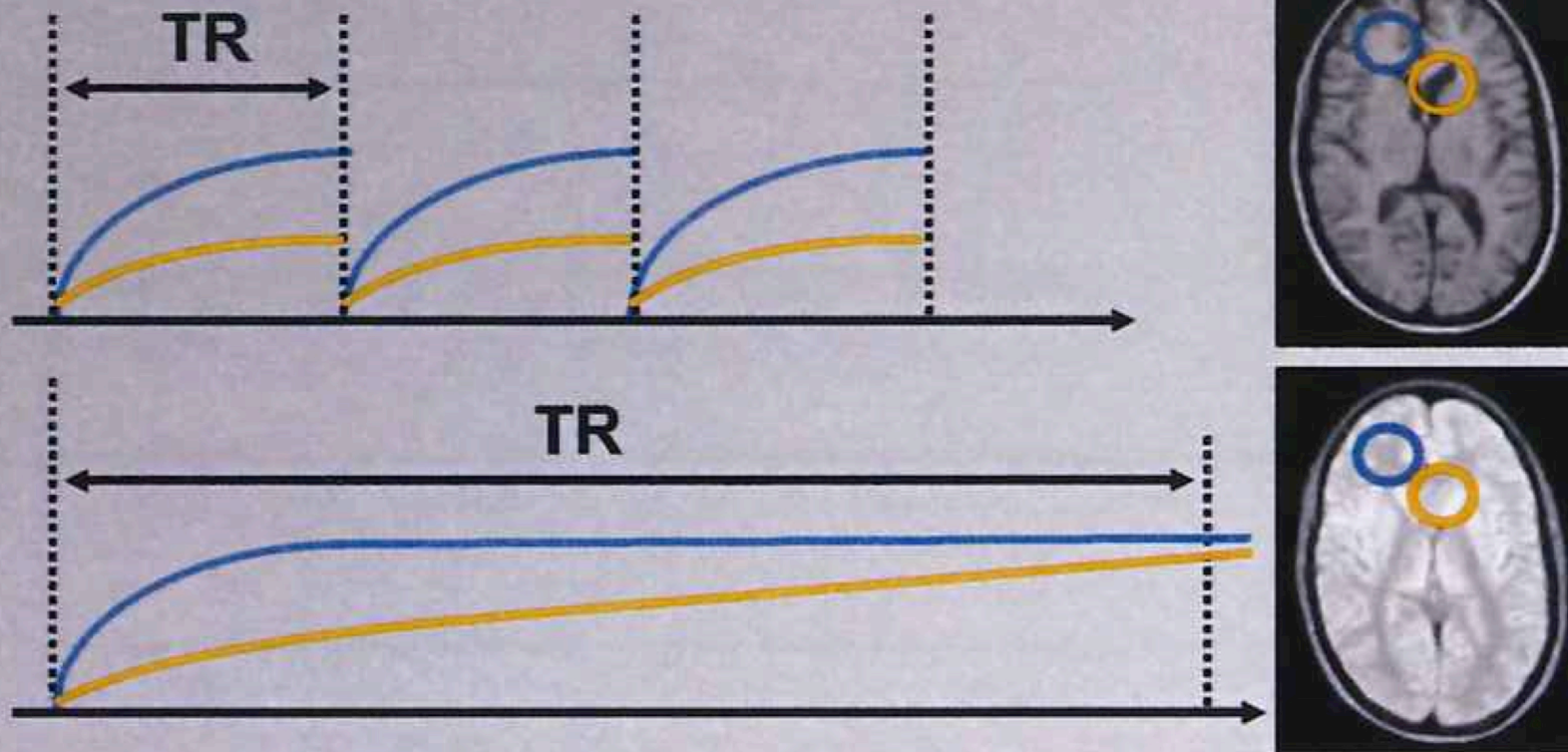




## Olika TR

Effekten av lång och kort TR

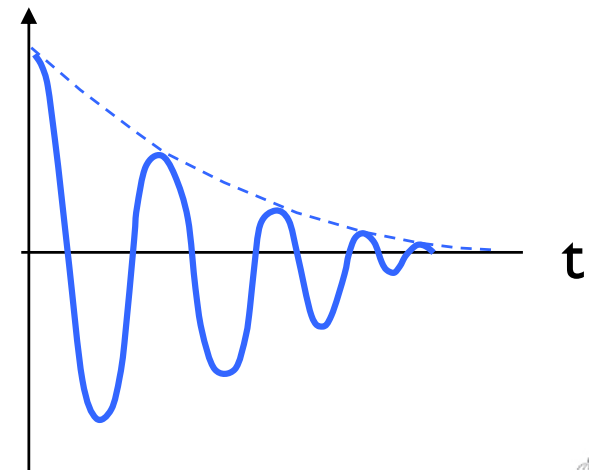
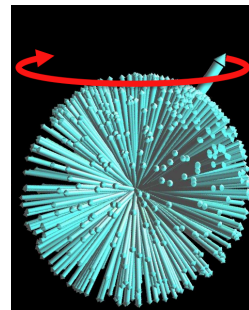
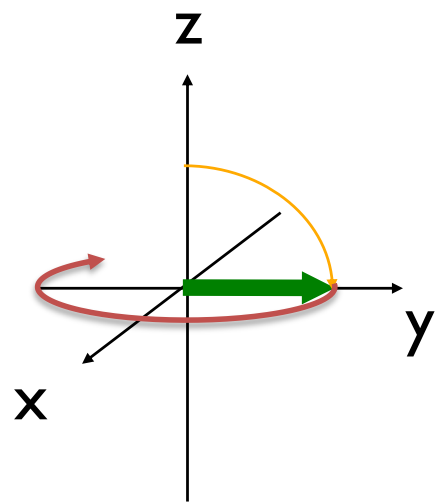
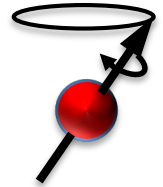
SIEMENS



Kort TR trycker ner magnetiseringen från vävnader med lång T1 så att vävnader med kort T1 får starkare signal relativt sätt  
Lång TR gör att magnetiseringen från alla vävnader hinner återhämta sig

# Summary, nuclear magnetic resonance

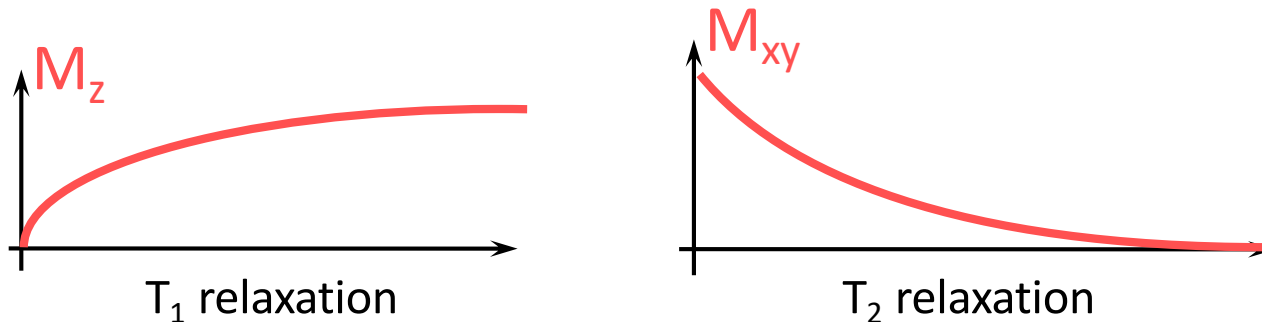
- Spins precess with a Larmor frequency proportional to external field
- Net magnetization vector can be flipped into the transverse plane  $M_{xy}$
- The precessing net magnetization vector in  $M_{xy}$  induces current in a loop



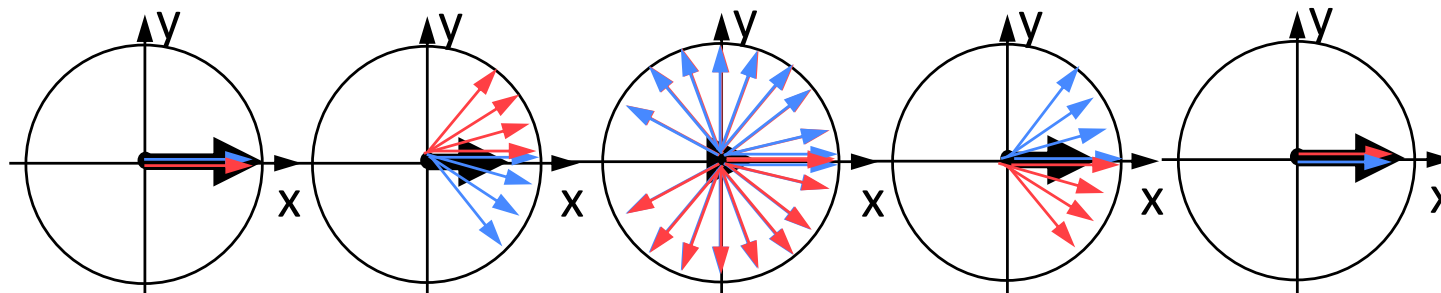


# Summary, relaxation

- The longitudinal magnetization  $M_z$  returns to equilibrium;  $T_1$  relaxation
- The transverse component dephases due to inhomogeneities;  $T_2$  relaxation

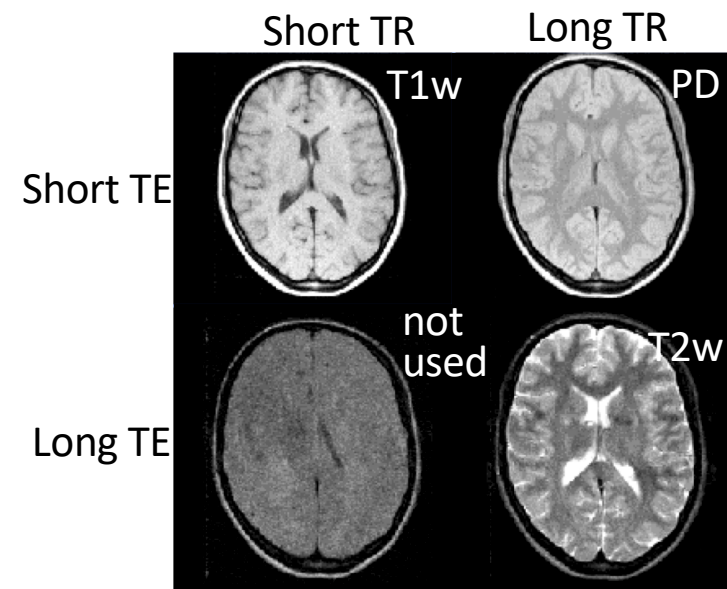
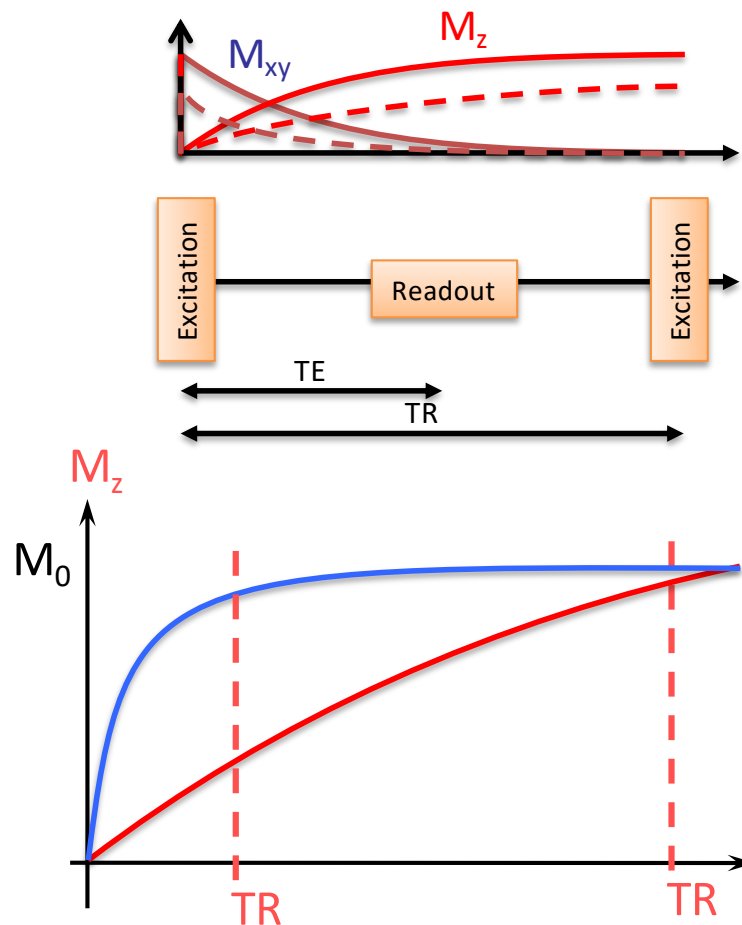


- Using spin-echo, a 180 degree refocusing pulse can recover static inhomogeneities



# Summary, image contrast

- By choosing TE and TR appropriately, a desired image contrast can be obtained



# Part II

[karolinska-cmr.com](http://karolinska-cmr.com)

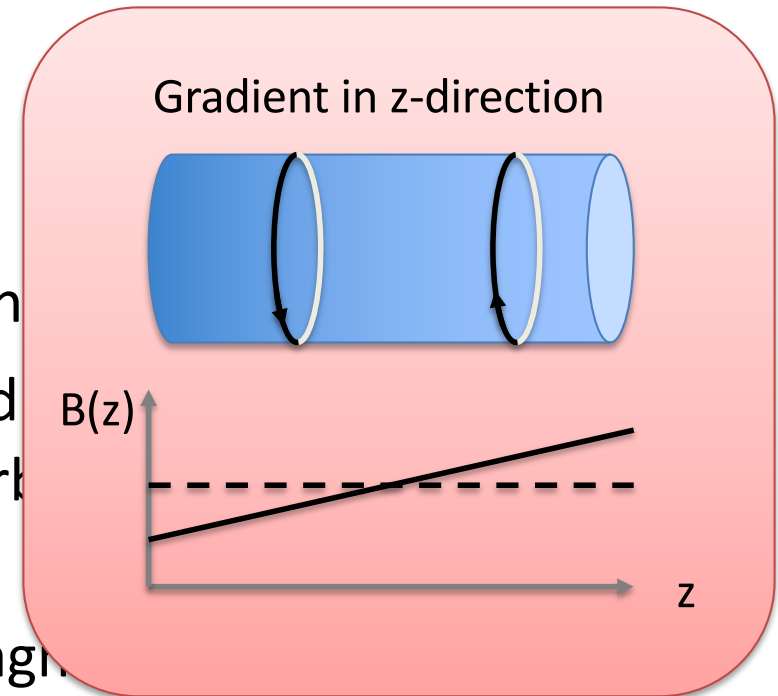


# Recap

- Static magnetic field ( $B_0$ )
  - Net magnetization precesses with Larmor frequency
- Varying magnetic field with Larmor frequency ( $B_1$ , “RF pulse”)
  - Rotates the magnetization of all spins on resonance
  - Excites signal
  - Refocuses static magnetic field variations
- Sequence timing ( $TE$  and  $TR$ ) controls image contrast depending on  $T_1$  and  $T_2$  relaxation
- Spatial localization??

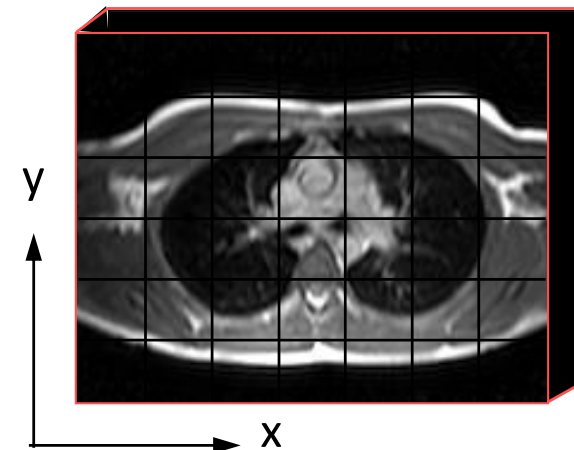
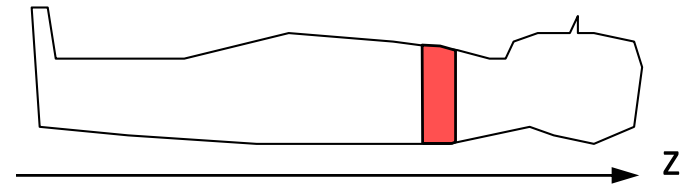
# Magnetic field gradients

- Using coils, an additional magnetic field can be superimposed over the  $B_0$  field
  - Field strength varies
  - Field direction *always* in z-direction
- The current can be varied in the gradient coils
  - One coil set in each direction x, y and z
  - Combined will create a gradient in any direction
- Larmor frequency is proportional to magnetic field strength
- Using gradients makes Larmor frequency vary spatially



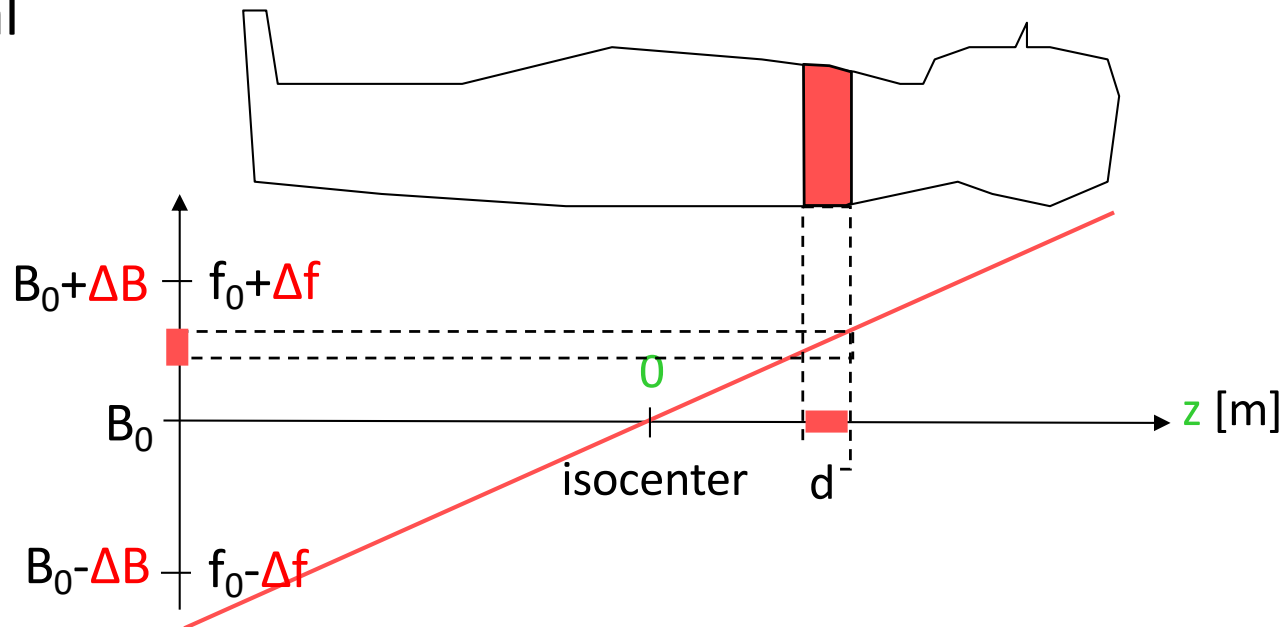
# Spatial localization of signal

- Localization is performed using both excitation and signal reception
- During excitation, only spins where Larmor frequency matches the applied pulse are excited
  - Apply excitation pulse when a gradient is on
- Only excited spins will give signal
- Signal reception with gradient on
  - Signal can be separated by frequency



# Slice selection

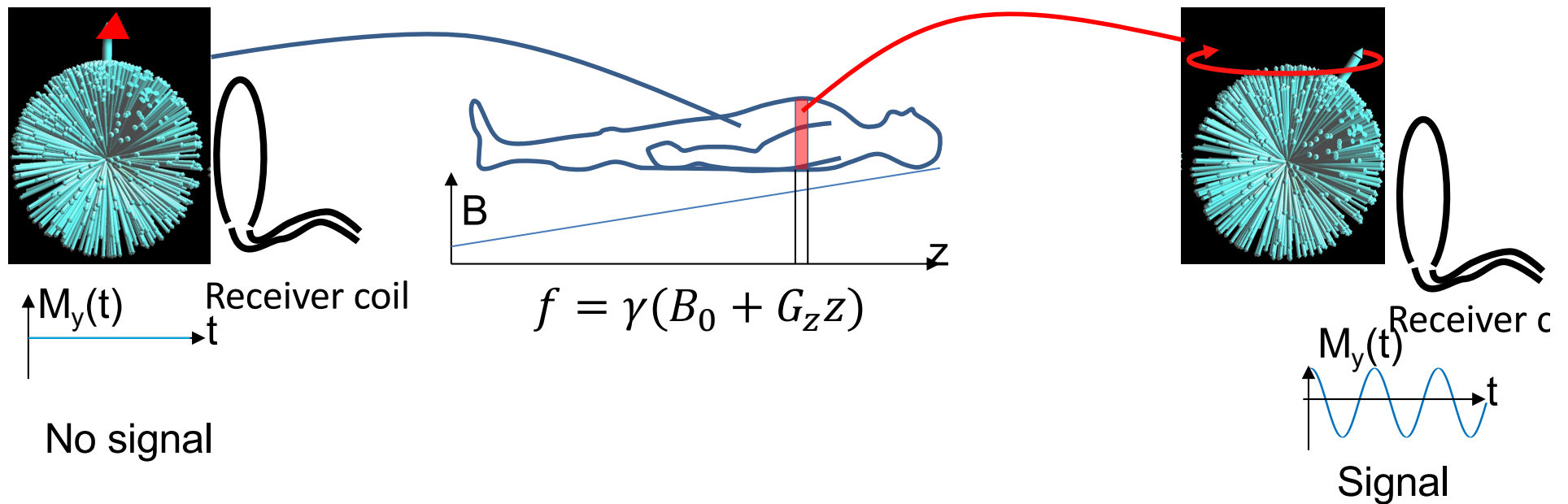
- With a gradient, the Larmor frequency varies linearly with space
- The RF pulse has a center frequency and a **bandwidth**; a span of frequencies
- Only the spins in resonance will be excited and thus provide signal



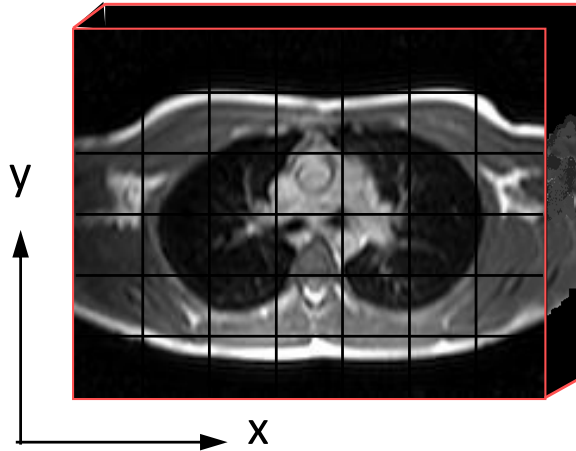


# Slice selection

- With a gradient, the Larmor frequency varies linearly with space
- Only the spins in resonance will be excited and thus provide signal



# 2D in-plane encoding

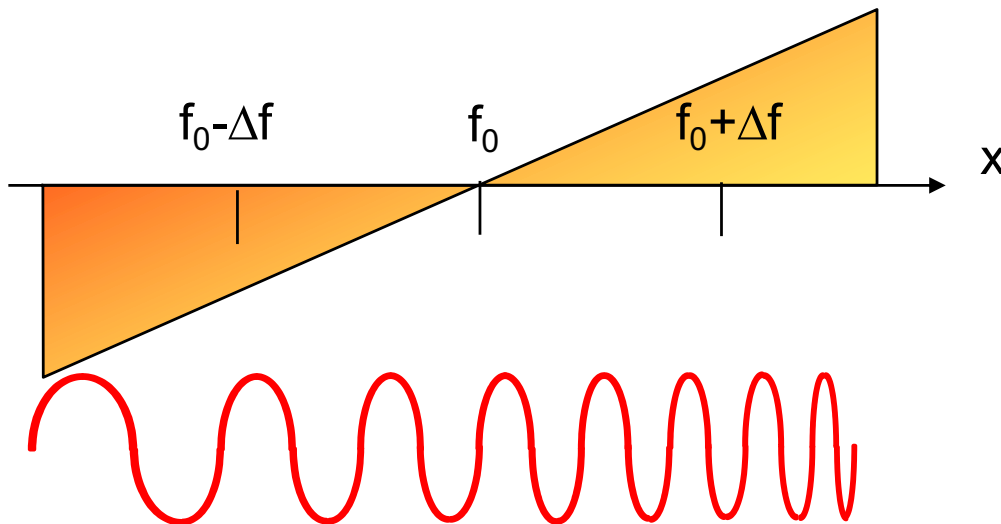


- The signal received comes from the **whole excited** volume
- We use gradients in two steps to encode the x and y directions
- **Frequency** encoding (convention: x)
- **Phase** encoding (convention: y)

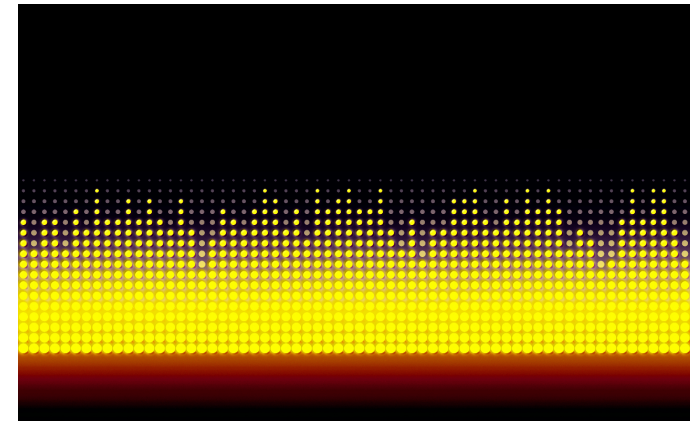
# Frequency encoding direction (x)

- A gradient is turned on during signal reception
- Signals from different positions have different **frequencies**

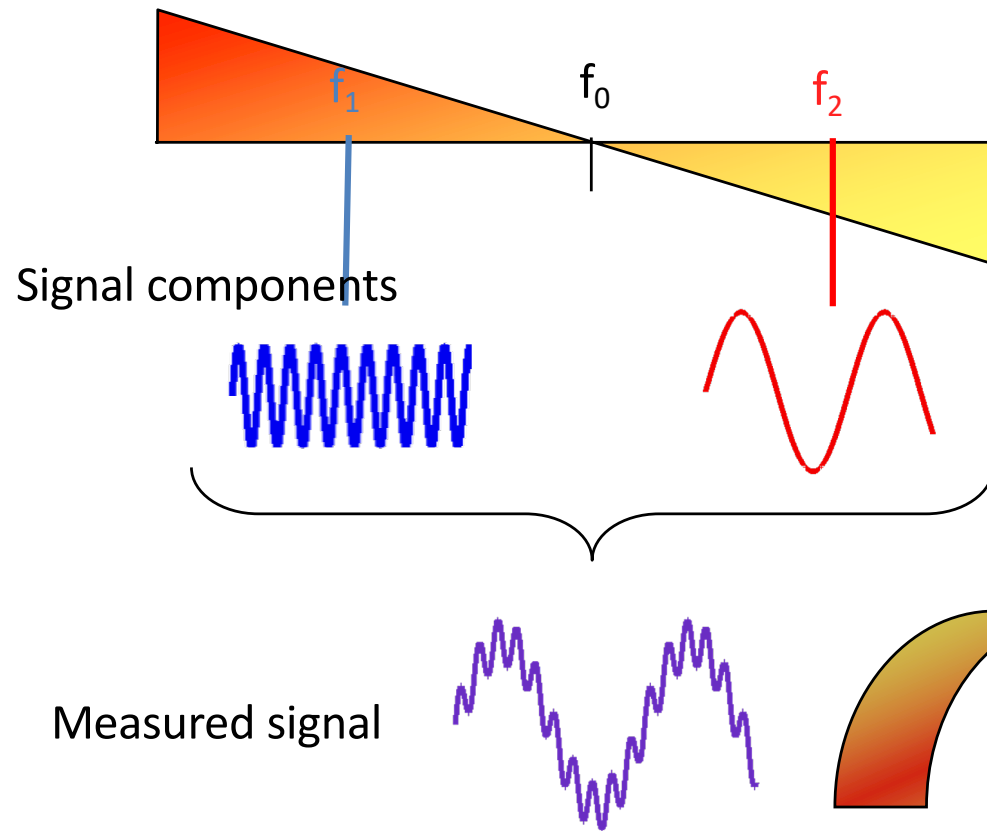
$$f = \gamma(B_0 + G_x x)$$



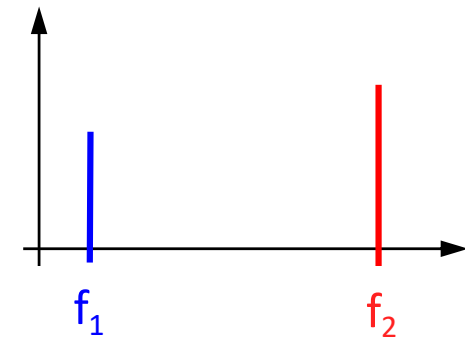
Cf: spectrum analyzer for music



# The Fourier transform



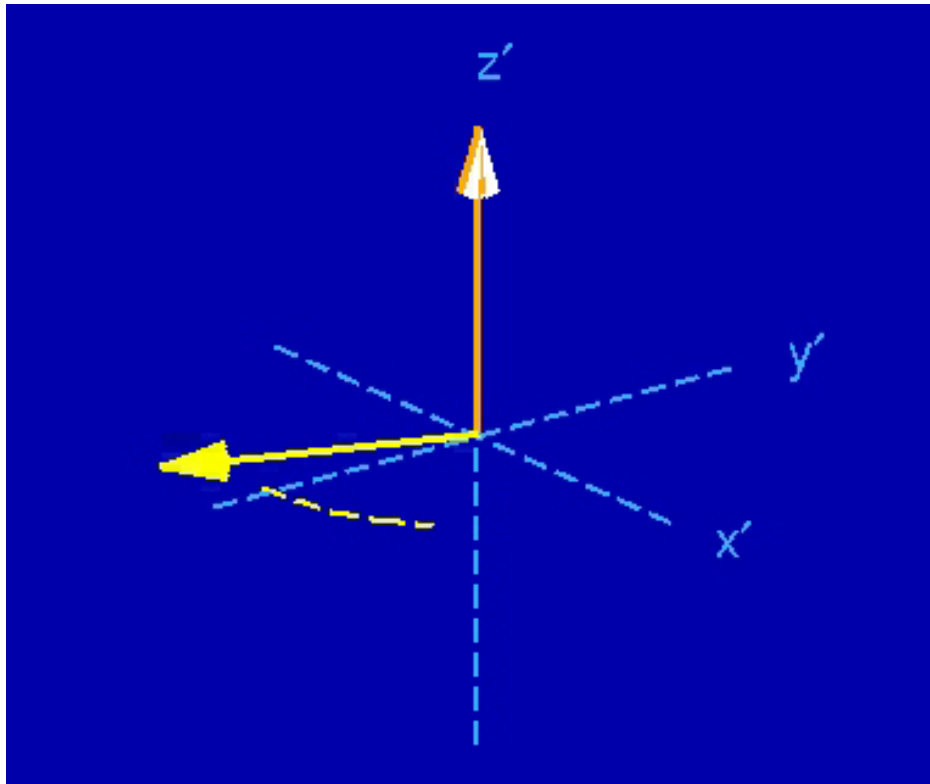
The **Fourier** transform recovers the frequencies and separates into  $f_1$  and  $f_2$



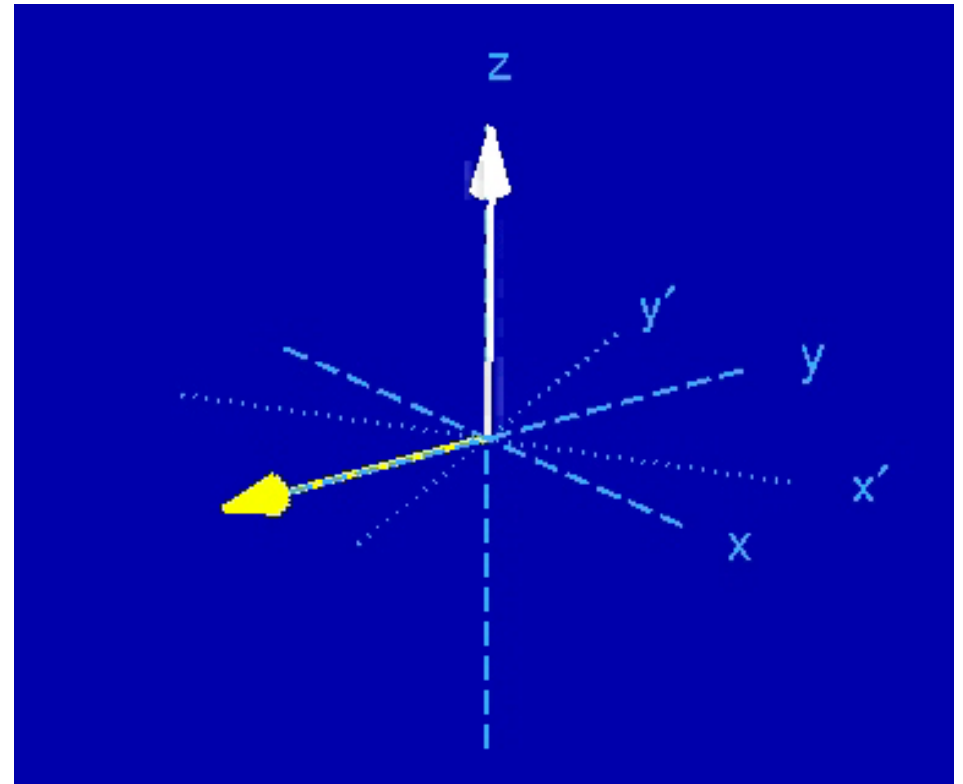
cf: Music chords



# Rotating frame of reference



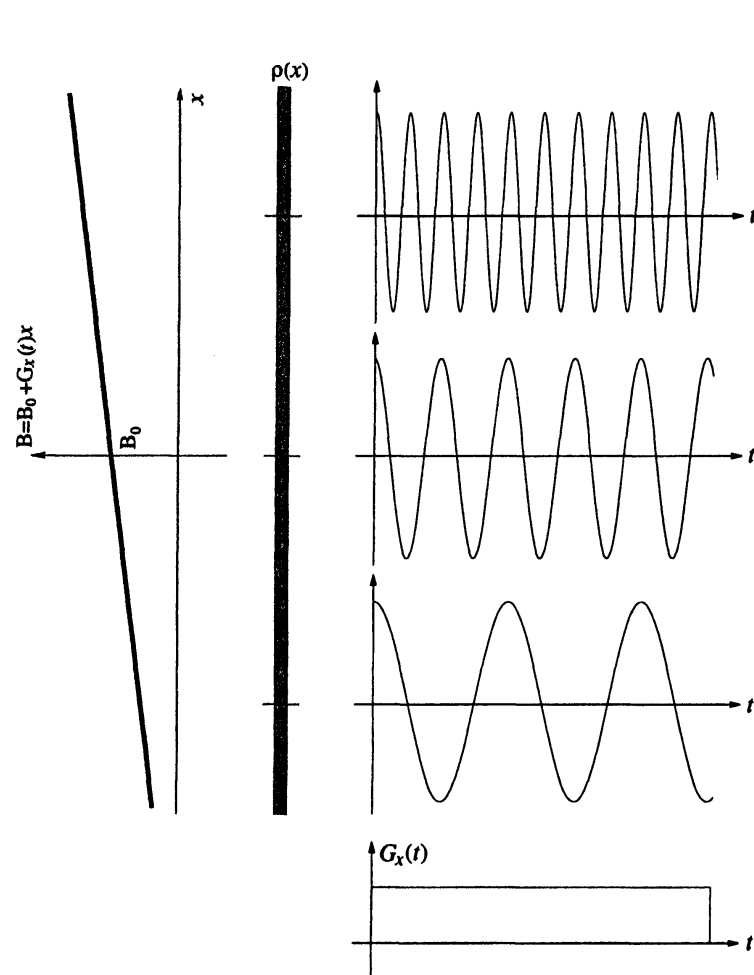
Static frame of reference



Rotating frame of reference

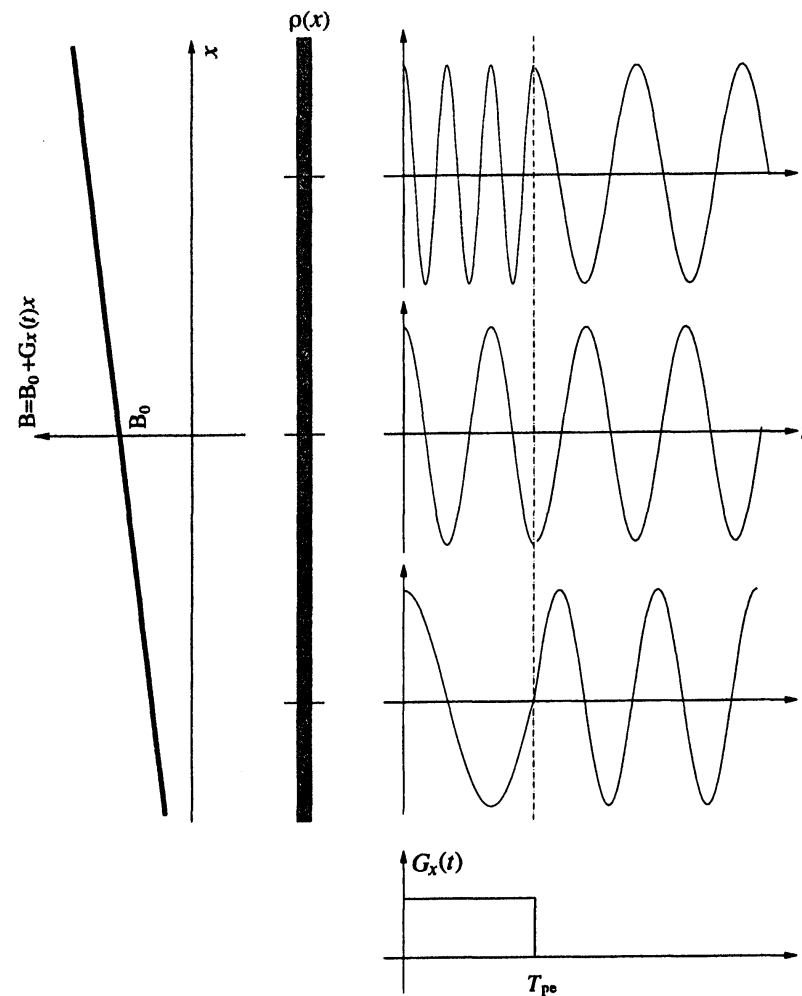
Movies from <http://mrsrl.stanford.edu/~brian/intromr/> (Brian Hargreaves)

# Frequency encoding



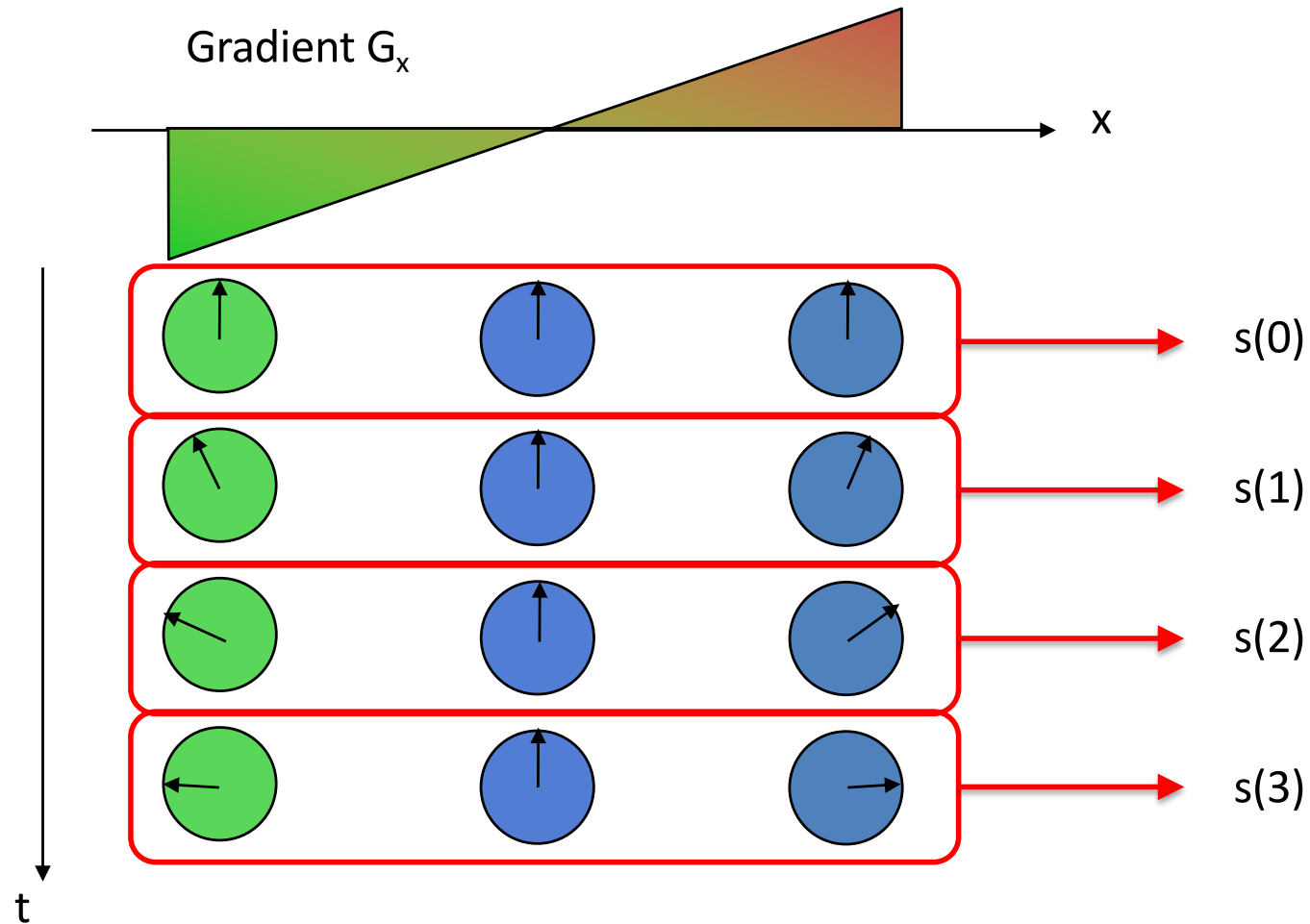
**Figure 5.7** Localized signals from a hypothetical one-dimensional object in the presence of a frequency-encoding gradient.

# Phase encoding



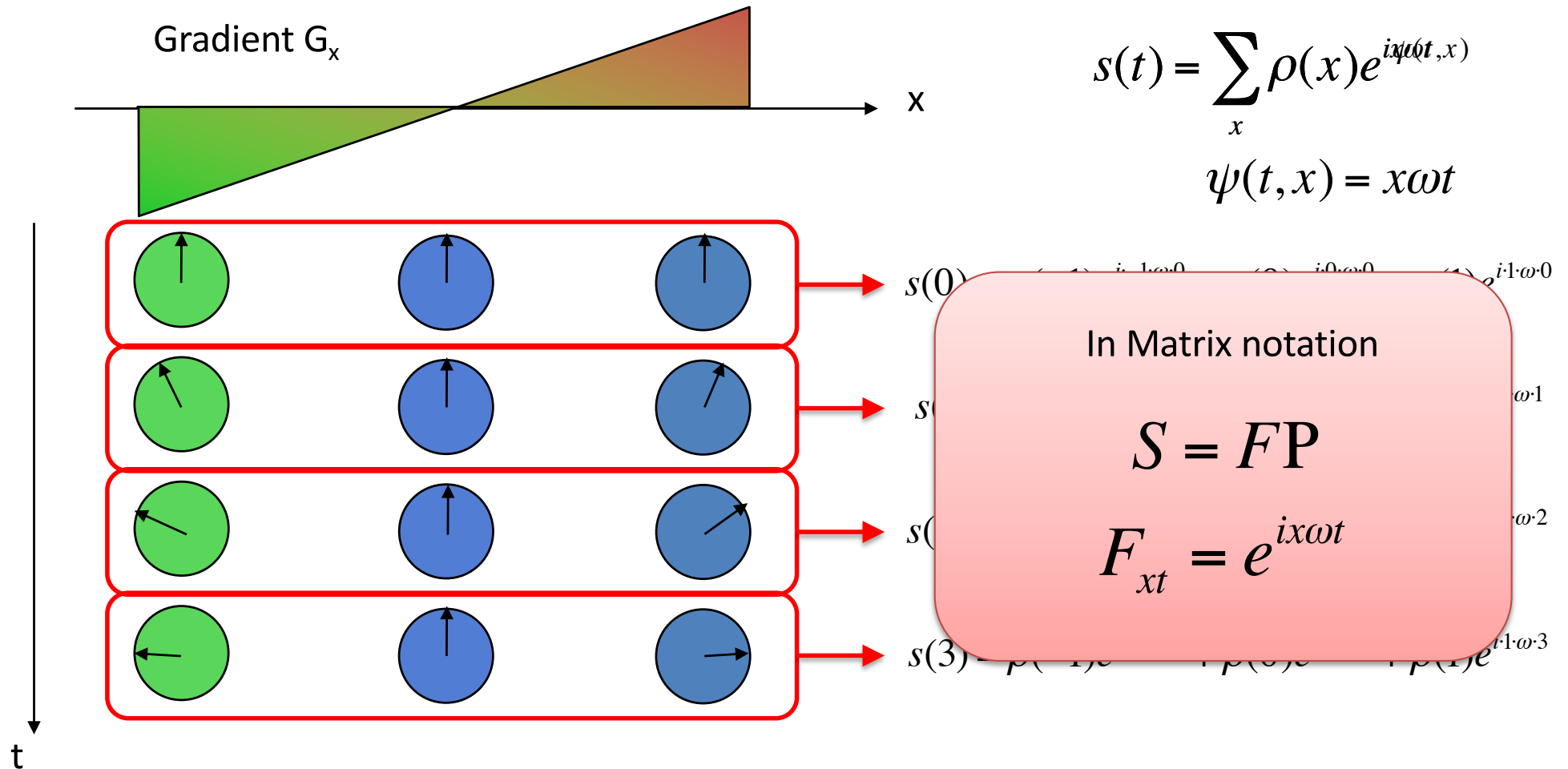
**Figure 5.9** Phase-encoded signals from a one-dimensional object. Note that phase encoding is achieved by pre-frequency encoding the signals for a short period of time  $T_{pe}$ .

# Signal in time domain

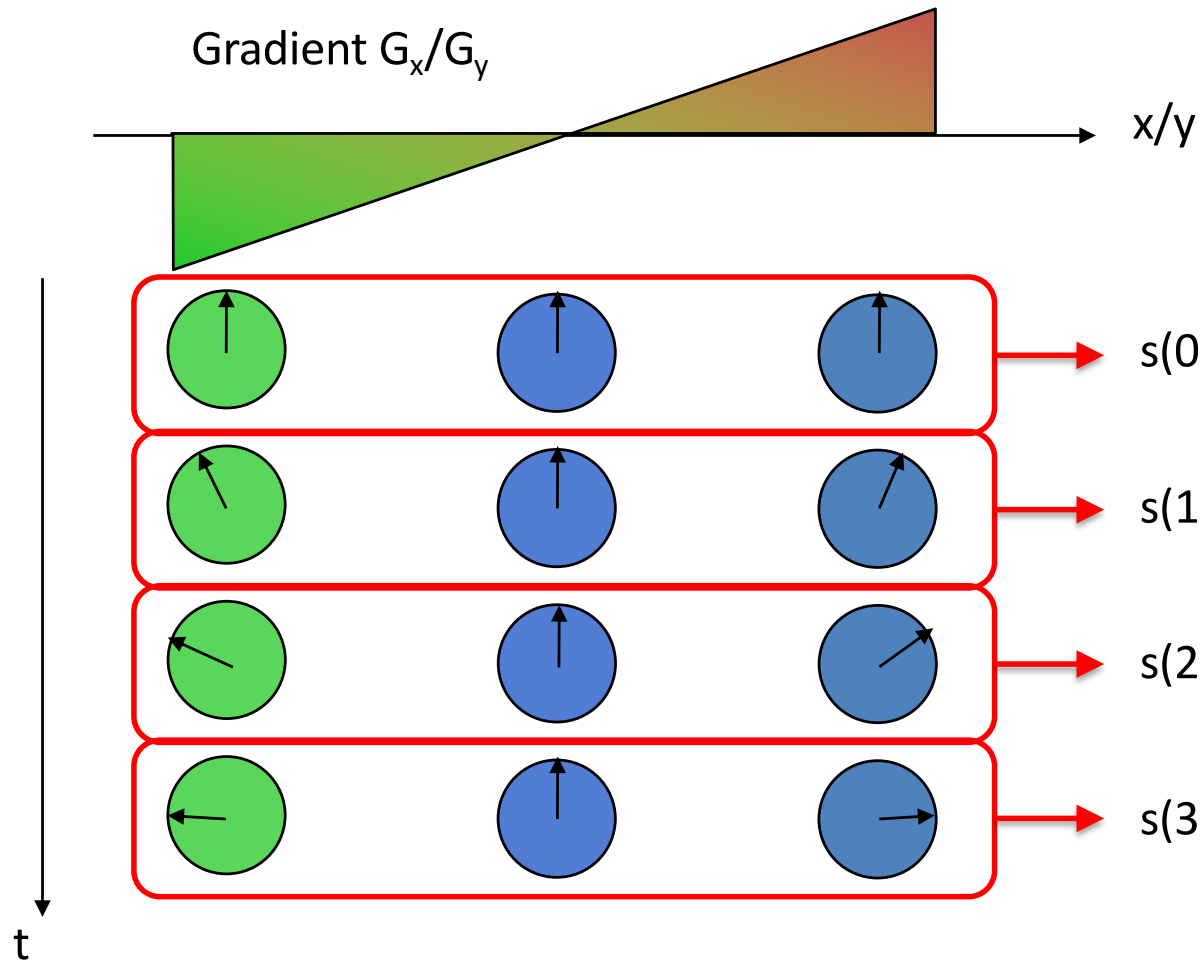




# Signal in time domain



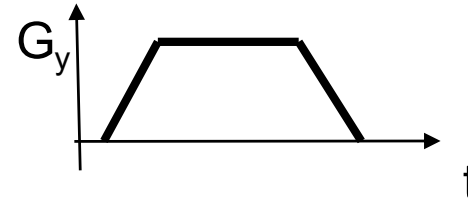
# Phase encoding



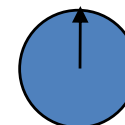
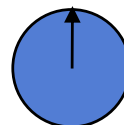
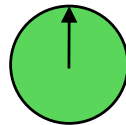
- Position is encoded in the phase of the signal
- Need all combinations to reconstruct

# Phase encoding in the y direction

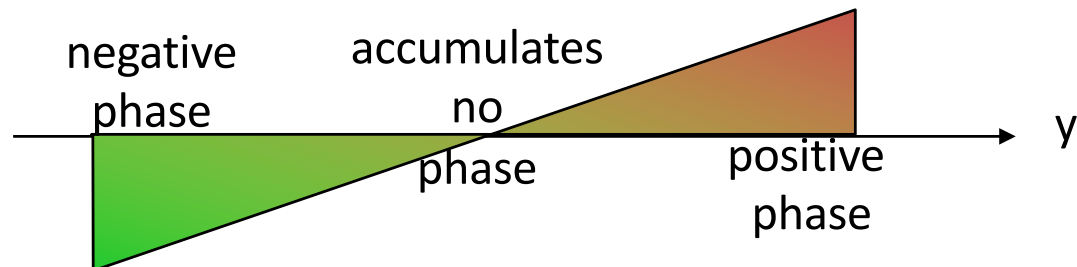
- Apply a short gradient lobe (on-off)



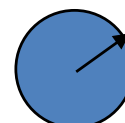
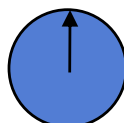
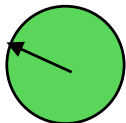
Before  $G_y$



During  $G_y$

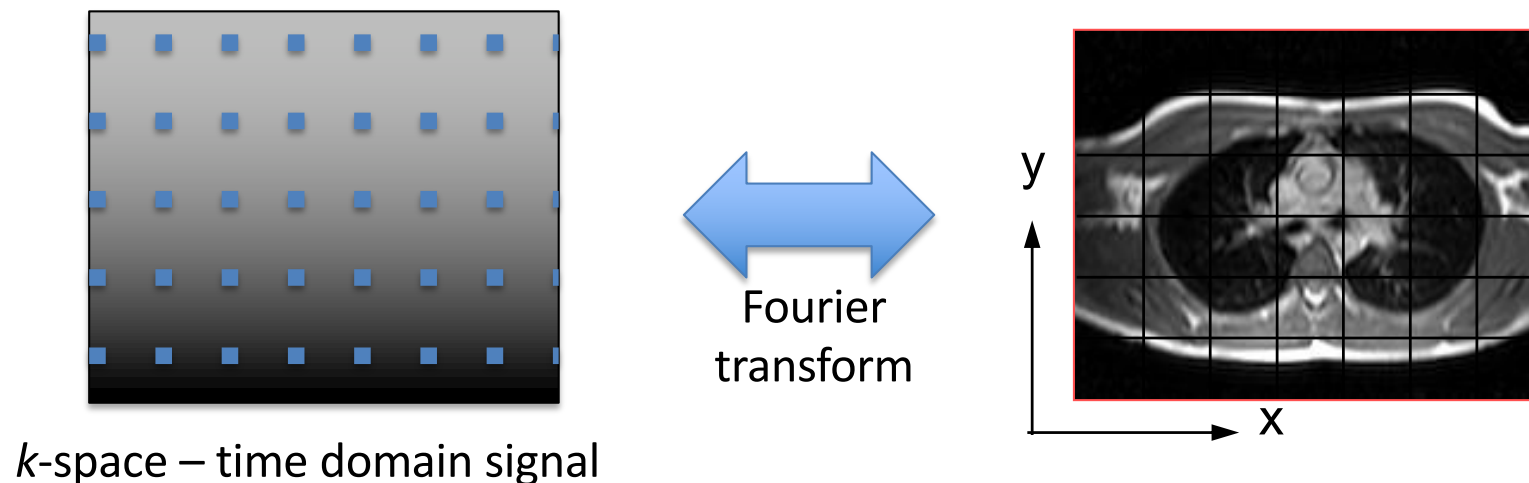


After  $G_y$



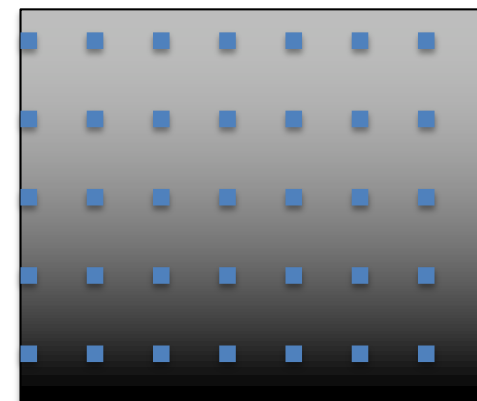
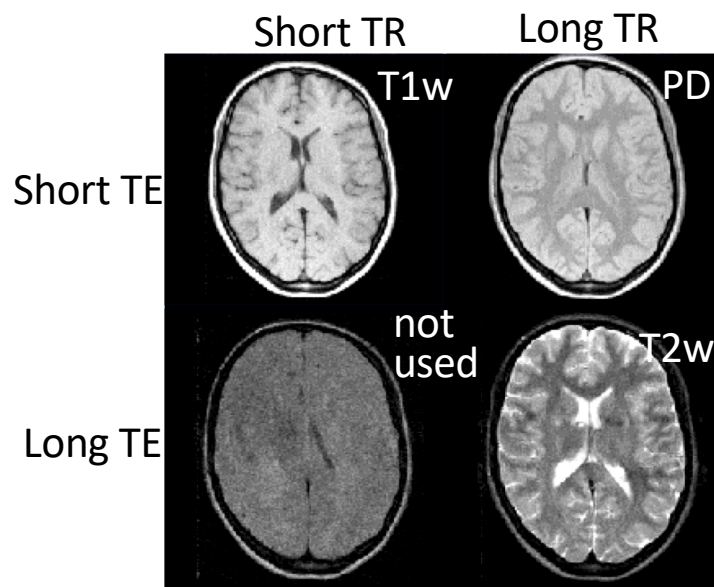
# In-plane encoding in two directions

- Need all combinations to reconstruct an  $N \times N$  pixel image
- x direction in one go (frequency encoding)
  - acquires  $N$  samples per readout
- y direction sequentially (phase encoding)
  - repeated  $N$  times, with varying strength of the  $G_y$  gradient pulse



# Scan time

- Need to collect **N** phase encodings
- Each **TR**, we can acquire **N** time domain samples (frequency encoding)
- For an image of **N x N**, the scan time becomes **N x TR**
- **TR** is chosen for the appropriate contrast
  - 256 x 256 with TR of 100 ms => 25.6 s scan time for one slice



k-space – time domain signal

# Summary

- Slice direction is encoded during excitation
  - z gradient on  $\rightarrow$  linear frequency in z-direction
  - RF pulse with suitable bandwidth excites only spins within a band of Larmor frequencies
- In-plane encoding during signal reception
  - Frequency encoding (x) direction, gradient on during readout
    - Different positions have different frequency
  - Phase encoding (y) direction, gradient lobe of varying strength before each readout
    - Different positions have different phase
  - Reconstructed using Fourier transform
- MR measures the complex-valued Fourier transform of the image

1. Vad står förkortningen MR för?

- ☐ Magnetröntgen
- ☐ Mjukdelsröntgen
- ☐ Magnetresonans

2. Från vad kommer MR-signalen?

- ☐ Från vatten
- ☐ Från alla atomkärnor
- ☐ Från väteatomkärnan

3. Vilken av följande komponenter behövs för att ta bilder med en magnetkamera?

- ☐ En supraledande magnet
- ☐ Gradientspolar
- ☐ Ytspolar

4. Den kraftigaste kontrastmekanismen i MR bygger på skillnader i?

- ☐  $T_1$  och  $T_2$
- ☐ Protodensitet
- ☐ Resonansfrekvens

5. Frekvensen på Larmor-precessionen beror på?

- ☐ Frekvensen på RF-sändaren
- ☐  $T_1$ -relaxationen
- ☐ Magnetfältstyrkan och typ av atomkärna

6. Vilket påstående är sant?

- ☐  $T_1$ -relaxationen är alltid snabbare än  $T_2$ -relaxationen
- ☐  $T_2^*$  är alltid kortare än  $T_2$
- ☐ Efter excitering avklingar signalen på grund av  $T_1$ -relaxationen

7. Gradienter används för?

- ☐ Frekvenskodning och faskodning
- ☐ Snittselektion

8. Vilket påstående om MR-signalen är sant?

- ☐ Bara magnetisering i samma riktning som huvudmagnetfältet kan detekteras
- ☐ MR-signalen är proportionell mot nettomagnetiseringen ( $M_0$ )
- ☐ Bara magnetisering i transversalplanet (xy-planet) kan detekteras

9. Vilket påstående är sant?

- ☐ Signalen innehåller bidrag från hela den valda skivan
- ☐ Intensiteten i en bildpixel är densamma som motsvarande pixel i  $k$ -space
- ☐ I varje faskodningssteg kodas en rad pixlar av MR-bilden

10. En vävnad med lång  $T_1$  och lång  $T_2$  är ljus

- ☐ På en  $T_1$ -viktad bild
- ☐ På en  $T_2$ -viktad bild

# Part III

[karolinska-cmr.com](http://karolinska-cmr.com)

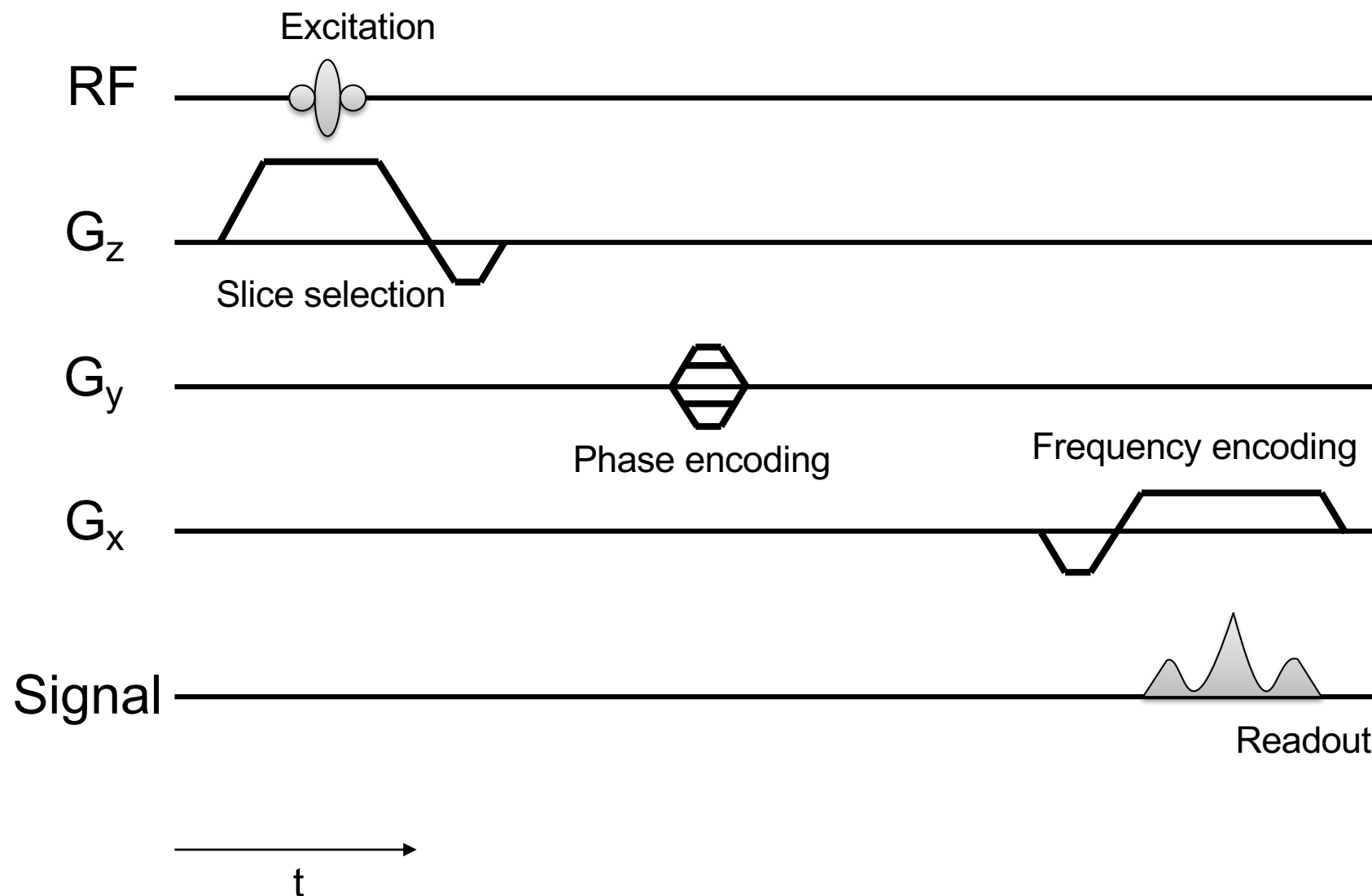




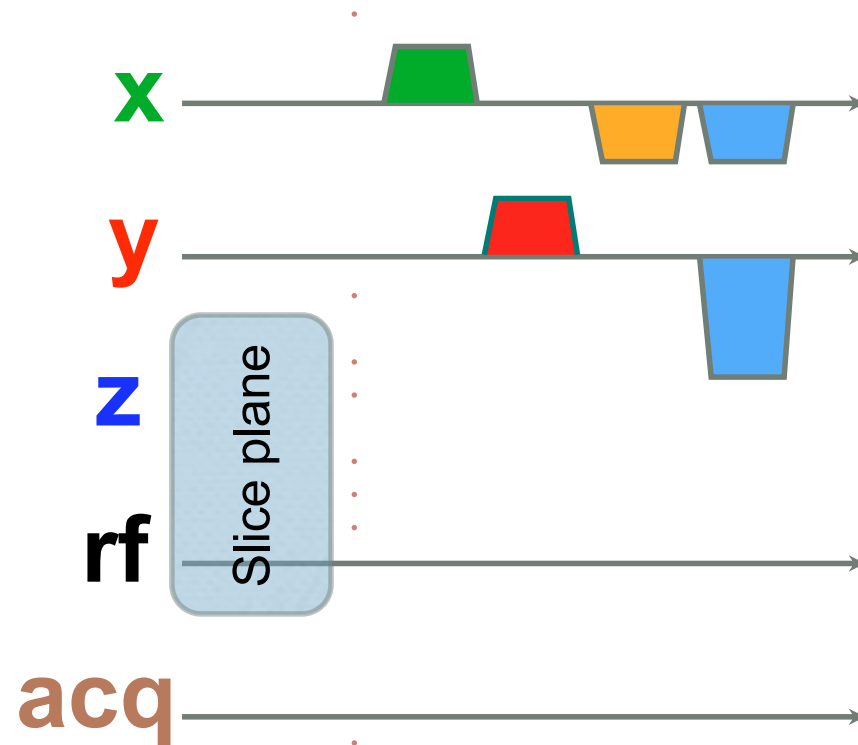
# MRI is versatile

- Means of manipulation
  - RF pulses
    - Only on-resonance spins get excited
    - Arbitrary flip angle
    - Prepulses
  - Gradients
    - Slice selection: change resonance frequency spatially
    - Spatial encoding: position gets encoded in phase
  - Time
    - Relaxation, transverse ( $T_2$ ) and longitudinal ( $T_1$ )
  - Motion
    - Phase shifts and dephasing during gradients

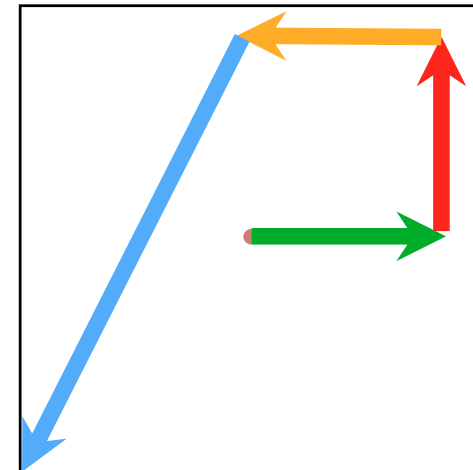
# Pulse sequences



# Gradient area & k-space

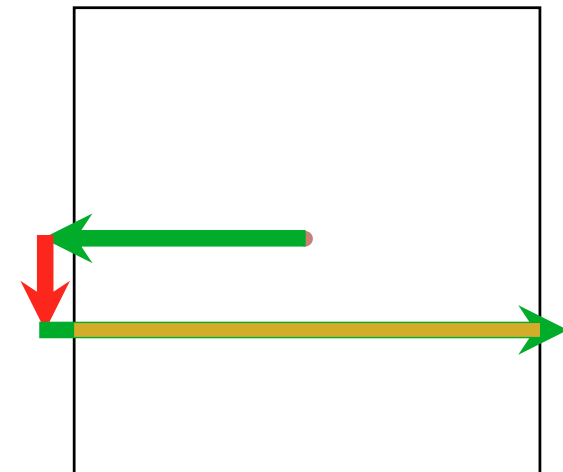
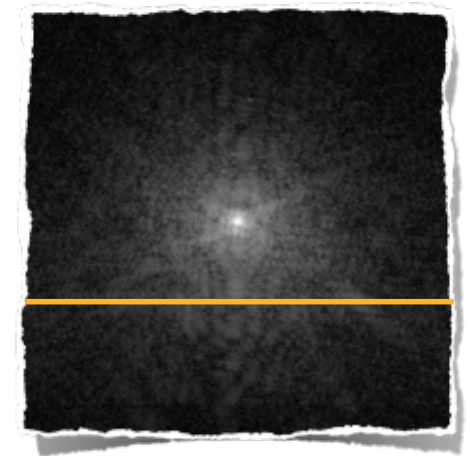
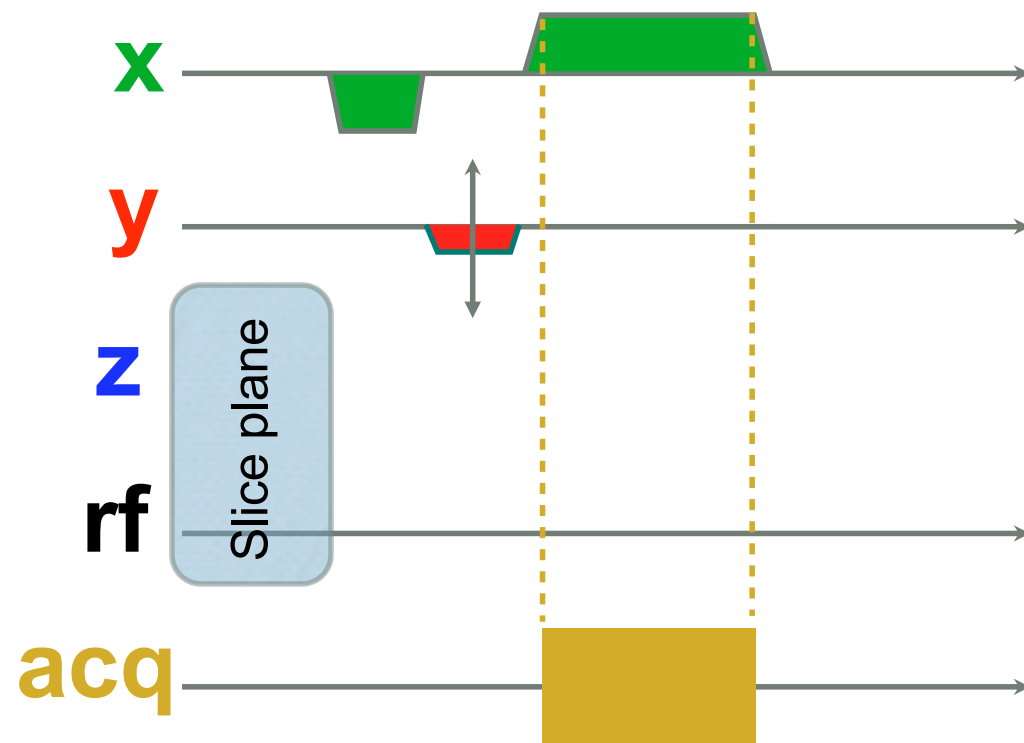


.....  
After excitation, in k-space  
center  
.....



k-space [1 / m]

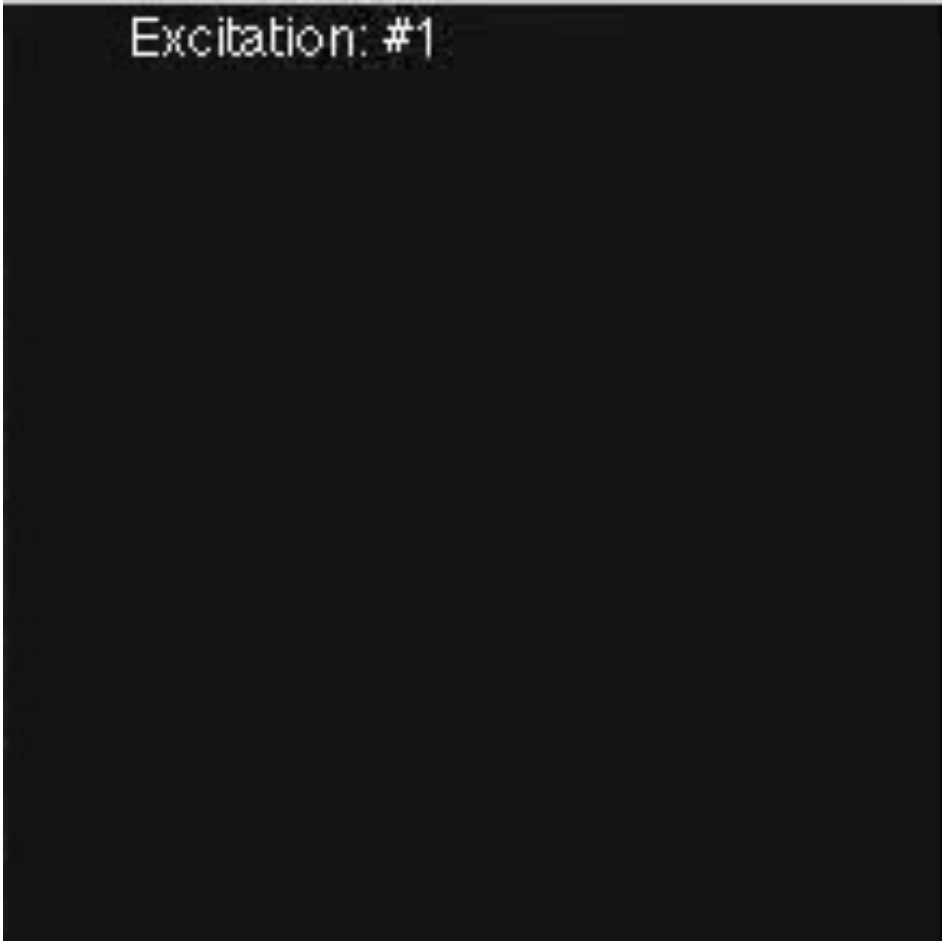
# Gradient echo



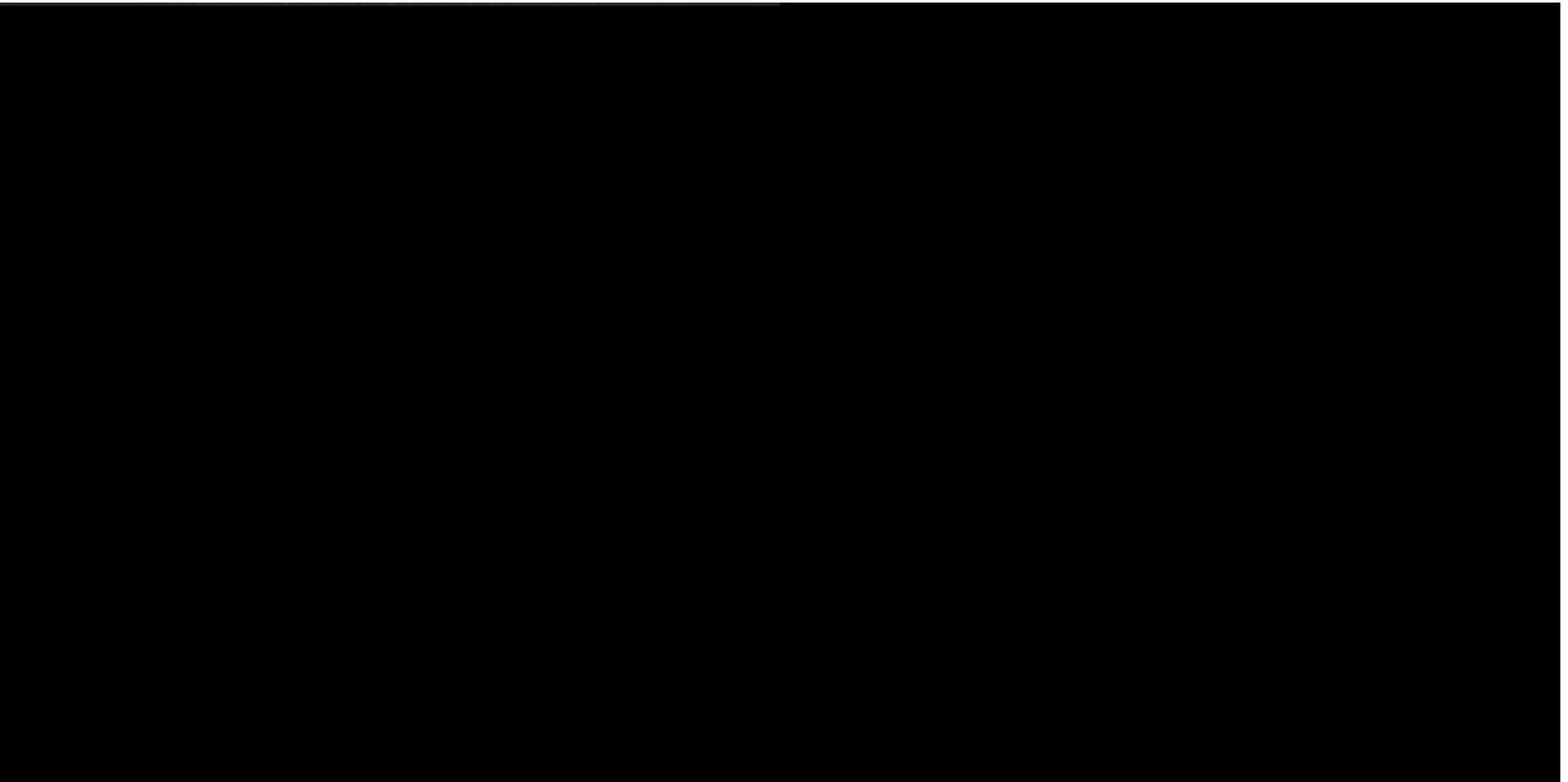
k-space [1 / m]

# Linear left-right k-space filling

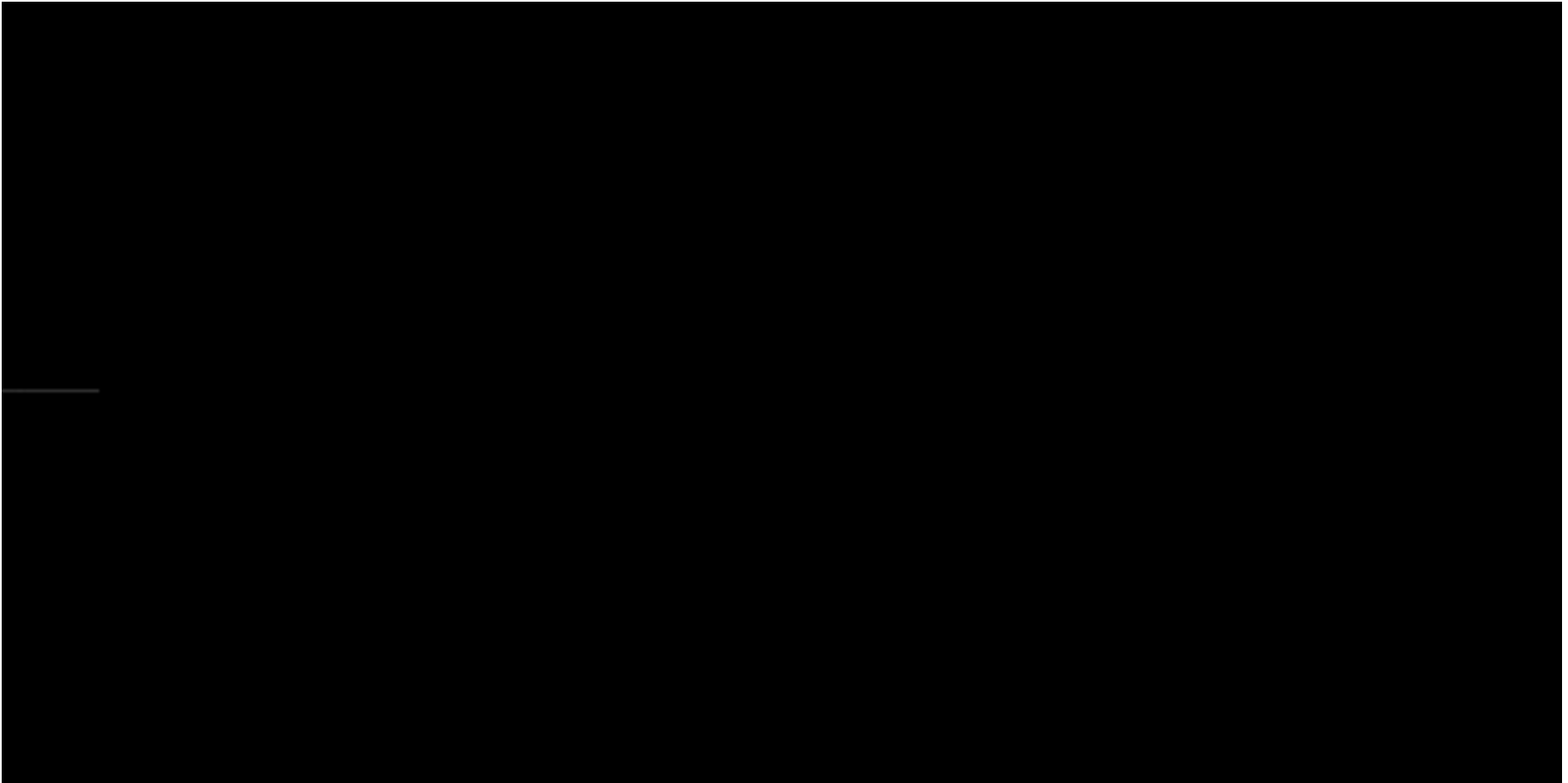
Excitation: #1



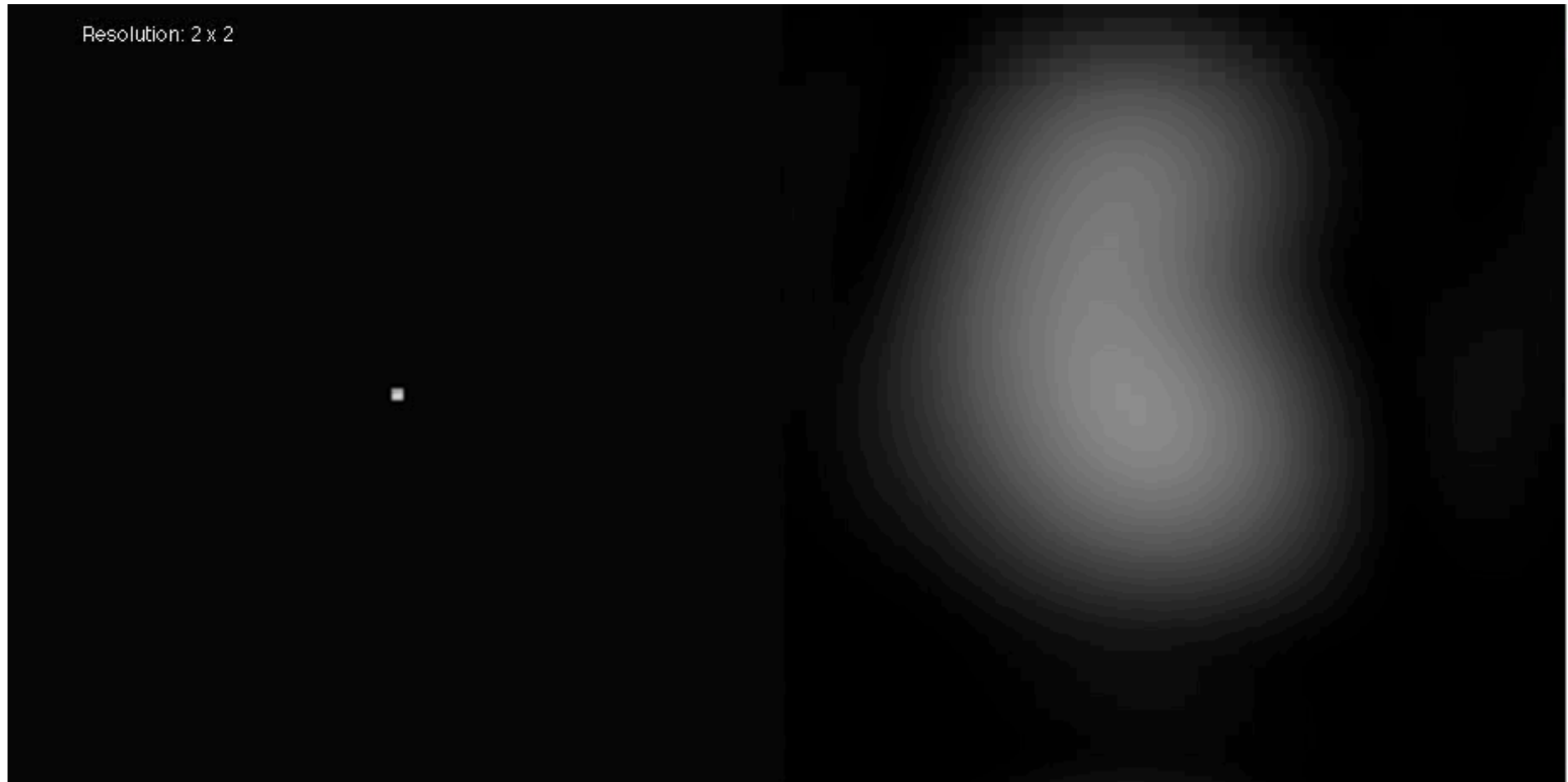
# Linear top-down k-space filling



# Center-out vertical k-space filling

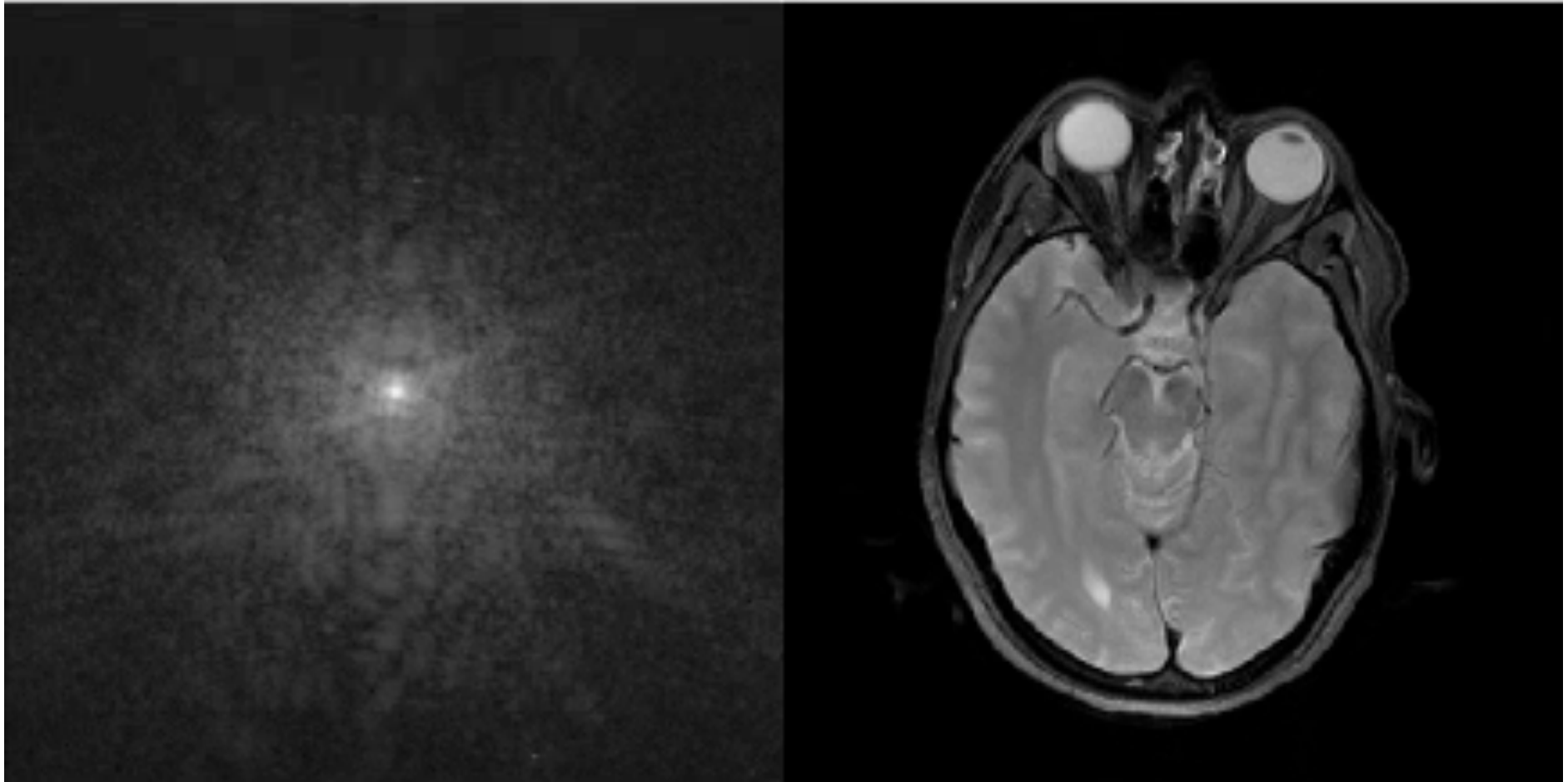


# From 2x2 to 256x256



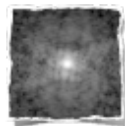


# Removal: center-out

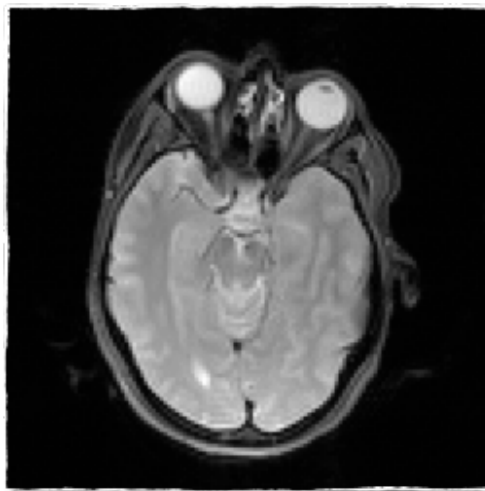
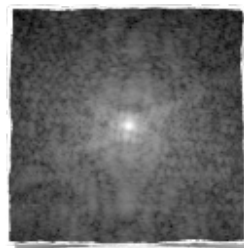


# k-space size

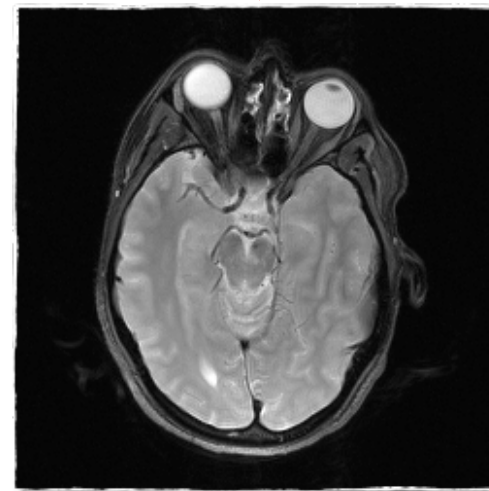
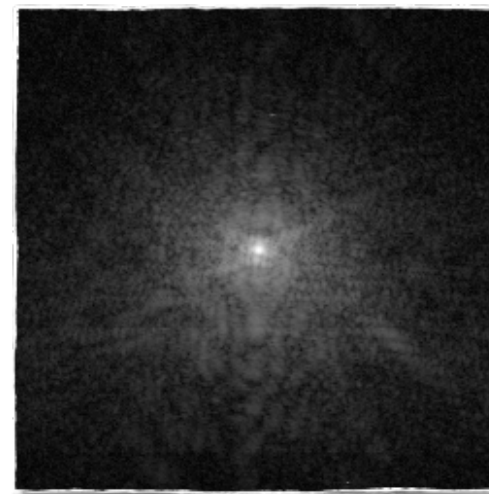
64x64



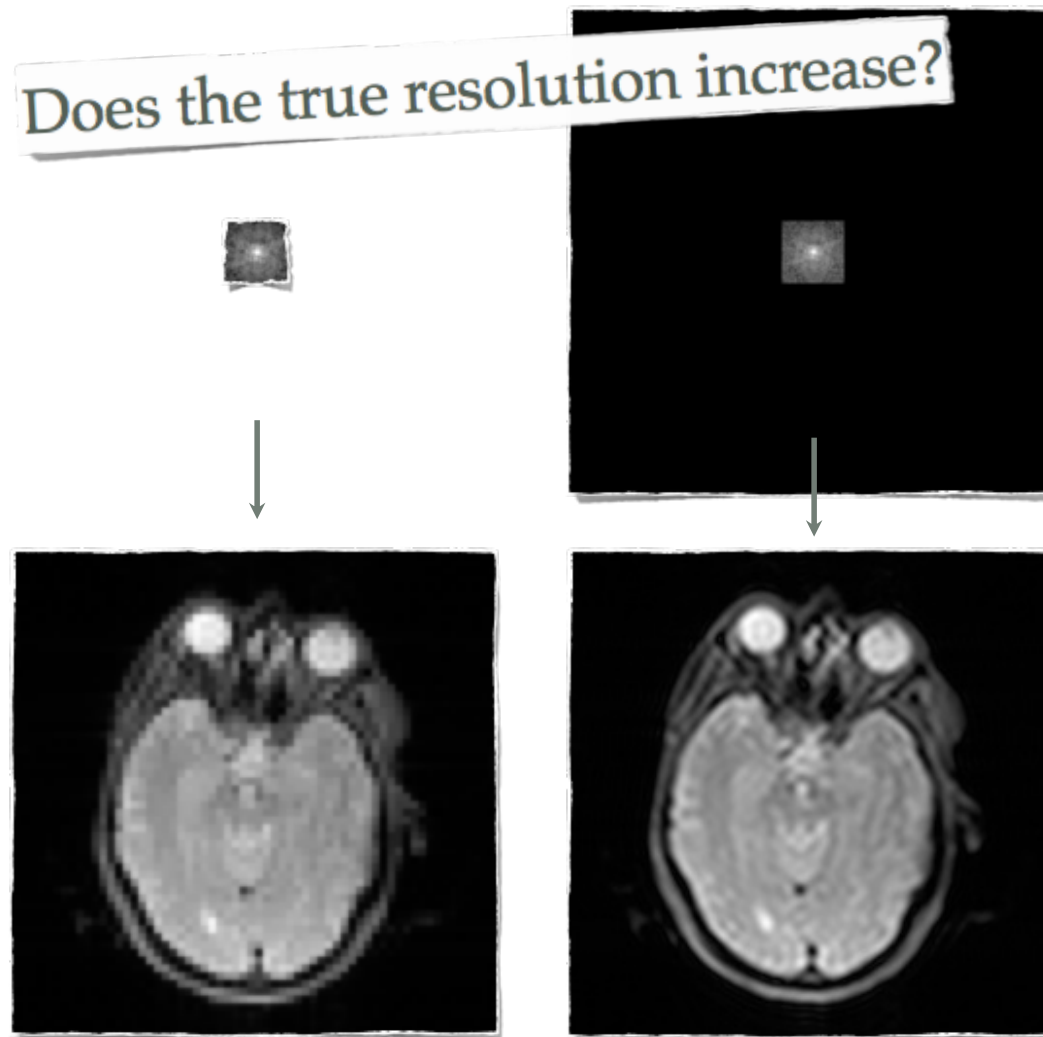
128x128



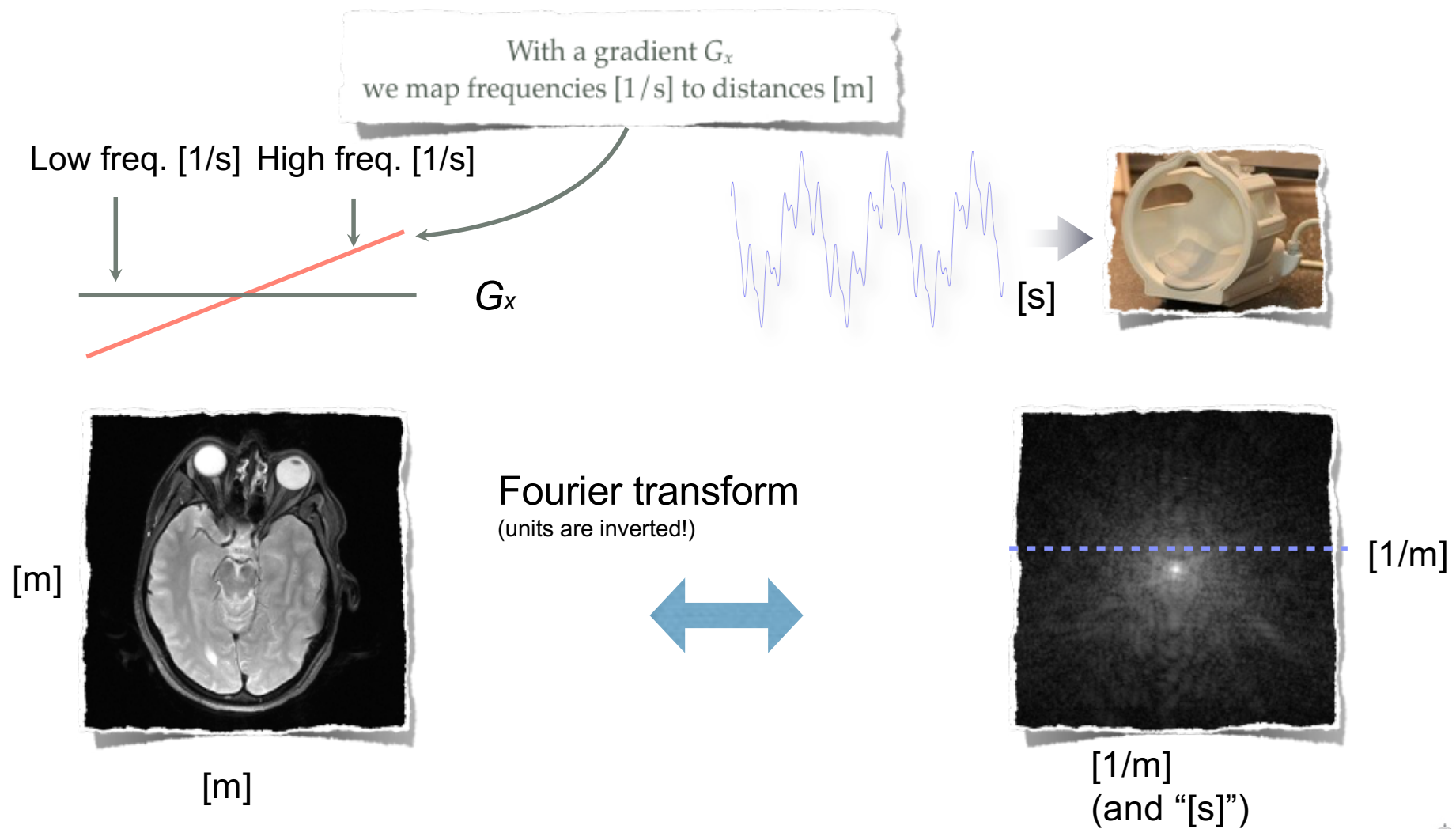
256x256



# Zero-filling $64 \times 64 \rightarrow 512 \times 512$

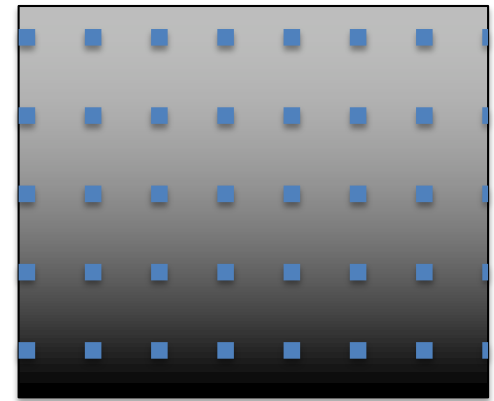


# Signal, k-space, image space



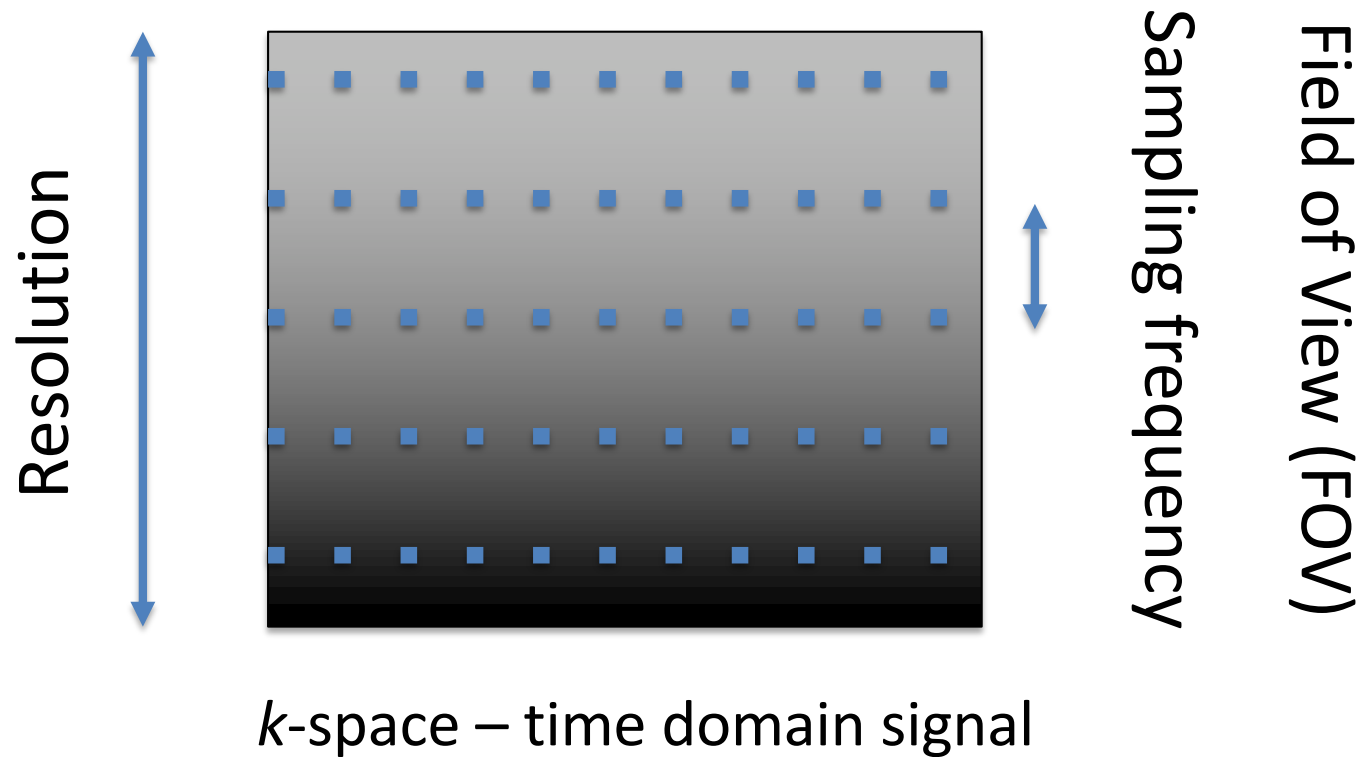
# Scan time

- 256 x 256 with TR of 100 ms => 25.6 s scan time for one slice
- Shorten scan time
  - Reduce TR
    - Changes contrast
  - Reduce number of lines in k-space
    - Reduces resolution
    - or reduces Field Of View (FOV)

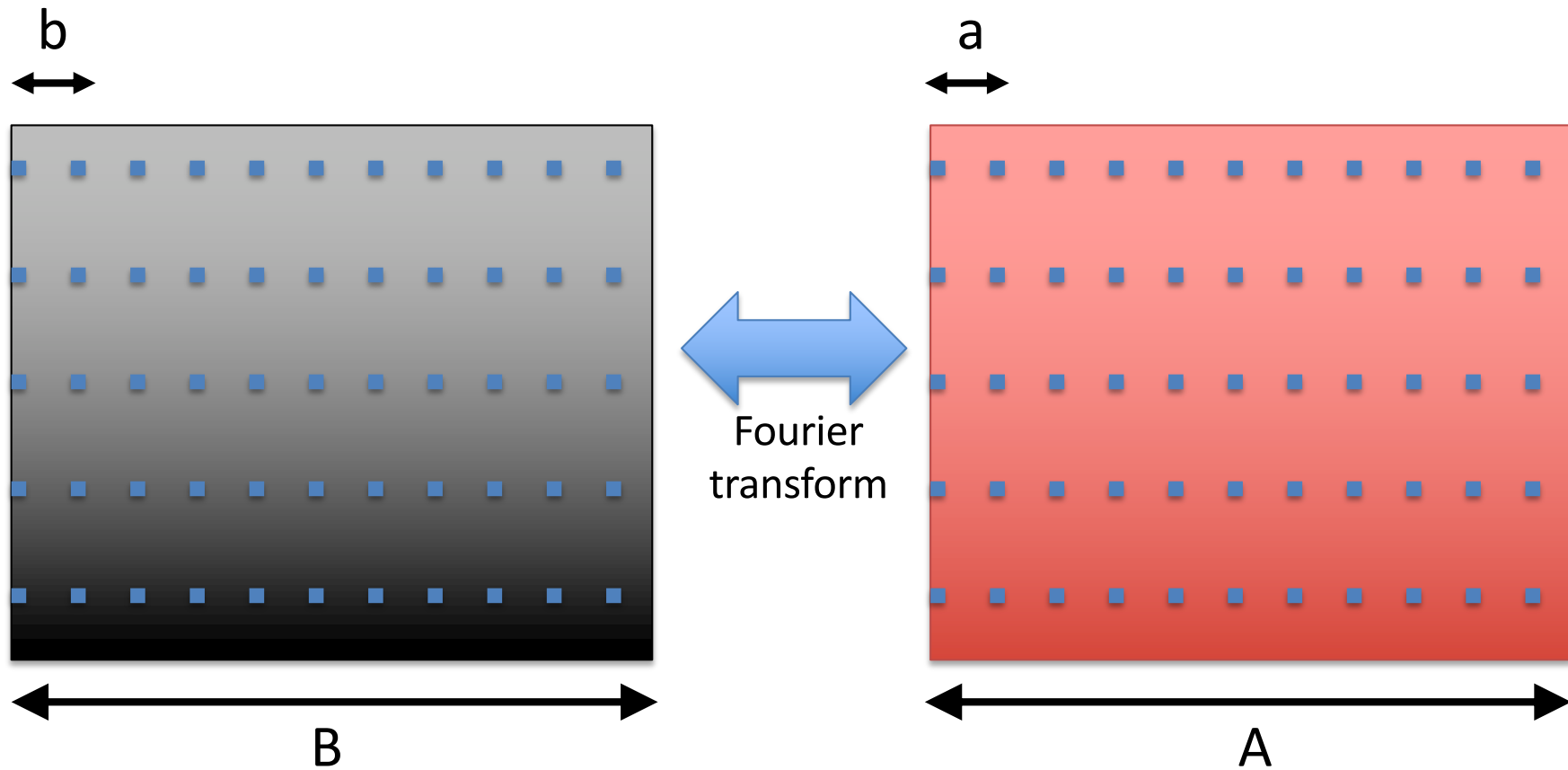


*k*-space – time domain signal

# $k$ -space matrix properties



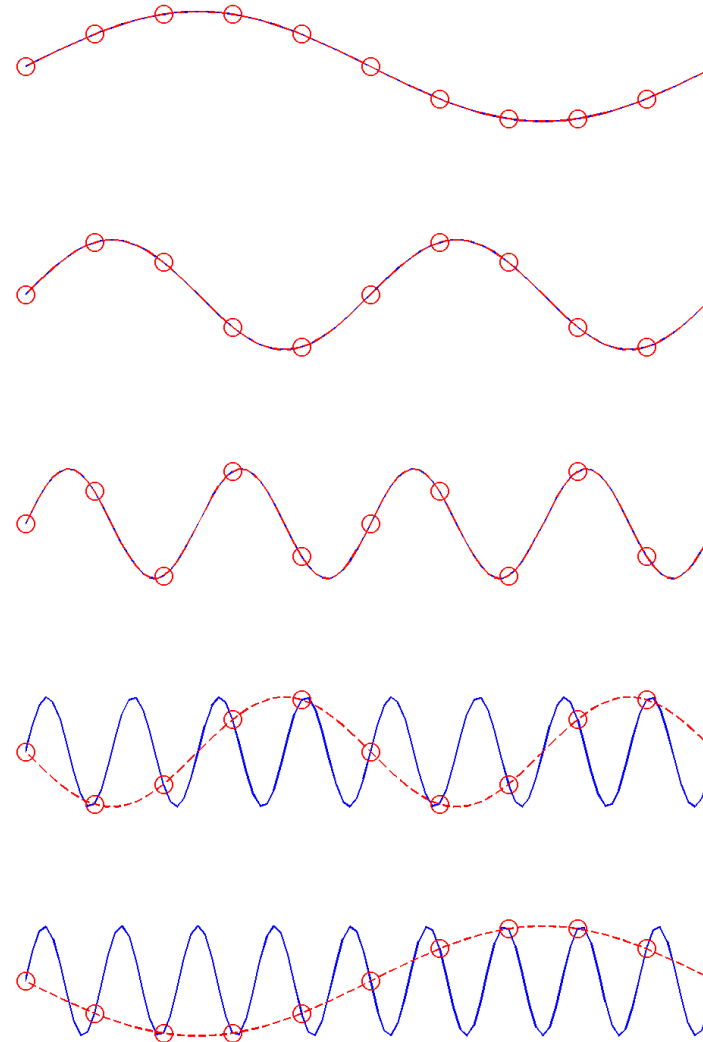
# $k$ -space relationships



$$a \sim 1 / B$$
$$b \sim 1 / A$$

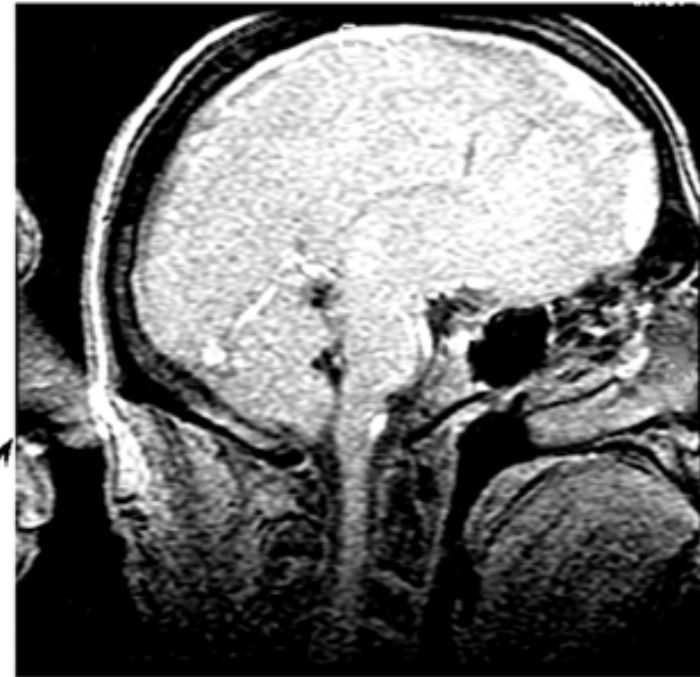
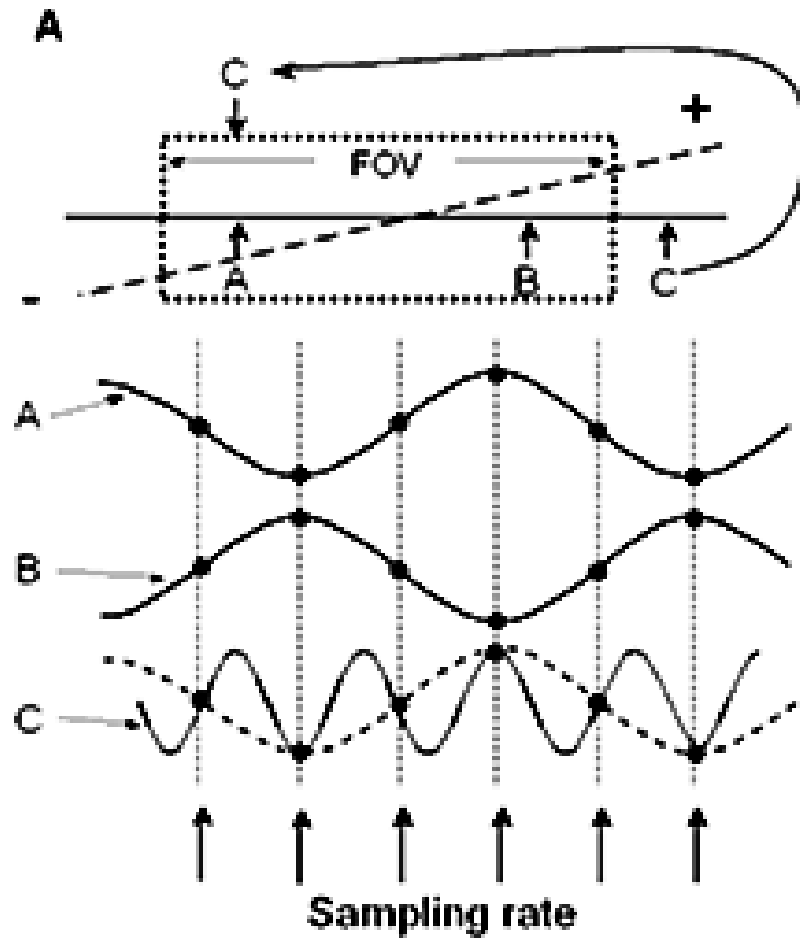
# Fold-over artifacts

- Frequency determination relies on sufficient sampling frequency
- Can only resolve up to Nyquist frequency
- Nyquist frequency is half of sampling frequency
  - Corresponds to two samples per period
- If Nyquist sampling criterion is not fulfilled “aliasing” occurs



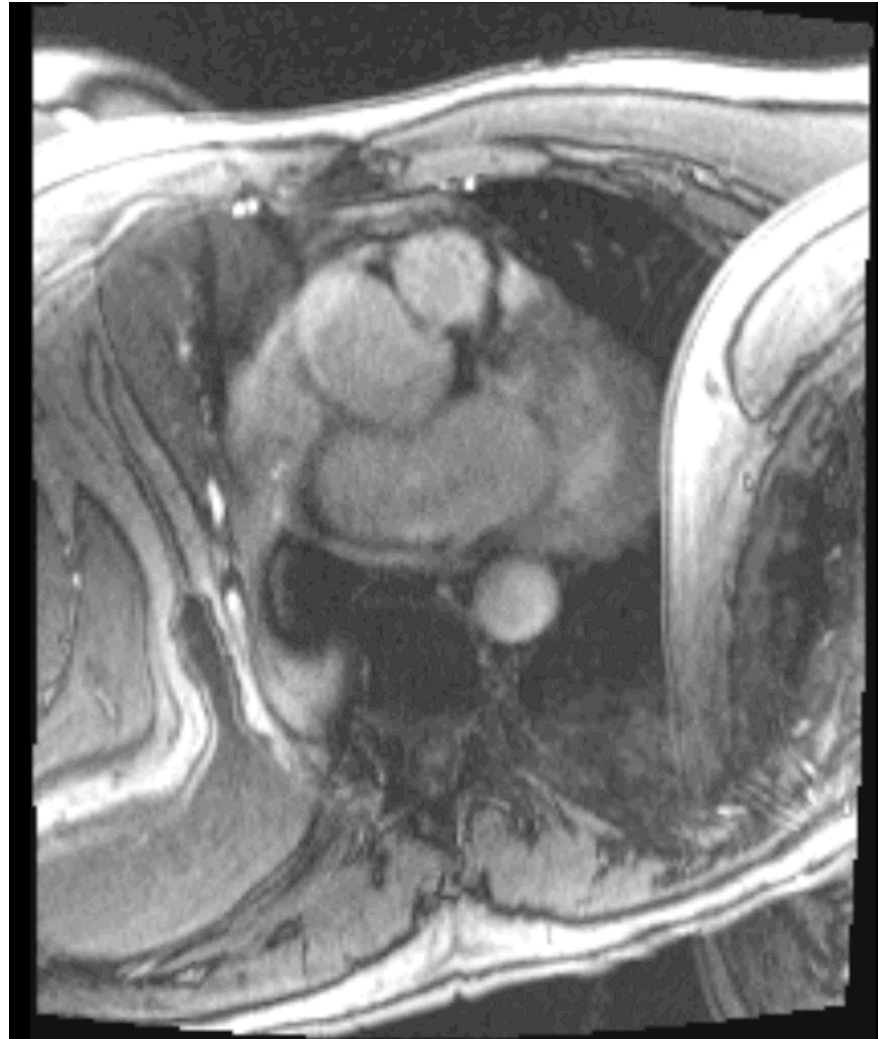


# Fold-over artifacts



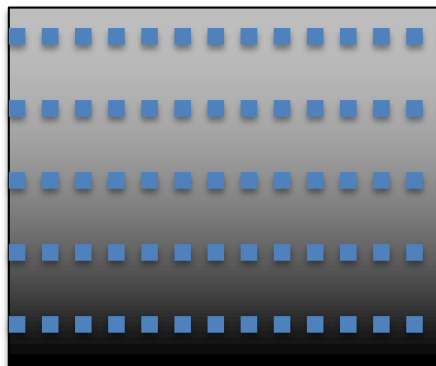
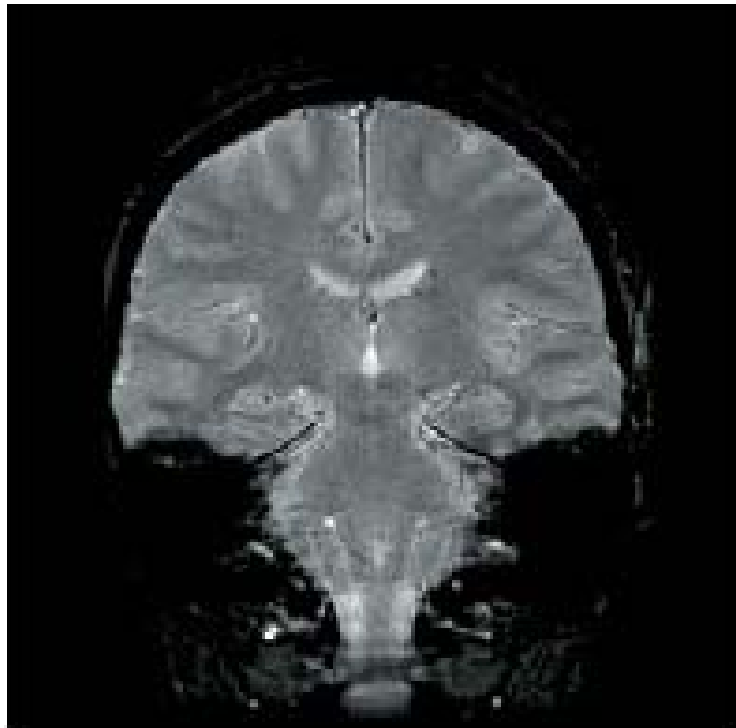
Wrap-around

# Fold-over artifacts



# Importance of readout direction

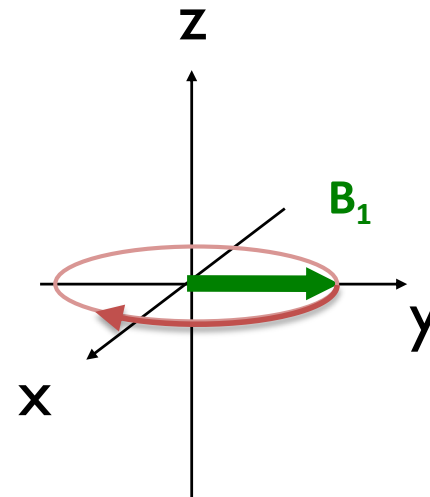
Frequency encode  
↑



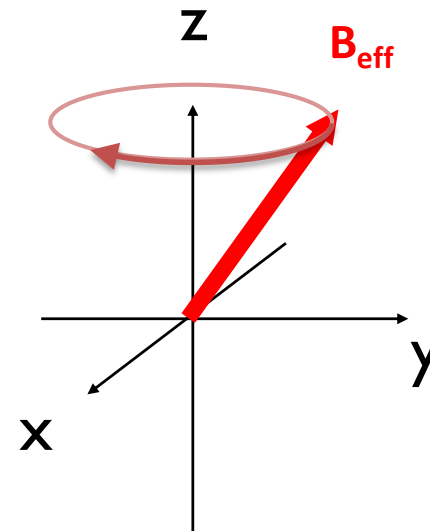
Frequency encode  
Wrong!

# RF pulses

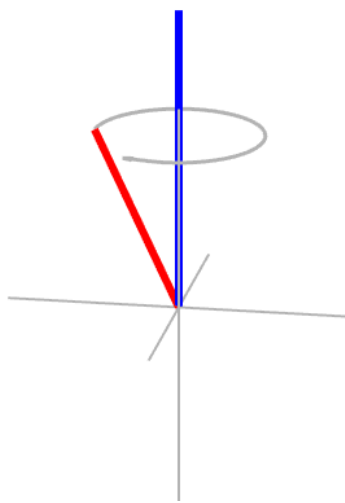
- Rotating magnetic field
  - Not radio waves
  - H field, ideally no E field



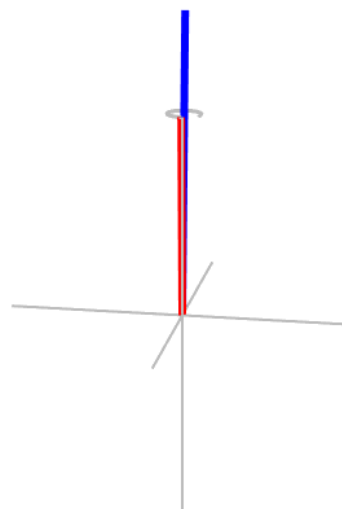
- $B_{\text{eff}} = B_0 + B_1$ 
  - $B_0 \sim 1.5\text{-}3\text{ T}$ , 0 Hz
  - $B_1 \sim 30\text{ }\mu\text{T}$ , 64-128 MHz



# RF pulses - forced precession

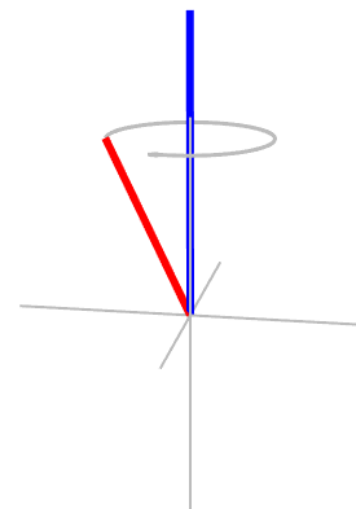


No RF pulse



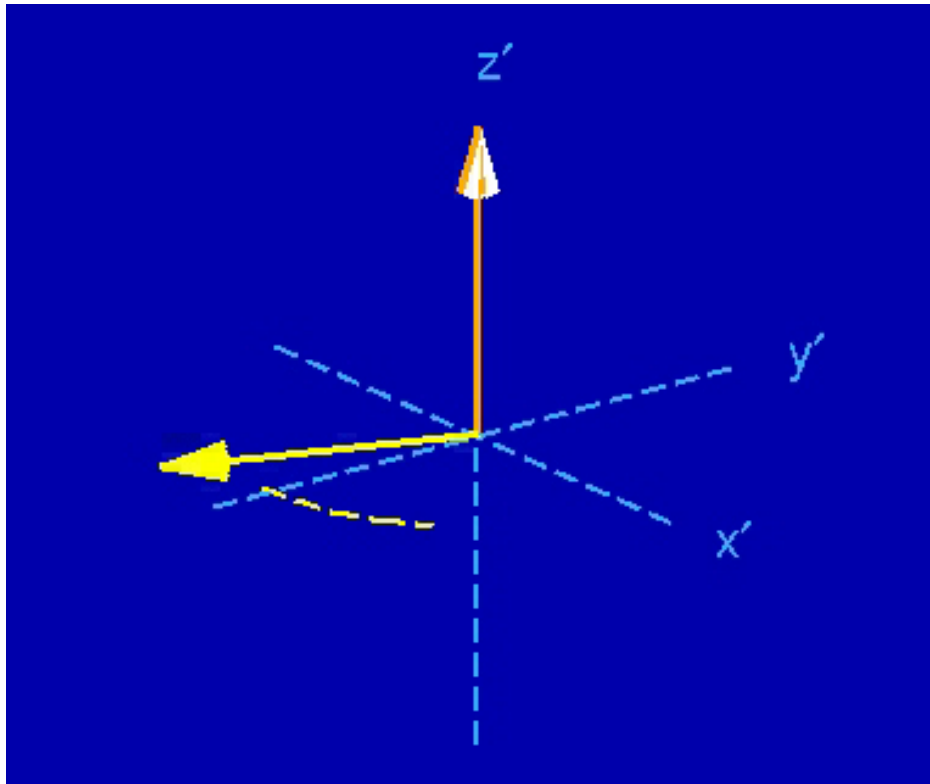
RF on resonance

 Magnetization  
 Effective B1

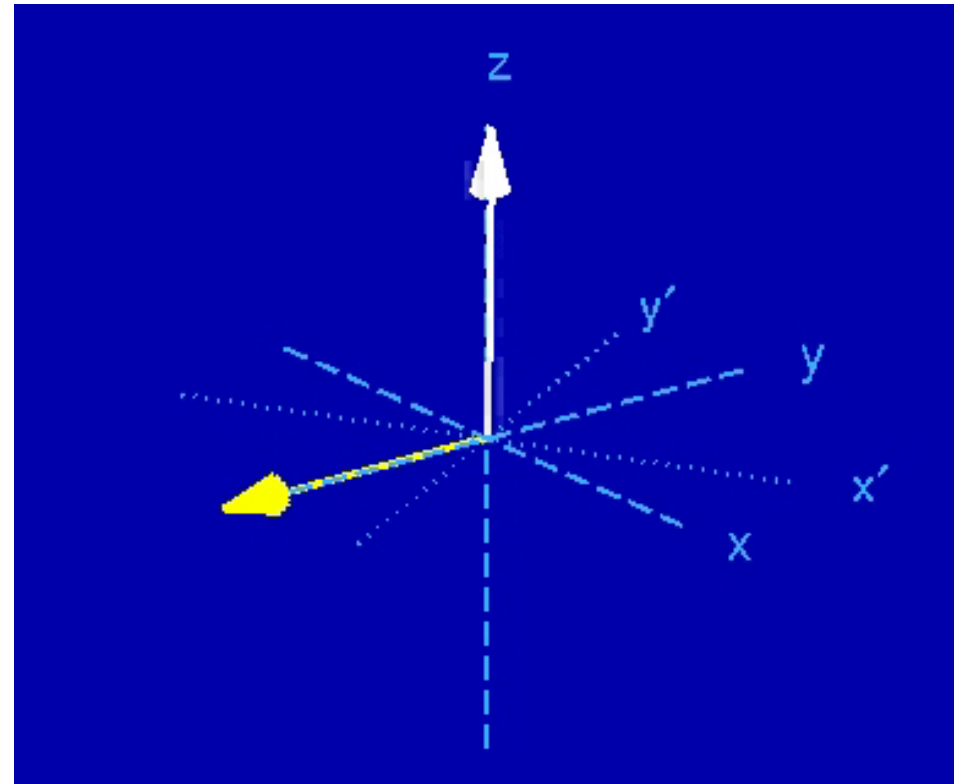


RF off resonance

# Rotating frame of reference



Static frame of reference



Rotating frame of reference

Movies from <http://mrsrl.stanford.edu/~brian/intromr/> (Brian Hargreaves)

# Simulation

- <http://www.drcmr.dk/bloch>
- Bloch equations (after Felix Bloch); differential equations in matrix form that describe precession, relaxation and other manipulations

$$\frac{dM_x(t)}{dt} = \gamma(\mathbf{M}(t) \times \mathbf{B}(t))_x - \frac{M_x(t)}{T_2}$$

$$\frac{dM_y(t)}{dt} = \gamma(\mathbf{M}(t) \times \mathbf{B}(t))_y - \frac{M_y(t)}{T_2}$$

$$\frac{dM_z(t)}{dt} = \gamma(\mathbf{M}(t) \times \mathbf{B}(t))_z - \frac{M_z(t) - M_0}{T_1}$$

# Chemical shift

- Electrons shield the magnetic field
- Electron distribution depends on molecular structure
- Local magnetic field will be different for different molecules
- Chemical shift
- Can be used to discriminate different molecules
  - Despite that the signal is from the same nuclei
- Most apparent with water and fat
  - $\sim 150$  Hz/T difference



# Water-fat shift

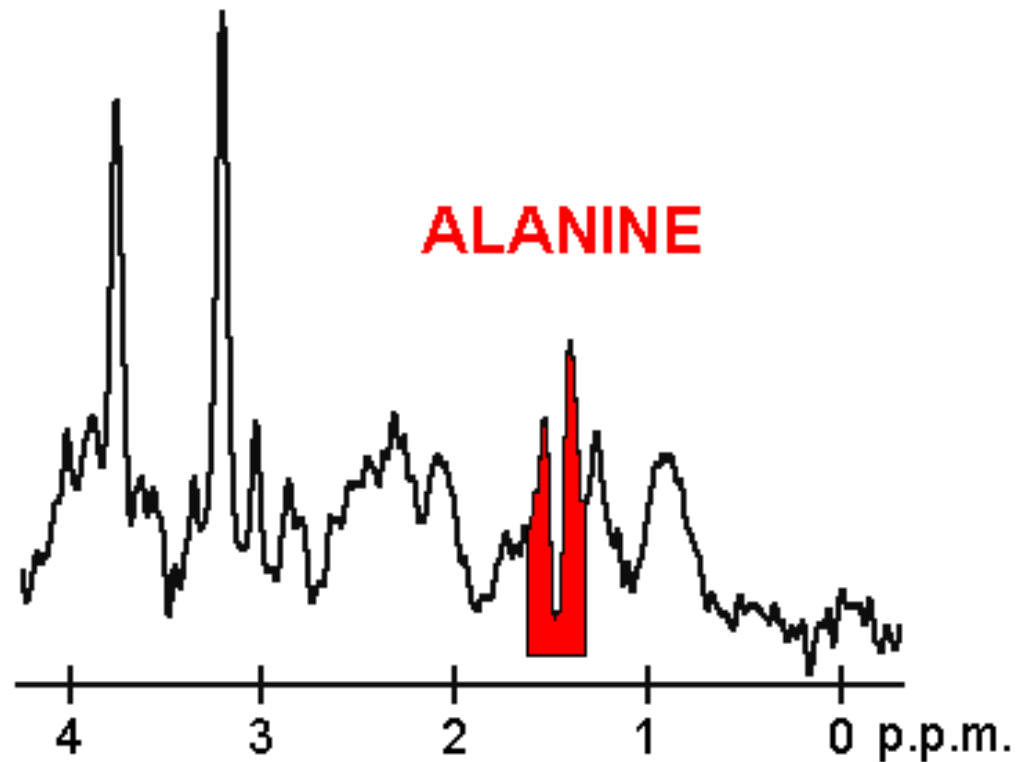
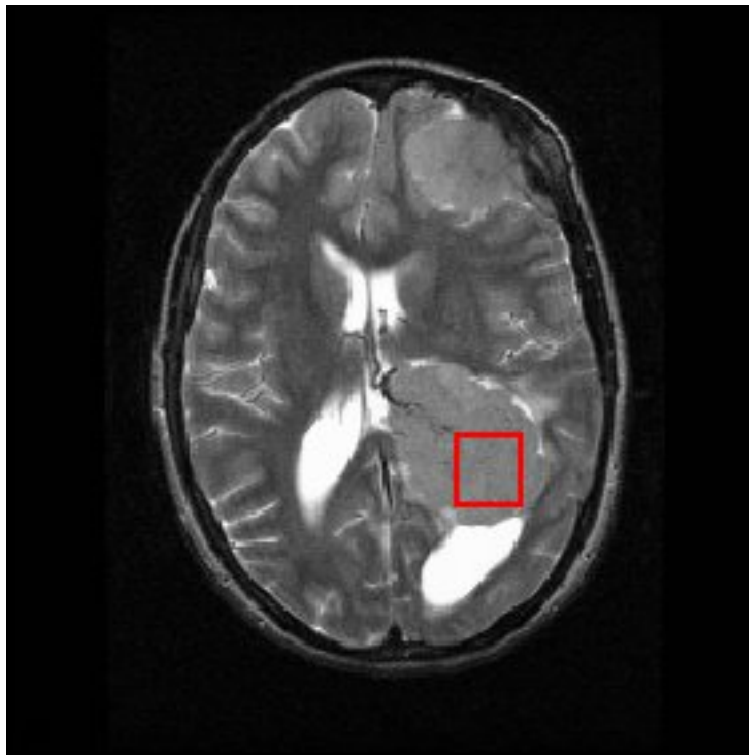
- Water-based tissues and fat-based tissues have different chemical shift
- The position encoding relies on frequency differences caused by the gradient
- Additional frequency differences due to chemical shift result in position decoding errors -> fat signal is shifted in the image



# MR Spectroscopy

- In spatial encoding, a gradient was applied during readout
  - Reconstruct different positions depending on frequency
- MR spectroscopy
  - Readout without applied gradient
  - Different molecules give signal with different Larmor frequency
  - Similar reconstruction, but with a frequency dimension instead of a spatial dimension
- Spatial localization of MR spectroscopy requires extra effort
  - Single-voxel reasonably simple
  - MR spectroscopic imaging, requires more acquisition time

# MR spectroscopy

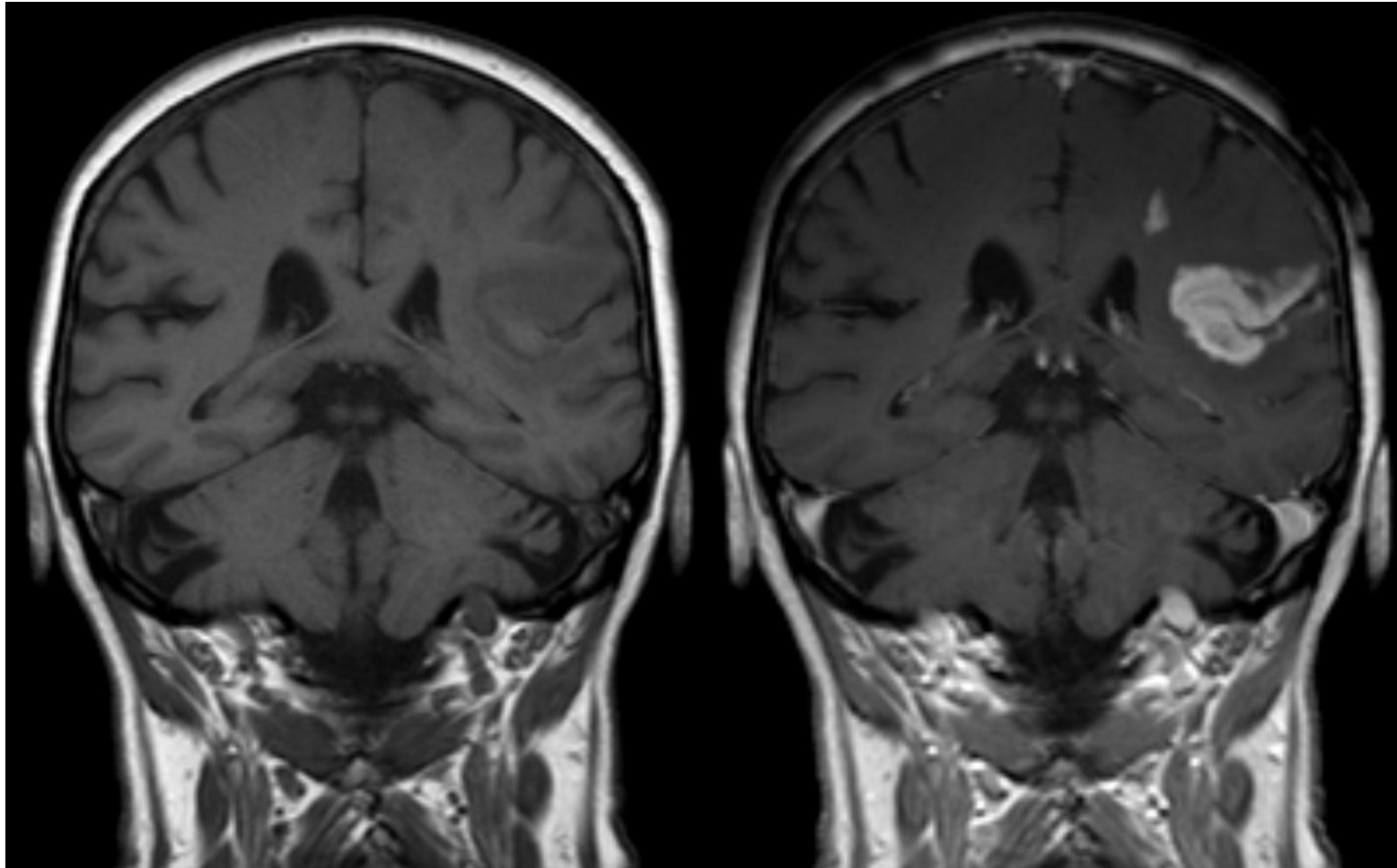


The University of Hull Centre for Magnetic Resonance Investigations (<http://www.hull.ac.uk/mri>).

# Contrast agents

- Most MRI contrast agents don't give signal themselves
- Affects  $T_1$  and  $T_2$
- Lower dose than X-ray / CT contrast agents
- Gadolinium-based
  - Paramagnetic
  - Rare-earth metal
  - Toxic, but chelated in practice
  - Reduces  $T_1$
- Iron oxide
  - Reduces  $T_2$

# Contrast agents



Defect of the blood-brain barrier after stroke shown in MRI. T1-weighted images, left image without right image with contrast medium administration.



# The insides of an MRI system

Superconducting magnet,  
cooling system (liquid N, He)

Gradient coils  
sealed in epoxy

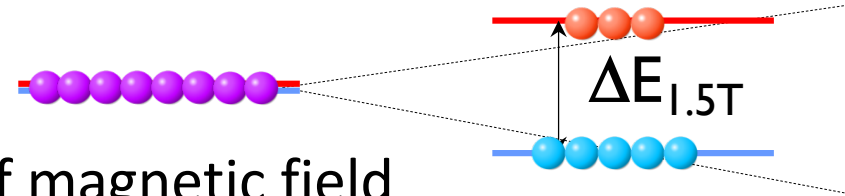
Integrated  
RF coil

Electronics, cooling systems,  
and more



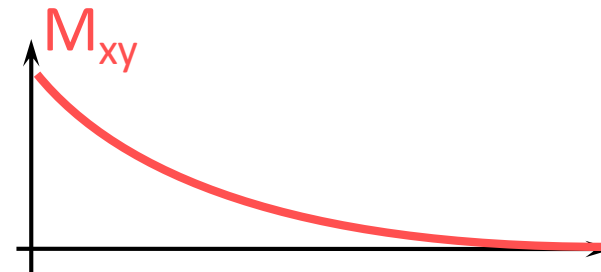
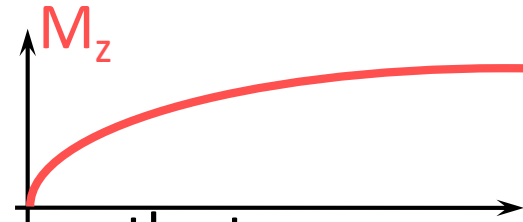
# Summary

- Some nuclei have spin
  - Split energy level in presence of magnetic field
  - Energy difference results in a **Larmor frequency precession**
  - Larmor frequency *proportional to magnetic field* ( $^1\text{H}$ , 1.5 T  $\Rightarrow$  64 MHz)
  - Population difference very small ( $10^{-5}$ )
- Net magnetization vector M
  - A group of spins have a net magnetization vector
  - Can be measured when flipped to the transversal plane ( $M_{xy}$ )
    - Complex signal with magnitude and phase
  - Relaxes back to thermal equilibrium ( $M_0$  along  $B_0$  direction)



# Summary, relaxation

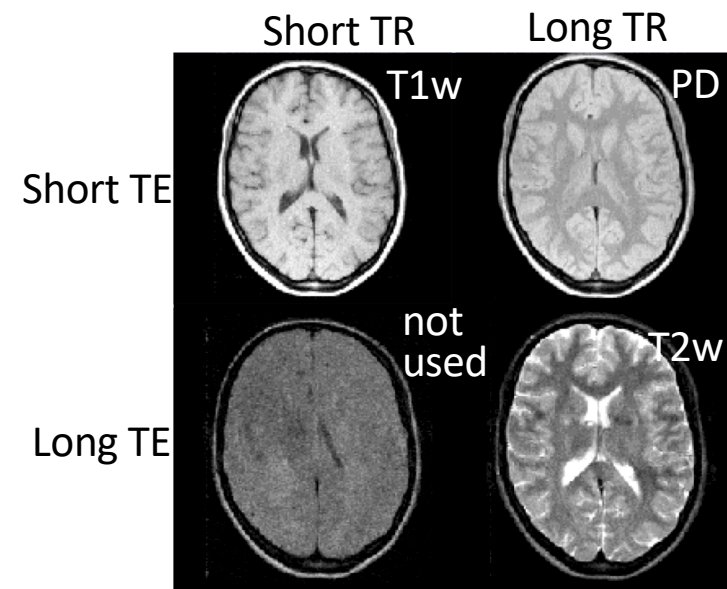
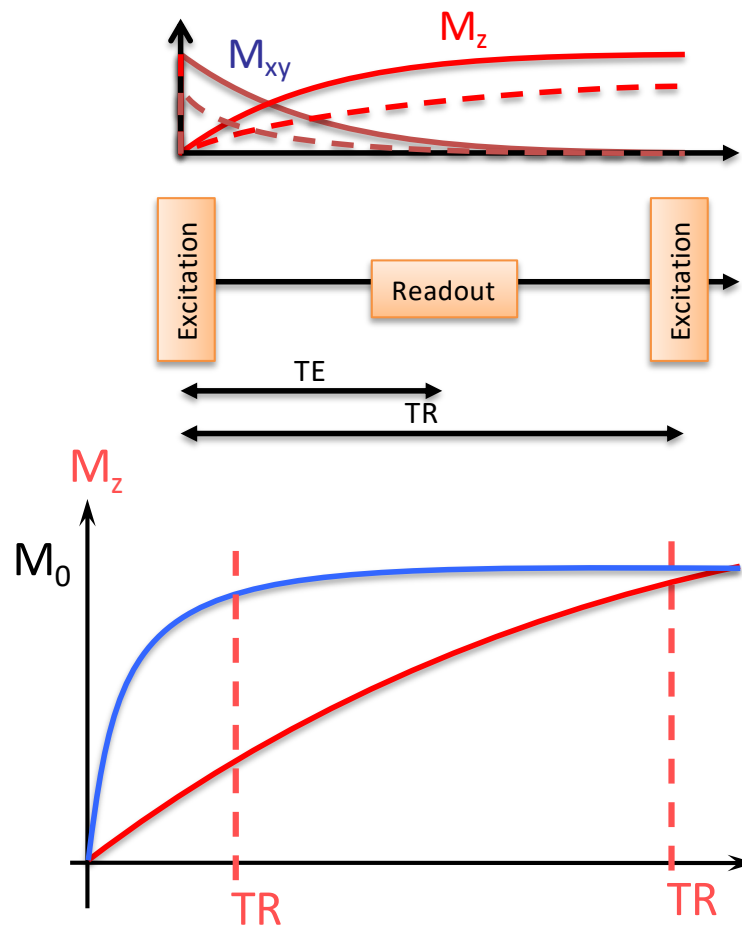
- $T_1$ : Longitudinal relaxation, the net magnetization vector returns to thermal equilibrium along  $B_0$
- $T_2$  and  $T_2^*$ : due to varying Larmor frequency, the transverse component ( $M_{xy}$ ) of the net magnetization dephases and signal vanishes
- $T_2$  is irreversible because they are random in time
- $T_2^*$  is the apparent  $T_2$  when not using 180 degree refocusing pulses
- The temporally static variations are refocused using a 180 degree pulse
- $T_2^* < T_2 < T_1$





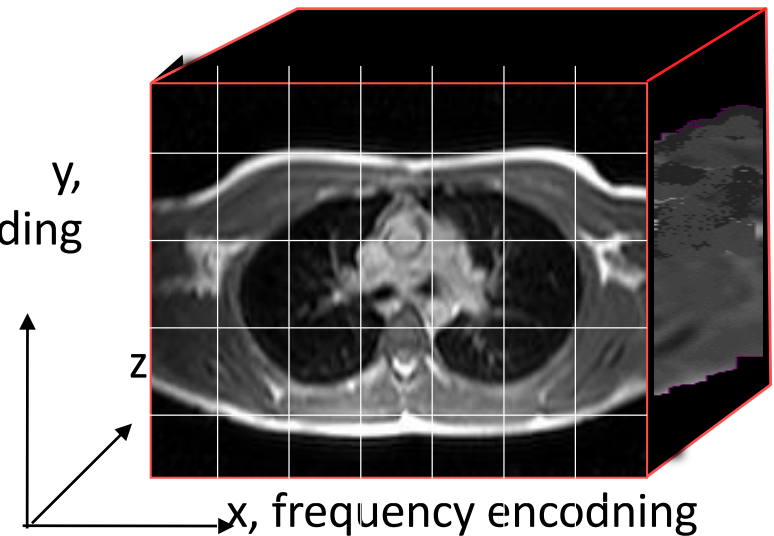
# Summary, image contrast

- By choosing TE and TR appropriately, a desired image contrast can be obtained



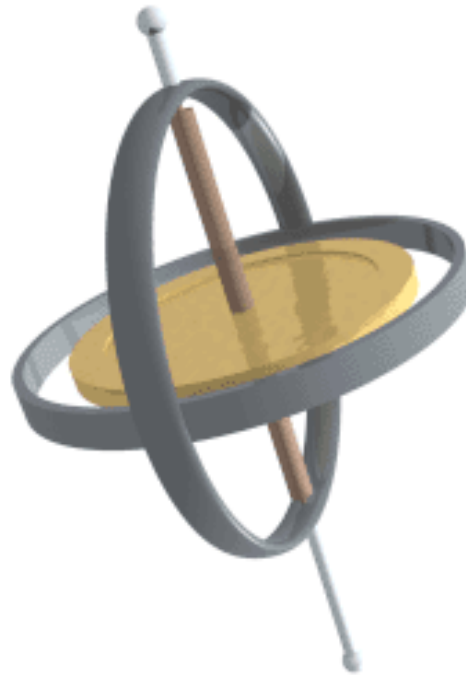
# Summary, image localization

- Slice is selected during excitation
  - Gradient during RF pulse      phase encoding
  - Only spins within the bandwidth are excited
- Frequency encoding (x)
  - Gradient during signal reception (one TR)
  - Signal with frequency depending on position is emitted
  - Fourier transform (“spectrum analyzer”)
- Phase encoding (y)
  - Gradient lobe with varying strength before readout
  - Needs to be repeated for all combinations ( $N \times TR$ )
  - Fourier transform for reconstruction



# Acknowledgements

- Karin Markenroth Bloch, Lund (Slides)



# The next step

- Course in Magnetic Resonance Imaging
  - HL2011, spring, 4.5 HP (-> autumn, 6 HP)
- Master projects
  - Cardiac MRI, pulse sequences and reconstruction
  - <andreas.sigfridsson@gmail.com>

